

Mitra J Z Hartmann

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/7555667/publications.pdf>

Version: 2024-02-01

50
papers

1,509
citations

331670

21
h-index

345221

36
g-index

57
all docs

57
docs citations

57
times ranked

969
citing authors

#	ARTICLE	IF	CITATIONS
1	Biomechanical Models for Radial Distance Determination by the Rat Vibrissal System. <i>Journal of Neurophysiology</i> , 2007, 98, 2439-2455.	1.8	149
2	The Morphology of the Rat Vibrissal Array: A Model for Quantifying Spatiotemporal Patterns of Whisker-Object Contact. <i>PLoS Computational Biology</i> , 2011, 7, e1001120.	3.2	131
3	The Brain in Its Body: Motor Control and Sensing in a Biomechanical Context. <i>Journal of Neuroscience</i> , 2009, 29, 12807-12814.	3.6	122
4	Mechanical signals at the base of a rat vibrissa: the effect of intrinsic vibrissa curvature and implications for tactile exploration. <i>Journal of Neurophysiology</i> , 2012, 107, 2298-2312.	1.8	79
5	Variability in Velocity Profiles During Free-Air Whisking Behavior of Unrestrained Rats. <i>Journal of Neurophysiology</i> , 2008, 100, 740-752.	1.8	73
6	Modeling Forces and Moments at the Base of a Rat Vibrissa during Noncontact Whisking and Whisking against an Object. <i>Journal of Neuroscience</i> , 2014, 34, 9828-9844.	3.6	66
7	Variation in Young's modulus along the length of a rat vibrissa. <i>Journal of Biomechanics</i> , 2011, 44, 2775-2781.	2.1	61
8	Radial distance determination in the rat vibrissal system and the effects of Weber's law. <i>Philosophical Transactions of the Royal Society B: Biological Sciences</i> , 2011, 366, 3049-3057.	4.0	56
9	Extracting Object Contours with the Sweep of a Robotic Whisker Using Torque Information. <i>International Journal of Robotics Research</i> , 2010, 29, 1233-1245.	8.5	54
10	Whisking mechanics and active sensing. <i>Current Opinion in Neurobiology</i> , 2016, 40, 178-188.	4.2	49
11	Artificial Whiskers Suitable for Array Implementation: Accounting for Lateral Slip and Surface Friction. <i>IEEE Transactions on Robotics</i> , 2008, 24, 1157-1167.	10.3	48
12	Decoupling kinematics and mechanics reveals coding properties of trigeminal ganglion neurons in the rat vibrissal system. <i>ELife</i> , 2016, 5, .	6.0	43
13	A night in the life of a rat: vibrissal mechanics and tactile exploration. <i>Annals of the New York Academy of Sciences</i> , 2011, 1225, 110-118.	3.8	42
14	Tactile Sensing with Whiskers of Various Shapes: Determining the Three-Dimensional Location of Object Contact Based on Mechanical Signals at the Whisker Base. <i>Soft Robotics</i> , 2017, 4, 88-102.	8.0	40
15	Whiskers aid anemotaxis in rats. <i>Science Advances</i> , 2016, 2, e1600716.	10.3	39
16	Spatiotemporal Patterns of Contact Across the Rat Vibrissal Array During Exploratory Behavior. <i>Frontiers in Behavioral Neuroscience</i> , 2015, 9, 356.	2.0	37
17	Mechanical responses of rat vibrissae to airflow. <i>Journal of Experimental Biology</i> , 2016, 219, 937-948.	1.7	36
18	Tactile signals transmitted by the vibrissa during active whisking behavior. <i>Journal of Neurophysiology</i> , 2015, 113, 3511-3518.	1.8	33

#	ARTICLE	IF	CITATIONS
19	Variations in vibrissal geometry across the rat mystacial pad: base diameter, medulla, and taper. <i>Journal of Neurophysiology</i> , 2017, 117, 1807-1820.	1.8	27
20	The search space of the rat during whisking behavior. <i>Journal of Experimental Biology</i> , 2014, 217, 3365-3376.	1.7	25
21	The Cellular and Mechanical Basis for Response Characteristics of Identified Primary Afferents in the Rat Vibrissal System. <i>Current Biology</i> , 2020, 30, 815-826.e5.	3.9	23
22	Using hardware models to quantify sensory data acquisition across the rat vibrissal array. <i>Bioinspiration and Biomimetics</i> , 2007, 2, S135-S145.	2.9	22
23	Defining "active sensing" through an analysis of sensing energetics: homeoactive and alloactive sensing. <i>Journal of Neurophysiology</i> , 2020, 124, 40-48.	1.8	22
24	Probability distributions of whisker "surface contact: quantifying elements of the rat vibrissotactile natural scene. <i>Journal of Experimental Biology</i> , 2015, 218, 2551-2562.	1.7	21
25	Simulations of a Vibrissa Slipping along a Straight Edge and an Analysis of Frictional Effects during Whisking. <i>IEEE Transactions on Haptics</i> , 2016, 9, 158-169.	2.7	21
26	Ergodic Exploration Using Binary Sensing for Nonparametric Shape Estimation. <i>IEEE Robotics and Automation Letters</i> , 2017, 2, 827-834.	5.1	21
27	A two-dimensional force sensor in the millinewton range for measuring vibrissal contacts. <i>Journal of Neuroscience Methods</i> , 2008, 172, 158-167.	2.5	20
28	Whisking Kinematics Enables Object Localization in Head-Centered Coordinates Based on Tactile Information from a Single Vibrissa. <i>Frontiers in Behavioral Neuroscience</i> , 2016, 10, 145.	2.0	19
29	Active touch, exploratory movements, and sensory prediction. <i>Integrative and Comparative Biology</i> , 2009, 49, 681-690.	2.0	18
30	Evidence for Functional Groupings of Vibrissae across the Rodent Mystacial Pad. <i>PLoS Computational Biology</i> , 2016, 12, e1004109.	3.2	17
31	Sensory prediction on a whiskered robot: a tactile analogy to "optical flow". <i>Frontiers in Neurorobotics</i> , 2012, 6, 9.	2.8	15
32	Quantifying the three-dimensional facial morphology of the laboratory rat with a focus on the vibrissae. <i>PLoS ONE</i> , 2018, 13, e0194981.	2.5	14
33	Whisker Vibrations and the Activity of Trigeminal Primary Afferents in Response to Airflow. <i>Journal of Neuroscience</i> , 2019, 39, 5881-5896.	3.6	9
34	Constraints on the deformation of the vibrissa within the follicle. <i>PLoS Computational Biology</i> , 2021, 17, e1007887.	3.2	9
35	Quantification of vibrissal mechanical properties across the rat mystacial pad. <i>Journal of Neurophysiology</i> , 2019, 121, 1879-1895.	1.8	8
36	WhiskSight: A Reconfigurable, Vision-Based, Optical Whisker Sensing Array for Simultaneous Contact, Airflow, and Inertia Stimulus Detection. <i>IEEE Robotics and Automation Letters</i> , 2021, 6, 3357-3364.	5.1	7

#	ARTICLE	IF	CITATIONS
37	Linear reactive control for efficient 2D and 3D bipedal walking over rough terrain. <i>Adaptive Behavior</i> , 2013, 21, 29-46.	1.9	6
38	Contact-Resistive Sensing of Touch and Airflow Using A Rat Whisker. , 2018, , .		4
39	A dynamical model for generating synthetic data to quantify active tactile sensing behavior in the rat. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , 2021, 118, .	7.1	4
40	Representation of Stimulus Speed and Direction in Vibrissal-Sensitive Regions of the Trigeminal Nuclei: A Comparison of Single Unit and Population Responses. <i>PLoS ONE</i> , 2016, 11, e0158399.	2.5	4
41	Tapered Polymer Whiskers to Enable Three-Dimensional Tactile Feature Extraction. <i>Soft Robotics</i> , 2021, 8, 44-58.	8.0	3
42	Continuous, multidimensional coding of 3D complex tactile stimuli by primary sensory neurons of the vibrissal system. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , 2021, 118, .	7.1	3
43	Principles and applications of active tactile sensing strategies in the rat vibrissal system. , 2010, , .		2
44	Linear reactive control of three-dimensional bipedal walking in the presence of noise and uncertainty. <i>Adaptive Behavior</i> , 2012, 20, 409-426.	1.9	2
45	Fluid-structure interaction of a flexible cantilever cylinder at low Reynolds numbers. <i>Physical Review Fluids</i> , 2022, 7, .	2.5	2
46	Towards an “early neural circuit simulator”; A FPGA implementation of processing in the rat whisker system. , 2008, , .		1
47	Impaired trigeminal control of ingestive behavior in the <i>Prrxl1</i> ^{-/-} mouse is associated with a lemniscal-biased orosensory deafferentation. <i>PLoS ONE</i> , 2022, 17, e0258837.	2.5	1
48	Biology to Technology in Active Touch Sensing â€“ Introduction to the Special Section. <i>IEEE Transactions on Haptics</i> , 2016, 9, 155-157.	2.7	0
49	Shaking Paws Is Not the Same as Shaking Hands. <i>Neuron</i> , 2019, 102, 911-913.	8.1	0
50	A novel stimulator to investigate the tuning of multi-whisker responsive neurons for speed and the direction of global motion: Contact-sensitive moving stimulator for multi-whisker stimulation. <i>Journal of Neuroscience Methods</i> , 2022, 374, 109565.	2.5	0