Zhongkui Li

List of Publications by Year in descending order

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107 9,304 37 68
papers citations h-index g-index

109 109 109 3177 all docs docs citations times ranked citing authors

#	Article	IF	CITATIONS
1	An Operator-Theoretic Approach to Robust Event-Triggered Control of Network Systems With Frequency-Domain Uncertainties. IEEE Transactions on Automatic Control, 2023, 68, 2034-2047.	5.7	3
2	Distributed Robust Optimization Algorithms Over Uncertain Network Graphs. IEEE Transactions on Cybernetics, 2022, 52, 4451-4458.	9.5	5
3	Designing Zero-Gradient-Sum Protocols for Finite-Time Distributed Optimization Problem. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 4569-4577.	9.3	9
4	Is fully distributed adaptive protocol applicable to graphs containing a directed spanning tree?. Science China Information Sciences, 2022, 65, 1.	4.3	8
5	Fully Distributed Event-Based Protocols for Lur'e Systems Over Directed Graphs. IEEE Transactions on Circuits and Systems II: Express Briefs, 2022, 69, 1812-1816.	3.0	6
6	Survivable Networks for Consensus. IEEE Transactions on Control of Network Systems, 2022, 9, 588-600.	3.7	0
7	Fully Distributed Event-Triggered Affine Formation Maneuver Control Over Directed Graphs. IFAC-PapersOnLine, 2022, 55, 178-183.	0.9	3
8	Distributed sliding mode control for leaderâ€follower formation flight of fixedâ€wing unmanned aerial vehicles subject to velocity constraints. International Journal of Robust and Nonlinear Control, 2021, 31, 2110-2125.	3.7	36
9	Distributed Edge-Based Event-Triggered Formation Control. IEEE Transactions on Cybernetics, 2021, 51, 1241-1252.	9.5	64
10	Distributed Adaptive Tracking Control for Lur'e Systems With Event-Triggered Strategy. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2021, 51, 3263-3269.	9.3	12
11	Formation Reconfiguration for Fixed-Wing UAVs. Journal of Intelligent and Robotic Systems: Theory and Applications, 2021, 102, 1.	3.4	10
12	Event-triggered resilient network-level control of multi-agent systems under cyber attacks., 2021,,.		1
13	Distributed adaptive stabilization. Automatica, 2021, 129, 109616.	5.0	9
14	Robust <i>H</i> ₂ Consensus for Multi-Agent Systems With Parametric Uncertainties. IEEE Transactions on Circuits and Systems II: Express Briefs, 2021, 68, 2473-2477.	3.0	11
15	Robust Event-Triggered Consensus of Uncertain Network Systems. , 2021, , .		1
16	Privacy Preserving Discrete-Time Average Consensus by Injecting Edge-based Perturbations. , 2021, , .		1
17	Novel Adaptive Dynamic Event-Triggered Bipartite Consensus Protocols with Intermittent Updating and Interaction. , 2021, , .		2
18	Distributed PI Control for Consensus of Heterogeneous Multiagent Systems Over Directed Graphs. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 1602-1609.	9.3	61

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19	Distributed Continuous-Time Optimization With Scalable Adaptive Event-Based Mechanisms. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 3252-3257.	9.3	32
20	Robust Bipartite Consensus and Tracking Control of High-Order Multiagent Systems With Matching Uncertainties and Antagonistic Interactions. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 2541-2550.	9.3	62
21	Consensus disturbance rejection control of directed multi-agent networks with extended state observer. Chinese Journal of Aeronautics, 2020, 33, 1486-1493.	5.3	7
22	Distributed Optimal Coordination for Heterogeneous Linear Multiagent Systems With Event-Triggered Mechanisms. IEEE Transactions on Automatic Control, 2020, 65, 1763-1770.	5.7	80
23	Cooperative Output Regulation of Heterogeneous Multi-Agent Systems With Adaptive Edge-Event-Triggered Strategies. IEEE Transactions on Circuits and Systems II: Express Briefs, 2020, 67, 2199-2203.	3.0	26
24	Privacy Preserving Average Consensus by Adding Edge-based Perturbation Signals. , 2020, , .		6
25	A Sensitivity Minimization Approach to the Distributed Average Tracking Problem. , 2020, , .		1
26	Consensus in Networks of Nonlinear Integrators with Applications to Coordinated Path Following Control of Fixed-Wing UAVs. , 2020, , .		4
27	Distributed Adaptive Event-Triggered Consensus with Discrete Control Updating., 2020,,.		4
28	Finite-time Distributed ConvexOptimization with Zero-Gradient-Sum Algorithms. IFAC-PapersOnLine, 2020, 53, 2495-2500.	0.9	3
29	Resilient Network-level Design of Leader-follower Multi-agent Systems Against DoS Attacks. , 2020, , .		3
30	Fully Distributed Event-Triggered Protocols for Linear Multiagent Networks. IEEE Transactions on Automatic Control, 2019, 64, 1655-1662.	5.7	350
31	Robust Consensus for Multi-Agent Systems Communicating over Stochastic Uncertain Networks. SIAM Journal on Control and Optimization, 2019, 57, 3553-3570.	2.1	28
32	Coordinated flight control of miniature fixed-wing UAV swarms: methods and experiments. Science China Information Sciences, 2019, 62, 1.	4.3	62
33	Coordinated Tracking Control With Asynchronous Edge-Based Event-Triggered Communications. IEEE Transactions on Automatic Control, 2019, 64, 4321-4328.	5.7	102
34	On distributed high-gain adaptive stabilization. , 2019, , .		1
35	Bearingâ€only circumnavigation control of the multiâ€agent system around a moving target. IET Control Theory and Applications, 2019, 13, 2747-2757.	2.1	19
36	Coordinated Tracking of a Leader with Bounded Input Using Adaptive Event-Triggered Protocols*. , 2019, , .		1

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37	Distributed Formation Control via Output Feedback Event-Triggered Coordination. , 2019, , .		2
38	Fully Distributed Event-Based Protocols for Lipschitz Nonlinear Multi-Agent Systems., 2019,,.		2
39	Event-Triggered Consensus of Homogeneous and Heterogeneous Multiagent Systems With Jointly Connected Switching Topologies. IEEE Transactions on Cybernetics, 2019, 49, 4421-4430.	9.5	98
40	Coherence of Noisy Double-Integrator Networks Without Velocity Measurements. IEEE Transactions on Circuits and Systems II: Express Briefs, 2019, 66, 993-997.	3.0	4
41	Designing Fully Distributed Adaptive Event-Triggered Controllers for Networked Linear Systems With Matched Uncertainties. IEEE Transactions on Neural Networks and Learning Systems, 2019, 30, 3645-3655.	11.3	104
42	Consensus disturbance rejection with event-triggered communications. Journal of the Franklin Institute, 2019, 356, 956-974.	3.4	36
43	Distributed PI Control of Active-Passive Networked Linear Multi-agent Systems. , 2019, , .		0
44	Fully Distributed Adaptive PI Controllers for Heterogeneous Linear Networks. IEEE Transactions on Circuits and Systems II: Express Briefs, 2018, 65, 1209-1213.	3.0	29
45	Cooperative Guidance Law Design for Simultaneous Attack with Multiple Missiles Against a Maneuvering Target. Journal of Systems Science and Complexity, 2018, 31, 287-301.	2.8	36
46	Distributed adaptive consensus protocols for linear multiâ€agent systems over directed graphs with relative output information. IET Control Theory and Applications, 2018, 12, 613-620.	2.1	29
47	Distributed Adaptive Convex Optimization on Directed Graphs via Continuous-Time Algorithms. IEEE Transactions on Automatic Control, 2018, 63, 1434-1441.	5.7	134
48	Fully Distributed Consensus Control for Nonlinear Multi-agent Network with Extended State Observer. , $2018, \ldots$		1
49	Event-Triggered Consensus of Multi-Agent Systems with Jointly Connected Switching Topologies. , 2018, , .		0
50	Distributed Adaptive Consensus Disturbance Rejection for Multi-Agent Systems on Directed Graphs. IEEE Transactions on Control of Network Systems, 2018, 5, 629-639.	3.7	85
51	Novel distributed robust adaptive consensus protocols for linear multi-agent systems with directed graphs and external disturbances. International Journal of Control, 2017, 90, 137-147.	1.9	84
52	Observer-based consensus of networked thrust-propelled vehicles with directed graphs. ISA Transactions, 2017, 71, 130-137.	5.7	5
53	Robust consensus of Lur'e networks with uncertain communications. IET Control Theory and Applications, 2017, 11, 877-882.	2.1	5
54	Robust Consensus of Linear Feedback Protocols Over Uncertain Network Graphs. IEEE Transactions on Automatic Control, 2017, 62, 4251-4258.	5.7	123

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55	Event-triggered encirclement control of multi-agent systems with bearing rigidity. Science China Information Sciences, 2017, 60, 1.	4.3	15
56	Distributed containment control of Euler–Lagrange systems over directed graphs via distributed continuous controllers. IET Control Theory and Applications, 2017, 11, 1786-1795.	2.1	11
57	Simultaneous attack of a stationary target using multiple missiles: a consensus-based approach. Science China Information Sciences, 2017, 60, $\hat{1}$.	4.3	43
58	Distributed average tracking for multiple signals generated by linear dynamical systems: An edge-based framework. Automatica, 2017, 75, 158-166.	5.0	135
59	Distributed adaptive consensus protocol design for heterogeneous multi-agent systems with switching communication topologies., 2017,,.		4
60	Consensus disturbance rejection over uncertain networks., 2017,,.		1
61	Consensus of directed networks of thrust-propelled vehicles using distributed observed-based protocols., 2017,,.		O
62	Consensus of linear multi-agent systems via fully distributed event-triggered protocols., 2017,,.		1
63	Output consensus of heterogeneous linear multi-agent systems via fully distributed event-triggered protocols., 2017,,.		1
64	Adaptive consensus disturbance rejection for multi-agent systems on directed graphs. , 2016, , .		0
65	Coordinated tracking of Euler-Lagrange systems over directed graphs via distributed continuous controllers., 2016,,.		0
66	Distributed adaptive output feedback consensus protocols for linear systems on directed graphs with a leader of bounded input. Automatica, 2016, 74, 308-314.	5.0	142
67	Distributed adaptive consensus protocols for linear multi-agent systems: An integrated design approach. , 2016, , .		2
68	Robust consensus of multi-agent systems with stochastic uncertain channels. , 2016, , .		13
69	Distributed adaptive consensus control of nonlinear output-feedback systems on directed graphs. Automatica, 2016, 72, 46-52.	5.0	113
70	Robust consensus of discrete-time linear agents over deterministic uncertain channels. , 2016, , .		0
71	Distributed adaptive consensus protocols for multiple Lur'e systems over directed graphs. IET Control Theory and Applications, 2016, 10, 443-450.	2.1	31
72	Distributed adaptive controllers for cooperative output regulation of heterogeneous agents over directed graphs. Automatica, 2016, 68, 179-183.	5.0	170

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73	On constructing Lyapunov functions for multi-agent systems. Automatica, 2015, 58, 39-42.	5.0	203
74	Distributed adaptive consensus and output tracking of unknown linear systems on directed graphs. Automatica, 2015, 55, 12-18.	5.0	83
75	Adaptive output-feedback consensus protocol design for linear multi-agent systems with directed graphs. , 2015, , .		7
76	Distributed adaptive consensus protocols for linear multi-agent systems with directed graphs and a leader of unknown control input. , 2015 , , .		0
77	Containment control of linear multiâ€agent systems with multiple leaders of bounded inputs using distributed continuous controllers. International Journal of Robust and Nonlinear Control, 2015, 25, 2101-2121.	3.7	144
78	Distributed Robust Consensus of a Class of <scp>L</scp> ipschitz Nonlinear Multiâ€agent Systems with Matching Uncertainties. Asian Journal of Control, 2015, 17, 3-13.	3.0	17
79	Designing Fully Distributed Consensus Protocols for Linear Multi-Agent Systems With Directed Graphs. IEEE Transactions on Automatic Control, 2015, 60, 1152-1157.	5.7	809
80	Distributed average tracking for multiple signals with linear dynamics: An edge-based framework, , 2014, , .		3
81	Distributed consensus protocol design for general linear multiâ€agent systems: a consensus region approach. IET Control Theory and Applications, 2014, 8, 2145-2161.	2.1	34
82	Recent Developments in Networked Control and Estimation. IET Control Theory and Applications, 2014, 8, 2123-2125.	2.1	9
83	Robust redesign of distributed adaptive consensus protocols for linear multi-agent systems. , 2014, , .		1
84	Distributed adaptive consensus protocols for linear multi-agent systems with directed graphs in the presence of external disturbances. , 2014 , , .		5
85	Distributed robust consensus control of multi-agent systems with heterogeneous matching uncertainties. Automatica, 2014, 50, 883-889.	5.0	246
86	Distributed <i>H</i> _{â^ž} and <i>H</i> ₂ consensus control in directed networks. IET Control Theory and Applications, 2014, 8, 193-201.	2.1	39
87	Distributed robust leaderless consensus of Lipschitz nonlinear multi-agent systems with matching uncertainties., 2014,,.		5
88	Distributed containment control of multiâ€agent systems with general linear dynamics in the presence of multiple leaders. International Journal of Robust and Nonlinear Control, 2013, 23, 534-547.	3.7	450
89	Consensus condition for linear multi-agent systems over randomly switching topologies. Automatica, 2013, 49, 3125-3132.	5.0	238
90	Distributed consensus tracking of multi-agent systems with nonlinear dynamics under a reference leader. International Journal of Control, 2013, 86, 1859-1869.	1.9	67

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91	Distributed tracking control of multi-agent systems with heterogeneous uncertainties. , 2013, , .		2
92	Consensus of Multi-Agent Systems With General Linear and Lipschitz Nonlinear Dynamics Using Distributed Adaptive Protocols. IEEE Transactions on Automatic Control, 2013, 58, 1786-1791.	5.7	695
93	Distributed Tracking Control for Linear Multiagent Systems With a Leader of Bounded Unknown Input. IEEE Transactions on Automatic Control, 2013, 58, 518-523.	5.7	452
94	Distributed consensus of linear multi-agent systems with adaptive dynamic protocols. Automatica, 2013, 49, 1986-1995.	5.0	531
95	Adaptive containment control of coupled linear systems with parameter uncertainties. , 2013, , .		6
96	Distributed robust control of linear multi-agent systems with parameter uncertainties. International Journal of Control, 2012, 85, 1039-1050.	1.9	107
97	Global synchronised regions of linearly coupled Lur'e systems. International Journal of Control, 2011, 84, 216-227.	1.9	43
98	On <mml:math altimg="si4.gif" display="inline" overflow="scroll" xmlns:mml="http://www.w3.org/1998/Math/MathML"> <mml:msub><mml:mrow><mml:mi>H</mml:mi></mml:mrow><mml:mrow><mml:mi>a^ž <mml:msub><mml:mrow><mml:mi>H</mml:mi>H</mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:mrow><mml:< td=""><td>5.0</td><td>191</td></mml:<></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:mrow></mml:msub></mml:mi></mml:mrow></mml:msub></mml:math>	5.0	191
99	performance regions of multi-agent systems. Automatica, 2011, 47, 797-803. Consensus of linear multi-agent systems with reduced-order observer-based protocols. Systems and Control Letters, 2011, 60, 510-516.	2.3	220
100	Consensus of discrete-time linear multi-agent systems with observer-type protocols. Discrete and Continuous Dynamical Systems - Series B, 2011, 16, 489-505.	0.9	77
101	Consensus of Multiagent Systems and Synchronization of Complex Networks: A Unified Viewpoint. IEEE Transactions on Circuits and Systems I: Regular Papers, 2010, 57, 213-224.	5.4	1,902
102	Global consensus regions of multi-agent systems with nonlinear dynamics. , 2010, , .		3
103	H â^ž control of networked multi-agent systems. Journal of Systems Science and Complexity, 2009, 22, 35-48.	2.8	55
104	Leader-follower consensus of multi-agent systems. , 2009, , .		47
105	Disturbance rejection and H _{â^ž} pinning control of networked multi-agent systems. , 2008, , .		2
106	Decentralized dynamic output feedback for globally asymptotic stabilization of a class of dynamic networks. International Journal of Control, 2008, 81, 1054-1061.	1.9	4
107	Network sensitivity function, optimization and robust performance in dynamic average consensus. International Journal of Robust and Nonlinear Control, 0, , .	3.7	1