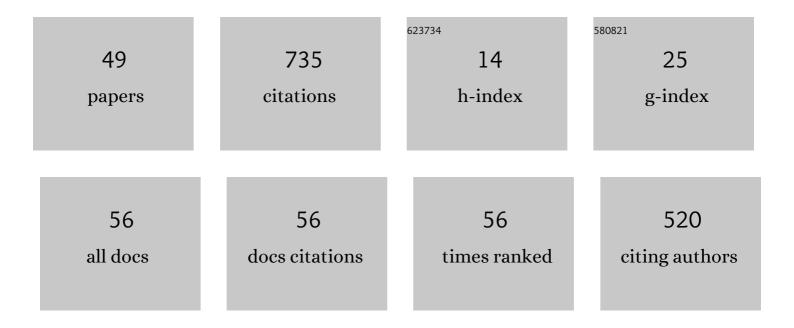
Johan Thunberg

List of Publications by Year in descending order

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| # | Article | IF | CITATIONS |
|----|--|----------|-----------|
| 1 | Distributed attitude synchronization control of multi-agent systems with switching topologies. Automatica, 2014, 50, 832-840. | 5.0 | 117 |
| 2 | Almost Global Consensus on the <inline-formula> <tex-math notation="LaTeX">\$n\$ </tex-math </inline-formula> -Sphere. IEEE Transactions on Automatic Control, 2018, 63, 1664-1675. | 5.7 | 83 |
| 3 | Consensus and formation control on <mml:math <br="" xmlns:mml="http://www.w3.org/1998/Math/MathML">altimg="si3.gif" display="inline" overflow="scroll"><mml:mi>S</mml:mi><mml:mi>E</mml:mi><mml:mrow><mml:mo>(</mml:mo><ml:mn>3for switching topologies. Automatica. 2016. 66. 109-121.</ml:mn></mml:mrow></mml:math> | nml:mn≻∢ | (59) |
| 4 | Vehicle-to-Vehicle Communications for Platooning: Safety Analysis. IEEE Networking Letters, 2019, 1, 168-172. | 1.9 | 40 |
| 5 | High-dimensional Kuramoto models on Stiefel manifolds synchronize complex networks almost globally. Automatica, 2020, 113, 108736. | 5.0 | 32 |
| 6 | A solution for multi-alignment by transformation synchronisation. , 2015, , . | | 31 |
| 7 | Shape-aware surface reconstruction from sparse 3D point-clouds. Medical Image Analysis, 2017, 38, 77-89. | 11.6 | 31 |
| 8 | Epipolar Visual Servoing for Multirobot Distributed Consensus. IEEE Transactions on Robotics, 2013, 29, 1212-1225. | 10.3 | 25 |
| 9 | Distributed attitude synchronization control. , 2011, , . | | 22 |
| 10 | A lifting method for analyzing distributed synchronization on the unit sphere. Automatica, 2018, 96, 253-258. | 5.0 | 20 |
| 11 | Optimal output consensus for linear systems: a topology free approach. Automatica, 2016, 68, 352-356. | 5.0 | 18 |
| 12 | Finite-Time Attitude Synchronization With Distributed Discontinuous Protocols. IEEE Transactions on Automatic Control, 2018, 63, 3608-3615. | 5.7 | 18 |
| 13 | A Mixed Integer Linear Programming approach to pursuit evasion problems with optional connectivity constraints. Autonomous Robots, 2011, 31, 333-343. | 4.8 | 16 |
| 14 | Distributed methods for synchronization of orthogonal matrices over graphs. Automatica, 2017, 80, 243-252. | 5.0 | 16 |
| 15 | Synchronisation of partial multi-matchings via non-negative factorisations. Pattern Recognition, 2019, 92, 146-155. | 8.1 | 16 |
| 16 | Safety of Automatic Emergency Braking in Platooning. IEEE Transactions on Vehicular Technology, 2022, 71, 2319-2332. | 6.3 | 16 |
| 17 | Local Lyapunov Functions for Consensus in Switching Nonlinear Systems. IEEE Transactions on Automatic Control, 2017, 62, 6466-6472. | 5.7 | 14 |
| 18 | Linear Dynamic Network Reconstruction from Heterogeneous Datasets. IFAC-PapersOnLine, 2017, 50, 10586-10591 | 0.9 | 12 |

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| 19 | Dynamic controllers for column synchronization of rotation matrices: A QR-factorization approach. Automatica, 2018, 93, 20-25. | 5.0 | 11 |
| 20 | Vehicle-to-Vehicle Communication for Safe and Fuel-Efficient Platooning. , 2020, , . | | 11 |
| 21 | Distributed high-gain attitude synchronization using rotation vectors. Journal of Systems Science and Complexity, 2015, 28, 289-304. | 2.8 | 10 |
| 22 | Cyber-Physical Systems: A Model-Based Approach. , 2021, , . | | 10 |
| 23 | Efficiently Bounding the Probabilities of Vehicle Collision at Intelligent Intersections. IEEE Open Journal of Intelligent Transportation Systems, 2021, 2, 47-59. | 4.8 | 10 |
| 24 | Multi-robot distributed visual consensus using epipoles. , 2011, , . | | 9 |
| 25 | Unreliable V2X Communication in Cooperative Driving: Safety Times for Emergency Braking. IEEE Access, 2021, 9, 148024-148036. | 4.2 | 9 |
| 26 | Distributed attitude synchronization control of multi-agent systems with directed topologies. , 2012, , . | | 8 |
| 27 | An iterative Mixed Integer Linear Programming Approach to pursuit evasion problems in polygonal environments. , 2010, , . | | 7 |
| 28 | A boolean control network approach to pursuit evasion problems in polygonal environments. , 2011, , . | | 7 |
| 29 | A Comparative Study of Task Assignment and Path Planning Methods for Multi-UGV Missions. Lecture Notes in Control and Information Sciences, 2009, , 167-180. | 1.0 | 7 |
| 30 | Optimal positioning of surveillance UGVs. , 2008, , . | | 6 |
| 31 | Distributed attitude synchronization using backstepping and sliding mode control. Control Theory and Technology, 2014, 12, 48-55. | 1.6 | 6 |
| 32 | Dynamic network reconstruction from heterogeneous datasets. Automatica, 2021, 123, 109339. | 5.0 | 6 |
| 33 | Towards Almost Global Synchronization on the Stiefel Manifold. , 2018, , . | | 5 |
| 34 | Distributed attitude synchronization control of multi-agent systems with time-varying topologies. , 2012, , . | | 4 |
| 35 | Fast correspondences for statistical shape models of brain structures. , 2016, , . | | 4 |
| 36 | Emergency Braking With ACC: How Much Does V2V Communication Help?. IEEE Networking Letters, 2022, 4, 157-161. | 1.9 | 4 |

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| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 37 | Analytical solutions to feedback systems on the special orthogonal group SO(n). , 2013, , . | | 3 |
| 38 | Towards Optimal Positioning of Surveillance UGVs. Lecture Notes in Control and Information Sciences, 2009, , 221-233. | 1.0 | 3 |
| 39 | Dynamical Structure Function and Granger Causality: Similarities and differences. , 2015, , . | | 2 |
| 40 | IEEE Access Special Section Editorial: Recent Developments in Consensus Problems for Complex Networked Systems. IEEE Access, 2018, 6, 60993-60995. | 4.2 | 2 |
| 41 | A transformation of the Position Based Visual Servoing Problem into a convex optimization problem. , 2012, , . | | 1 |
| 42 | Attitude consensus using networks of uncalibrated cameras. , 2014, , . | | 1 |
| 43 | Sound Over-Approximation of Probabilities. Acta Cybernetica, 2020, 24, 269-285. | 0.6 | 1 |
| 44 | System Aliasing in Dynamic Network Reconstruction:Issues on Low Sampling Frequencies. IEEE Transactions on Automatic Control, 2021, 66, 5788-5801. | 5.7 | 1 |
| 45 | Integration of sparse electrophysiological measurements with preoperative MRI using 3D surface estimation in deep brain stimulation surgery. Proceedings of SPIE, 2017, , . | 0.8 | Ο |
| 46 | Network Stability, Realisation and Random Model Generation. , 2019, , . | | 0 |
| 47 | Transitively Consistent and Unbiased Multi-Image Registration using Numerically Stable Transformation Synchronisation. , 2015, , . | | 0 |
| 48 | Modeling Computational Systems. , 2021, , 79-96. | | 0 |
| 49 | Control Theory. , 2021, , 57-78. | | 0 |