

Angelo Alessandri

List of Publications by Year in descending order

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132
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186265
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times ranked

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citing authors

#	ARTICLE	IF	CITATIONS
1	Moving-horizon state estimation for nonlinear discrete-time systems: New stability results and approximation schemes. <i>Automatica</i> , 2008, 44, 1753-1765.	5.0	232
2	Receding-horizon estimation for discrete-time linear systems. <i>IEEE Transactions on Automatic Control</i> , 2003, 48, 473-478.	5.7	170
3	Design of state estimators for uncertain linear systems using quadratic boundedness. <i>Automatica</i> , 2006, 42, 497-502.	5.0	127
4	On Estimation Error Bounds for Receding-Horizon Filters Using Quadratic Boundedness. <i>IEEE Transactions on Automatic Control</i> , 2004, 49, 1350-1355.	5.7	118
5	Design of Luenberger Observers for a Class of Hybrid Linear Systems. <i>Lecture Notes in Computer Science</i> , 2001, , 7-18.	1.3	113
6	Fault detection of actuator faults in unmanned underwater vehicles. <i>Control Engineering Practice</i> , 1999, 7, 357-368.	5.5	108
7	Receding-horizon estimation for switching discrete-time linear systems. <i>IEEE Transactions on Automatic Control</i> , 2005, 50, 1736-1748.	5.7	106
8	Optimal control of freeways via speed signalling and ramp metering. <i>Control Engineering Practice</i> , 1998, 6, 771-780.	5.5	85
9	Stubborn state observers for linear time-invariant systems. <i>Automatica</i> , 2018, 88, 1-9.	5.0	79
10	Moving-horizon estimation with guaranteed robustness for discrete-time linear systems and measurements subject to outliers. <i>Automatica</i> , 2016, 67, 85-93.	5.0	78
11	A neural state estimator with bounded errors for nonlinear systems. <i>IEEE Transactions on Automatic Control</i> , 1999, 44, 2028-2042.	5.7	72
12	Nonlinear optimization for freeway control using variable-speed signaling. <i>IEEE Transactions on Vehicular Technology</i> , 1999, 48, 2042-2052.	6.3	71
13	Min-Max and Predictive Control for the Management of Distribution in Supply Chains. <i>IEEE Transactions on Control Systems Technology</i> , 2011, 19, 1075-1089.	5.2	61
14	Moving-Horizon State Estimation for Nonlinear Systems Using Neural Networks. <i>IEEE Transactions on Neural Networks</i> , 2011, 22, 768-780.	4.2	61
15	Increasing-gain observers for nonlinear systems: Stability and design. <i>Automatica</i> , 2015, 57, 180-188.	5.0	59
16	Fault diagnosis for nonlinear systems using a bank of neural estimators. <i>Computers in Industry</i> , 2003, 52, 271-289.	9.9	51
17	Robust receding-horizon state estimation for uncertain discrete-time linear systems. <i>Systems and Control Letters</i> , 2005, 54, 627-643.	2.3	48
18	Fast Moving Horizon State Estimation for Discrete-Time Systems Using Single and Multi Iteration Descent Methods. <i>IEEE Transactions on Automatic Control</i> , 2017, 62, 4499-4511.	5.7	47

#	ARTICLE	IF	CITATIONS
19	Modeling and Feedback Control for Resource Allocation and Performance Analysis in Container Terminals. IEEE Transactions on Intelligent Transportation Systems, 2008, 9, 601-614.	8.0	46
20	Advances in moving horizon estimation for nonlinear systems. , 2010, , .		46
21	Luenberger observers for switching discrete-time linear systems. International Journal of Control, 2007, 80, 1931-1943.	1.9	44
22	Design of observers for lipschitz nonlinear systems using LMI. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2004, 37, 459-464.	0.4	43
23	Modelling and Optimal Receding-horizon Control of Maritime Container Terminals. Mathematical Modelling and Algorithms, 2007, 6, 109-133.	0.5	41
24	Design of observers for switched discrete-time linear systems. , 0, , .		37
25	A maximum-likelihood Kalman filter for switching discrete-time linear systems. Automatica, 2010, 46, 1870-1876.	5.0	37
26	Neural approximators for nonlinear finite-memory state estimation. International Journal of Control, 1997, 67, 275-302.	1.9	33
27	Design of Asymptotic Estimators: An Approach Based on Neural Networks and Nonlinear Programming. IEEE Transactions on Neural Networks, 2007, 18, 86-96.	4.2	32
28	Feedback Optimal Control of Distributed Parameter Systems by Using Finite-Dimensional Approximation Schemes. IEEE Transactions on Neural Networks and Learning Systems, 2012, 23, 984-996.	11.3	32
29	Min-Max Moving-Horizon Estimation for Uncertain Discrete-Time Linear Systems. SIAM Journal on Control and Optimization, 2012, 50, 1439-1465.	2.1	31
30	Time-varying increasing-gain observers for nonlinear systems. Automatica, 2013, 49, 2845-2852.	5.0	30
31	Sliding-mode estimators for a class of non-linear systems affected by bounded disturbances. International Journal of Control, 2003, 76, 226-236.	1.9	28
32	Predictive Control of Container Flows in Maritime Intermodal Terminals. IEEE Transactions on Control Systems Technology, 2013, 21, 1423-1431.	5.2	25
33	Management of logistics operations in intermodal terminals by using dynamic modelling and nonlinear programming. Maritime Economics and Logistics, 2009, 11, 58-76.	4.0	24
34	A recursive algorithm for nonlinear least-squares problems. Computational Optimization and Applications, 2007, 38, 195-216.	1.6	23
35	Observer-based stabilisation of linear systems with parameter uncertainties by using enhanced LMI conditions. International Journal of Control, 2015, 88, 1189-1200.	1.9	23
36	Optimization-based learning with bounded error for feedforward neural networks. IEEE Transactions on Neural Networks, 2002, 13, 261-273.	4.2	22

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37	Optimization based on quasi-Monte Carlo sampling to design state estimators for non-linear systems. Optimization, 2010, 59, 963-984.	1.7	21
38	Parameter estimation of fire propagation models using level set methods. Applied Mathematical Modelling, 2021, 92, 731-747.	4.2	21
39	Nonlinear modeling of complex large-scale plants using neural networks and stochastic approximation. IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans, 1997, 27, 750-757.	2.9	20
40	Motion Control for Autonomous Navigation in Blue and Narrow Water Using Switched Controllers. Journal of Marine Science and Engineering, 2019, 7, 196.	2.6	17
41	Dynamic mode decomposition for the inspection of three-regime separated transitional boundary layers using a least squares method. Physics of Fluids, 2019, 31, 044103.	4.0	17
42	Optimal Control of Propagating Fronts by Using Level Set Methods and Neural Approximations. IEEE Transactions on Neural Networks and Learning Systems, 2019, 30, 902-912.	11.3	16
43	Synchronization in Networks of Identical Nonlinear Systems via Dynamic Dead Zones. , 2019, 3, 667-672.		16
44	Stubborn and Dead-Zone Redesign for Nonlinear Observers and Filters. IEEE Transactions on Automatic Control, 2021, 66, 667-682.	5.7	16
45	A new LMI condition for decentralized observer-based control of linear systems with nonlinear interconnections. , 2014, , .		14
46	Design of sliding-mode observers and filters for nonlinear dynamic systems. , 0, , .		13
47	Stubborn ISS Redesign for Nonlinear High-Gain Observers. IFAC-PapersOnLine, 2017, 50, 15422-15427.	0.9	13
48	State Observers for Systems Subject to Bounded Disturbances Using Quadratic Boundedness. IEEE Transactions on Automatic Control, 2020, 65, 5352-5359.	5.7	13
49	Luenberger Observers For Switching Discrete-Time Linear Systems. , 0, , .		11
50	Modeling and Identification of Nonlinear Dynamics for Freeway Traffic by Using Information From a Mobile Cellular Network. IEEE Transactions on Control Systems Technology, 2009, 17, 952-959.	5.2	11
51	Evaluation of Resilience of Interconnected Systems Based on Stability Analysis. Lecture Notes in Computer Science, 2013, , 180-190.	1.3	11
52	Optimization of approximating networks for optimal fault diagnosis. Optimization Methods and Software, 2005, 20, 241-266.	2.4	10
53	Results on stubborn Luenberger observers for linear time-invariant plants. , 2015, , .		10
54	Input-output stability for optimal estimation problems. International Mathematical Forum, 0, 2, 593-617.	0.1	10

#	ARTICLE	IF	CITATIONS
55	Fast moving horizon state estimation for discrete-time systems with linear constraints. International Journal of Adaptive Control and Signal Processing, 2020, 34, 706-720.	4.1	9
56	Functional Optimal Estimation Problems and Their Solution by Nonlinear Approximation Schemes. Journal of Optimization Theory and Applications, 2007, 134, 445-466.	1.5	8
57	Optimal control of level sets dynamics. , 2014, , .		8
58	Further results on the optimal control of fronts generated by level set methods. , 2016, , .		8
59	Neural state estimators for direct model-based fault diagnosis. , 1998, , .		7
60	On the convergence of EDF-based parameters optimization for neural networks. , 0, , .		6
61	Robust Receding-Horizon Estimation for Discrete-time Linear Systems in the Presence of Bounded Uncertainties. , 0, , .		6
62	Moving-horizon estimation for discrete-time linear systems with measurements subject to outliers. , 2014, , .		6
63	Moving-horizon estimation for discrete-time linear and nonlinear systems using the gradient and Newton methods. , 2016, , .		6
64	Synchronization of interconnected linear systems via dynamic saturation redesign. IFAC-PapersOnLine, 2019, 52, 622-627.	0.9	6
65	Nonlinear predictive control for the management of container flows in maritime intermodal terminals. , 2008, , .		5
66	Extended Kalman filtering to design optimal controllers of fronts generated by level set methods. , 2016, , .		5
67	On the enhancement of high-gain observers for state estimation of nonlinear systems. , 2016, , .		5
68	Moving horizon estimation: Open problems, theoretical progress, and new application perspectives. International Journal of Adaptive Control and Signal Processing, 2020, 34, 703-705.	4.1	5
69	Lyapunov Functions for State Observers of Dynamic Systems Using Hamiltonian Jacobi Inequalities. Mathematics, 2020, 8, 202.	2.2	5
70	Nonlinear Model Predictive Control for Resource Allocation in the Management of Intermodal Container Terminals. Lecture Notes in Control and Information Sciences, 2009, , 205-213.	1.0	5
71	Fault Detection Through Dynamics Monitoring for Unmanned Underwater Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2000, 33, 951-956.	0.4	4
72	Sliding-window neural state estimation in a power plant heater line. International Journal of Adaptive Control and Signal Processing, 2001, 15, 815-836.	4.1	4

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73	New convergence conditions for receding-horizon state estimation of nonlinear discrete-time systems. , 2004, , .		4
74	Maximum-likelihood Kalman filtering for switching discrete-time linear systems. , 2008, , .		4
75	Design of time-varying state observers for nonlinear systems by using input-to-state stability. , 2013, , .		4
76	Model-Based Fault Detection and Estimation for Linear Time Invariant and Piecewise Affine Systems by Using Quadratic Boundedness. , 2018, , .		4
77	Minimum-Distance Receding-Horizon State Estimation for Switching Discrete-Time Linear Systems. , 2007, , 347-358.		4
78	Hysteresis-based switching observers for linear systems using quadratic boundedness. Automatica, 2022, 136, 109982.	5.0	4
79	Sliding-Mode Estimators for a Class of Nonlinear Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2000, 33, 155-160.	0.4	3
80	Receding-horizon estimation for switching discrete-time linear systems. , 2004, , .		3
81	Sliding-Mode State Observers for a Class of Nonlinear Continuous-Time Systems. Proceedings of the American Control Conference, 2007, , .	0.0	3
82	Moving-horizon state estimation for nonlinear systems using neural networks. , 2008, , .		3
83	Minimizing Sequences for a Family of Functional Optimal Estimation Problems. Journal of Optimization Theory and Applications, 2010, 147, 243-262.	1.5	3
84	State observers with first-/second-order sliding-mode for nonlinear systems with bounded noises. , 2010, , .		3
85	Output feedback control for discrete-time linear systems by using luenberger observers under unknown switching. , 2013, , .		3
86	Black-box Modeling and Optimal Control of a Two-Phase Flow by Using Navier-Stokes Equations and Level Set Methods. , 2018, , .		3
87	State and observer-based feedback control of normal flow equations. Automatica, 2020, 117, 108980.	5.0	3
88	Detection of Flow-Regime Transitions Using Dynamic Mode Decomposition and Moving Horizon Estimation. IEEE Transactions on Control Systems Technology, 2021, 29, 1324-1331.	5.2	3
89	ANN Application For On-Line Power System Security Assessment. , 2006, , .		2
90	Identification of freeway macroscopic models using information from mobile phones. , 2006, , .		2

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91	Robust receding-horizon estimation for uncertain discrete-time linear systems via semidefinite programming. , 2007, , .		2
92	Sliding-mode state estimation for a class of multi-output nonlinear continuous-time systems. , 2007, , .		2
93	Connections between stability and asymptotic stability of nonlinear switched systems. Nonlinear Analysis: Hybrid Systems, 2007, 1, 501-509.	3.5	2
94	Moving Horizon Trend Identification Based on Switching Models for Data Driven Decomposition of Fluid Flows. , 2018, , .		2
95	State Observation for Lipschitz Nonlinear Dynamical Systems Based on Lyapunov Functions and Functionals. Mathematics, 2020, 8, 1424.	2.2	2
96	On Hamilton-Jacobi Approaches to State Reconstruction for Dynamic Systems. Advances in Mathematical Physics, 2020, 2020, 1-13.	0.8	2
97	Black-Box Modeling and Optimal Control of a Two-Phase Flow Using Level Set Methods. IEEE Transactions on Control Systems Technology, 2022, 30, 520-534.	5.2	2
98	Optimistic vs Pessimistic Moving-Horizon Estimation for Quasi- LPV Discrete-Time Systems. IFAC-PapersOnLine, 2020, 53, 5004-5009.	0.9	2
99	State observer design method for a class of non-linear systems. IET Control Theory and Applications, 2020, 14, 1648-1655.	2.1	2
100	Receding-horizon estimation for noisy nonlinear discrete-time systems. , 0, , .		1
101	Design of Observers with Commutation-Dependent Gains for Linear Switching Systems. Proceedings of the American Control Conference, 2007, , .	0.0	1
102	Identification of freeway traffic dynamics using fluid and black-box nonlinear models. , 2007, , .		1
103	Nonparametric nonlinear regression using polynomial and neural approximators: a numerical comparison. Computational Management Science, 2009, 6, 5-24.	1.3	1
104	Approximate Solution of Feedback Optimal Control Problems for Distributed Parameter Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 987-992.	0.4	1
105	Rate-based Optimal Control of Priority Traffic Using a Deterministic Fluid Model. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 11477-11482.	0.4	1
106	Integer tree-based search and mixed-integer optimal control of distribution chains. , 2011, , .		1
107	Optimal control of PDE-based systems by using a finite-dimensional approximation scheme. , 2013, , .		1
108	On increasing-gain observers for nonlinear continuous-time systems. , 2013, , .		1

#	ARTICLE	IF	CITATIONS
109	Output feedback control for a class of switching discrete-time linear systems. , 2014, , .		1
110	Robust predictive control for the management of multi-echelon distribution chains. , 2014, , .		1
111	Adaptive state estimation for nonlinear systems based on the increasing-gain observer. , 2015, , .		1
112	Moving horizon state estimation for constrained discrete-time systems by using fast descent methods. , 2017, , .		1
113	On-line Mode Decomposition of Fluid Flows Using Moving Horizon Estimation. , 2019, , .		1
114	Optimal Propagating Fronts Using Hamilton-Jacobi Equations. Mathematics, 2019, 7, 1122.	2.2	1
115	Stabilization of diffusive systems using backstepping and the circle criterion. International Journal of Heat and Mass Transfer, 2020, 149, 119132.	4.8	1
116	Optimal Control of Level Sets Generated by the Normal Flow Equation. Springer Proceedings in Mathematics and Statistics, 2018, , 29-41.	0.2	1
117	DESIGN OF RECEDING-HORIZON FILTERS FOR DISCRETE-TIME LINEAR SYSTEMS USING QUADRATIC BOUNDEDNESS. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2002, 35, 173-178.	0.4	0
118	Application of neural control to economic growth problems. , 0, , .		0
119	Freeway Incident Detection Using Traffic Information from Mobile Phones. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2003, 36, 933-938.	0.4	0
120	Sliding-Mode State Estimators for Lipschitz Nonlinear Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2003, 36, 729-734.	0.4	0
121	Design of Parameterized State Observers and Controllers for a Class of Nonlinear Continuous-Time Systems. , 2006, , .		0
122	MODE ESTIMATION TECHNIQUES FOR SWITCHING DISCRETE-TIME LINEAR SYSTEMS.. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2007, 40, 253-258.	0.4	0
123	Sliding-mode state observers for multi-output nonlinear systems with bounded noises on dynamics and measurements. , 2009, , .		0
124	Computationally Efficient, Approximate Moving Horizon State Estimation for Nonlinear Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 759-764.	0.4	0
125	Optimal and Predictive Control of Distribution Chains by Using Integer Tree-Based Search and Mixed-Integer Programming. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 238-244.	0.4	0
126	Convex optimization approach to observer-based stabilization of linear systems with parameter uncertainties. , 2013, , .		0

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127	Optimal control of parallel buffers by using output feedback based on Practical Observers. , 2016, , .		0
128	Parameter identification of the normal flow equation by using adaptive estimation. , 2017, , .		0
129	Modeling and Estimation of Thermal Flows Based on Transport and Balance Equations. Advances in Mathematical Physics, 2020, 2020, 1-10.	0.8	0
130	Modeling and Estimation of Amnioserosa Cell Mechanical Behavior Using Moving Horizon Estimation. , 2021, , .		0
131	State Observer Design Method for a Class of Nonlinear Systems. IFAC-PapersOnLine, 2020, 53, 4935-4940.	0.9	0
132	Control of Normal Flow PDEs with ISS Properties. , 2021, , .		0