

# Hallel A Bunis

## List of Publications by Year in descending order

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2258059

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#	ARTICLE	IF	CITATIONS
1	Toward Grasping Against the Environment: Locking Polygonal Objects Against a Wall Using Two-Finger Robot Hands. IEEE Robotics and Automation Letters, 2019, 4, 105-112.	5.1	2
2	Equilateral Three-Finger Caging of Polygonal Objects Using Contact Space Search. IEEE Transactions on Automation Science and Engineering, 2018, 15, 919-931.	5.2	9
3	Caging Polygonal Objects Using Formationally Similar Three-Finger Hands. IEEE Robotics and Automation Letters, 2018, 3, 3271-3278.	5.1	8
4	Caging Polygonal Objects Using Equilateral Three-Finger Hands. IEEE Robotics and Automation Letters, 2017, 2, 1672-1679.	5.1	7