

Shun Zhang

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/8799176/publications.pdf>

Version: 2024-02-01

11
papers

150
citations

1307594

7
h-index

1474206

9
g-index

11
all docs

11
docs citations

11
times ranked

177
citing authors

#	ARTICLE	IF	CITATIONS
1	Multi-target tracking by learning local-to-global trajectory models. Pattern Recognition, 2015, 48, 580-590.	8.1	47
2	Remote Sensing Scene Classification Using Sparse Representation-Based Framework With Deep Feature Fusion. IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing, 2021, 14, 5867-5878.	4.9	23
3	Rotation-Invariant Feature Learning for Object Detection in VHR Optical Remote Sensing Images by Double-Net. IEEE Access, 2020, 8, 20818-20827.	4.2	16
4	Tracking Persons-of-Interest via Unsupervised Representation Adaptation. International Journal of Computer Vision, 2020, 128, 96-120.	15.6	15
5	Finding Nonrigid Tiny Person With Densely Cropped and Local Attention Object Detector Networks in Low-Altitude Aerial Images. IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing, 2022, 15, 4371-4385.	4.9	12
6	Hyperspectral Imagery Spatial Super-Resolution Using Generative Adversarial Network. IEEE Transactions on Computational Imaging, 2021, 7, 948-960.	4.4	10
7	A Novel Human-3DTV Interaction System Based on Free Hand Gestures and a Touch-Based Virtual Interface. IEEE Access, 2019, 7, 165961-165973.	4.2	8
8	Person Re-Identification With Joint Verification and Identification of Identity-Attribute Labels. IEEE Access, 2019, 7, 126116-126126.	4.2	7
9	Rotation-Invariant Feature Learning in VHR Optical Remote Sensing Images via Nested Siamese Structure With Double Center Loss. IEEE Transactions on Geoscience and Remote Sensing, 2021, 59, 3326-3337.	6.3	7
10	Content-Adaptive Image Compressed Sensing Using Deep Learning. , 2018, , .		3
11	Siammraan: Siamese Multi-Level Residual Attention Adaptive Network for Hyperspectral Videos Tracking. , 2021, , .		2