## Melanie N Zeilinger

List of Publications by Year in descending order

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58	2,781	18	34
papers	citations	h-index	g-index
59	59	59	1668
all docs	docs citations	times ranked	citing authors

#	Article	IF	Citations
1	A System Level Approach to Tube-Based Model Predictive Control. , 2022, 6, 776-781.		15
2	Probabilistic Model Predictive Safety Certification for Learning-Based Control. IEEE Transactions on Automatic Control, 2022, 67, 176-188.	5.7	41
3	A Soft Constrained MPC Formulation Enabling Learning From Trajectories With Constraint Violations. , 2022, 6, 980-985.		3
4	Recursively Feasible Stochastic Predictive Control Using an Interpolating Initial State Constraint., 2022, 6, 2743-2748.		10
5	A System Level Approach to Regret Optimal Control. , 2022, 6, 2792-2797.		16
6	System level disturbance reachable sets and their application to tube-based MPC. European Journal of Control, 2022, 68, 100680.	2.6	4
7	Inverse Learning for Data-Driven Calibration of Model-Based Statistical Path Planning. IEEE Transactions on Intelligent Vehicles, 2021, 6, 131-145.	12.7	16
8	Constrained Inverse Optimal Control With Application to a Human Manipulation Task. IEEE Transactions on Control Systems Technology, 2021, 29, 826-834.	5.2	24
9	Interaction-Aware Motion Prediction for Autonomous Driving: A Multiple Model Kalman Filtering Scheme. IEEE Robotics and Automation Letters, 2021, 6, 80-87.	5.1	41
10	Knee Compliance Reduces Peak Swing Phase Collision Forces in a Lower-Limb Exoskeleton Leg: A Test Bench Evaluation. IEEE Transactions on Biomedical Engineering, 2021, 68, 535-544.	4.2	6
11	Scalable Model Predictive Control for Autonomous Mobility-on-Demand Systems. IEEE Transactions on Control Systems Technology, 2021, 29, 635-644.	5.2	21
12	Nonlinear learningâ€based model predictive control supporting state and input dependent model uncertainty estimates. International Journal of Robust and Nonlinear Control, 2021, 31, 8897-8915.	3.7	10
13	A predictive safety filter for learning-based control of constrained nonlinear dynamical systems. Automatica, 2021, 129, 109597.	5.0	63
14	Plug-and-Play Distributed Safety Verification for Linear Control Systems With Bounded Uncertainties. IEEE Transactions on Control of Network Systems, 2021, 8, 1501-1512.	3.7	3
15	A Predictive Safety Filter for Learning-Based Racing Control. IEEE Robotics and Automation Letters, 2021, 6, 7635-7642.	5.1	18
16	Distributed Safe Learning using an Invariance-based Safety Framework. IFAC-PapersOnLine, 2021, 54, 95-102.	0.9	0
17	Data-Driven Distributed Stochastic Model Predictive Control with Closed-Loop Chance Constraint Satisfaction., 2021,,.		4
18	Insights of posture dependent pressure characteristics in five rats. Current Directions in Biomedical Engineering, 2021, 7, 799-802.	0.4	1

#	Article	IF	CITATIONS
19	Bayesian multi-task learning using finite-dimensional models: A comparative study. , 2021, , .		2
20	Scenario-Based Probabilistic Reachable Sets for Recursively Feasible Stochastic Model Predictive Control., 2020, 4, 450-455.		34
21	Cautious Model Predictive Control Using Gaussian Process Regression. IEEE Transactions on Control Systems Technology, 2020, 28, 2736-2743.	5.2	278
22	Learning-Based Model Predictive Control: Toward Safe Learning in Control. Annual Review of Control, Robotics, and Autonomous Systems, 2020, 3, 269-296.	11.8	335
23	Performance comparison of prediction filters for respiratory motion tracking in radiotherapy. Medical Physics, 2020, 47, 643-650.	3.0	20
24	Recursively feasible stochastic model predictive control using indirect feedback. Automatica, 2020, 119, 109095.	5.0	43
25	Using Human Ratings for Feedback Control: A Supervised Learning Approach With Application to Rehabilitation Robotics. IEEE Transactions on Robotics, 2020, 36, 789-801.	10.3	7
26	An Approximate Dynamic Programming Approach for Dual Stochastic Model Predictive Control. IFAC-PapersOnLine, 2020, 53, 8105-8111.	0.9	7
27	Performance Analysis of Stochastic Model Predictive Control with Direct and Indirect Feedback. , 2020, , .		4
28	Maximum Likelihood Methods for Inverse Learning of Optimal Controllers. IFAC-PapersOnLine, 2020, 53, 5266-5272.	0.9	9
29	Model Predictive Coverage Control. IFAC-PapersOnLine, 2020, 53, 6107-6112.	0.9	9
30	Distributed Model Predictive Safety Certification for Learning-based Control. IFAC-PapersOnLine, 2020, 53, 5258-5265.	0.9	11
31	Data-Driven Model Predictive Control for Trajectory Tracking With a Robotic Arm. IEEE Robotics and Automation Letters, 2019, 4, 3758-3765.	5.1	115
32	Learning-Based Model Predictive Control for Autonomous Racing. IEEE Robotics and Automation Letters, 2019, 4, 3363-3370.	5.1	206
33	The ideal couch tracking system—Requirements and evaluation of current systems. Journal of Applied Clinical Medical Physics, 2019, 20, 152-159.	1.9	5
34	Bayesian Optimization for Policy Search in High-Dimensional Systems via Automatic Domain Selection. , 2019, , .		5
35	Inverse Learning for Human-Adaptive Motion Planning. , 2019, , .		7
36	A General Safety Framework for Learning-Based Control in Uncertain Robotic Systems. IEEE Transactions on Automatic Control, 2019, 64, 2737-2752.	5.7	202

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37	Plug-and-Play Model Predictive Control for Load Shaping and Voltage Control in Smart Grids. IEEE Transactions on Smart Grid, 2019, 10, 2334-2344.	9.0	20
38	Stochastic Model Predictive Control for Linear Systems Using Probabilistic Reachable Sets., 2018,,.		42
39	On a Correspondence between Probabilistic and Robust Invariant Sets for Linear Systems., 2018,,.		11
40	Cautious NMPC with Gaussian Process Dynamics for Autonomous Miniature Race Cars., 2018,,.		68
41	Linear Model Predictive Safety Certification for Learning-Based Control. , 2018, , .		76
42	Scalable synthesis of safety certificates from data with application to learning-based control. , 2018, , .		17
43	Convex Formulations and Algebraic Solutions for Linear Quadratic Inverse Optimal Control Problems. , 2018, , .		14
44	Performance behavior of prediction filters for respiratory motion compensation in radiotherapy. Current Directions in Biomedical Engineering, 2017, 3, 429-432.	0.4	1
45	Quantization Design for Distributed Optimization. IEEE Transactions on Automatic Control, 2017, 62, 2107-2120.	5.7	49
46	Safe Learning for Distributed Systems with Bounded Uncertainties * *This work was supported by the Swiss National Science Foundation under grant no. PPOOP2_157601 / 1 and by the Swiss National Centre of Competence in Research NCCR Digital Fabrication IFAC-PapersOnLine, 2017, 50, 2536-2542.	0.9	9
47	Unconscious physiological response of healthy volunteers to dynamic respiration-synchronized couch motion. Radiation Oncology, 2017, 12, 189.	2.7	2
48	Distributed synthesis and stability of cooperative distributed model predictive control for linear systems. Automatica, 2016, 69, 117-125.	5.0	122
49	Gaussian Process-Based Predictive Control for Periodic Error Correction. IEEE Transactions on Control Systems Technology, 2016, 24, 110-121.	5.2	70
50	Inexact fast alternating minimization algorithm for distributed model predictive control. , 2014, , .		15
51	Reachability-based safe learning with Gaussian processes. , 2014, , .		153
52	Plug-and-play model predictive control for electric vehicle charging and voltage control in smart grids. , 2014, , .		29
53	On real-time robust model predictive control. Automatica, 2014, 50, 683-694.	5.0	88
54	Soft Constrained Model Predictive Control With Robust Stability Guarantees. IEEE Transactions on Automatic Control, 2014, 59, 1190-1202.	5.7	88

#	Article	IF	CITATIONS
55	Nonparametric dynamics estimation for time periodic systems. , 2013, , .		10
56	Robust distributed model predictive control of linear systems. , 2013, , .		19
57	Efficient interior point methods for multistage problems arising in receding horizon control. , 2012, , .		243
58	Computational aspects of distributed optimization in model predictive control., 2012,,.		40