Haibo Du

List of Publications by Year in descending order

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112	5,721	33	71
papers	citations	h-index	g-index
113	113	113	3207
all docs	docs citations	times ranked	citing authors

#	Article	IF	CITATIONS
1	Finite-time consensus algorithm for multi-agent systems with double-integrator dynamics. Automatica, 2011, 47, 1706-1712.	5.0	788
2	Finite-Time Attitude Tracking Control of Spacecraft With Application to Attitude Synchronization. IEEE Transactions on Automatic Control, 2011, 56, 2711-2717.	5.7	649
3	Chattering-free discrete-time sliding mode control. Automatica, 2016, 68, 87-91.	5.0	257
4	Distributed Formation Control of Multiple Quadrotor Aircraft Based on Nonsmooth Consensus Algorithms. IEEE Transactions on Cybernetics, 2019, 49, 342-353.	9.5	225
5	Finite-Time Synchronization of a Class of Second-Order Nonlinear Multi-Agent Systems Using Output Feedback Control. IEEE Transactions on Circuits and Systems I: Regular Papers, 2014, 61, 1778-1788.	5.4	213
6	Discrete-Time Fast Terminal Sliding Mode Control for Permanent Magnet Linear Motor. IEEE Transactions on Industrial Electronics, 2018, 65, 9916-9927.	7.9	197
7	Global Output Feedback Stabilization of a Class of Nonlinear Systems via Linear Sampled-Data Control. IEEE Transactions on Automatic Control, 2012, 57, 2934-2939.	5.7	194
8	Finite-Time Attitude Stabilization for a Spacecraft Using Homogeneous Method. Journal of Guidance, Control, and Dynamics, 2012, 35, 740-748.	2.8	188
9	Distributed fixed-time consensus for nonlinear heterogeneous multi-agent systems. Automatica, 2020, 113, 108797.	5.0	173
10	Finiteâ€time formation control of multiple nonholonomic mobile robots. International Journal of Robust and Nonlinear Control, 2014, 24, 140-165.	3.7	169
11	Discrete-Time Terminal Sliding Mode Control Systems Based on Euler's Discretization. IEEE Transactions on Automatic Control, 2014, 59, 546-552.	5.7	163
12	Finite-time consensus of multiple nonholonomic chained-form systems based on recursive distributed observer. Automatica, 2015, 62, 236-242.	5.0	162
13	Attitude synchronization control for a group of flexible spacecraft. Automatica, 2014, 50, 646-651.	5.0	157
14	Recursive design of finite-time convergent observers for a class of time-varying nonlinear systems. Automatica, 2013, 49, 601-609.	5.0	149
15	Distributed Finite-Time Cooperative Control of Multiple High-Order Nonholonomic Mobile Robots. IEEE Transactions on Neural Networks and Learning Systems, 2017, 28, 2998-3006.	11.3	142
16	A Distributed Finite-Time Consensus Algorithm for Higher-Order Leaderless and Leader-Following Multiagent Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2017, 47, 1625-1634.	9.3	139
17	Attitude Synchronization for Flexible Spacecraft With Communication Delays. IEEE Transactions on Automatic Control, 2016, 61, 3625-3630.	5.7	124
18	Global sampled-data output feedback stabilization for a class of uncertain nonlinear systems. Automatica, 2019, 99, 403-411.	5.0	111

#	Article	IF	Citations
19	Robust consensus algorithm for second-order multi-agent systems with external disturbances. International Journal of Control, 2012, 85, 1913-1928.	1.9	98
20	Finite-time formation control for a group of quadrotor aircraft. Aerospace Science and Technology, 2017, 69, 609-616.	4.8	87
21	Finiteâ€time formation control of multiagent systems via dynamic output feedback. International Journal of Robust and Nonlinear Control, 2013, 23, 1609-1628.	3.7	82
22	Current Sharing Control for Parallel DC–DC Buck Converters Based on Finite-Time Control Technique. IEEE Transactions on Industrial Informatics, 2019, 15, 2186-2198.	11.3	67
23	Robust finiteâ€time consensus formation control for multiple nonholonomic wheeled mobile robots via output feedback. International Journal of Robust and Nonlinear Control, 2018, 28, 2082-2096.	3.7	59
24	Secondâ€order consensus for nonlinear leaderâ€following multiâ€agent systems via dynamic output feedback control. International Journal of Robust and Nonlinear Control, 2016, 26, 329-344.	3.7	56
25	Global stabilization of a class of uncertain upperâ€ŧriangular systems under sampledâ€data control. International Journal of Robust and Nonlinear Control, 2013, 23, 620-637.	3.7	49
26	Robustness Analysis of a Continuous Higher Order Finite-Time Control System Under Sampled-Data Control. IEEE Transactions on Automatic Control, 2019, 64, 2488-2494.	5.7	47
27	Global Stabilization via Sampled-Data Output Feedback for a Class of Linearly Uncontrollable and Unobservable Systems. IEEE Transactions on Automatic Control, 2016, 61, 4088-4093.	5.7	46
28	Hovering control for quadrotor aircraft based on finite-time control algorithm. Nonlinear Dynamics, 2017, 88, 2359-2369.	5.2	46
29	Design and Implementation of Bounded Finite-Time Control Algorithm for Speed Regulation of Permanent Magnet Synchronous Motor. IEEE Transactions on Industrial Electronics, 2021, 68, 2417-2426.	7.9	45
30	Fixed-Time Synchronization Control for a Class of Master–Slave Systems Based on Homogeneous Method. IEEE Transactions on Circuits and Systems II: Express Briefs, 2019, 66, 1547-1551.	3.0	41
31	Fast Adaptive Finite-Time Voltage Regulation Control Algorithm for a Buck Converter System. IEEE Transactions on Circuits and Systems II: Express Briefs, 2017, 64, 1082-1086.	3.0	38
32	Fixed-time attitude stabilization for a rigid spacecraft. ISA Transactions, 2020, 98, 263-270.	5.7	37
33	Finite-time tracking control for a class of high-order nonlinear systems and its applications. Nonlinear Dynamics, 2014, 76, 1133-1140.	5.2	36
34	Designing Discrete-Time Sliding Mode Controller With Mismatched Disturbances Compensation. IEEE Transactions on Industrial Informatics, 2020, 16, 4109-4118.	11.3	35
35	Further results on finiteâ€time consensus of secondâ€order multiâ€agent systems without velocity measurements. International Journal of Robust and Nonlinear Control, 2016, 26, 3170-3185.	3.7	33
36	Global sampledâ€data output feedback stabilisation of a class of upperâ€triangular systems with input delay. IET Control Theory and Applications, 2013, 7, 1437-1446.	2.1	31

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37	Synchronization of nonlinear networked agents under event-triggered control. Information Sciences, 2018, 459, 317-326.	6.9	30
38	Position tracking control for permanent magnet linear motor via fast nonsingular terminal sliding mode control. Nonlinear Dynamics, 2019, 97, 2595-2605.	5.2	30
39	Fixedâ€Time Synchronization of a Class of Secondâ€Order Nonlinear Leaderâ€Following Multiâ€Agent Systems. Asian Journal of Control, 2018, 20, 39-48.	3.0	28
40	Finite-time output feedback tracking control for a nonholonomic wheeled mobile robot. Aerospace Science and Technology, 2018, 78, 574-579.	4.8	28
41	Global Event-Triggered Output Feedback Stabilization of a Class of Nonlinear Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2021, 51, 4040-4047.	9.3	28
42	Finite-time output feedback control for a class of second-order nonlinear systems with application to DC–DC buck converters. Nonlinear Dynamics, 2014, 78, 2021-2030.	5.2	27
43	Circulating Current Suppression of Parallel Photovoltaic Grid-Connected Converters. IEEE Transactions on Circuits and Systems II: Express Briefs, 2018, 65, 1214-1218.	3.0	25
44	Active finite-time disturbance rejection control for attitude tracking of quad-rotor under input saturation. Journal of the Franklin Institute, 2020, 357, 11153-11170.	3.4	22
45	Formation control for multiquadrotor aircraft: Connectivity preserving and collision avoidance. International Journal of Robust and Nonlinear Control, 2020, 30, 2352-2366.	3.7	22
46	Robust finite-time synchronization of coupled harmonic oscillations with external disturbance. Journal of the Franklin Institute, 2015, 352, 4366-4381.	3.4	21
47	A semi-global finite-time convergent observer for a class of nonlinear systems with bounded trajectories. Nonlinear Analysis: Real World Applications, 2012, 13, 1827-1836.	1.7	20
48	A generalised homogeneous solution for global stabilisation of a class of non-smooth upper-triangular systems. International Journal of Control, 2014, 87, 951-963.	1.9	19
49	Position control for permanent magnet synchronous motor based on neural network and terminal sliding mode control. Transactions of the Institute of Measurement and Control, 2020, 42, 1632-1640.	1.7	19
50	A genuine nonlinear approach for controller design of a boiler–turbine system. ISA Transactions, 2012, 51, 446-453.	5.7	18
51	Design of Robust Discretized Sliding Mode Controller: Analysis and Application to Buck Converters. IEEE Transactions on Industrial Electronics, 2020, 67, 10672-10681.	7.9	18
52	Universal finite-time observer based second-order sliding mode control for DC-DC buck converters with only output voltage measurement. Journal of the Franklin Institute, 2020, 357, 11863-11879.	3.4	17
53	Implementation of integral fixed-time sliding mode controller for speed regulation of PMSM servo system. Nonlinear Dynamics, 2020, 102, 185-196.	5.2	16
54	Design of Output-Based Finite-Time Convergent Composite Controller for a Class of Perturbed Second-Order Nonlinear Systems. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2021, 51, 6768-6778.	9.3	15

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55	Robust adaptive finiteâ€time trajectory tracking control of a quadrotor aircraft. International Journal of Robust and Nonlinear Control, 2021, 31, 8030-8054.	3.7	14
56	Synchronization of a class of nonlinear multi-agent systems with sampled-data information. Nonlinear Dynamics, 2015, 82, 1483-1492.	5.2	12
57	Homogeneous constrained finite-time controller for double integrator systems: Analysis and experiment. Automatica, 2021, 134, 109894.	5.0	11
58	Control of a hovering quadrotor aircraft based finite-time attitude control algorithm. , 2016, , .		10
59	Position Tracking Control for Permanent Magnet Linear Motor via Continuous-Time Fast Terminal Sliding Mode Control. Journal of Control Science and Engineering, 2018, 2018, 1-6.	1.0	10
60	Nonsmooth Observer-Based Sensorless Speed Control for Permanent Magnet Synchronous Motor. IEEE Transactions on Industrial Electronics, 2022, 69, 13514-13523.	7.9	9
61	Global finite-time attitude regulation using bounded feedback for a rigid spacecraft. Control Theory and Technology, 2017, 15, 26-33.	1.6	8
62	Attitude trajectory planning and attitude control for quad-rotor aircraft based on finite-time control technique. Applied Mathematics and Computation, 2020, 386, 125493.	2.2	8
63	Neural network-based robust finite-time attitude stabilization for rigid spacecraft under angular velocity constraint. Neural Computing and Applications, 2022, 34, 5107-5117.	5.6	7
64	Current sharing control for parallel DC-DC buck converters based on consensus theory. , 2017, , .		6
65	Globally exponential stabilization for a class of nonlinear systems with time delays both in nonlinearities and input. Applied Mathematics and Computation, 2019, 359, 478-489.	2.2	6
66	On eventâ€triggered nonsmooth attitude tracking controller for a rigid spacecraft. International Journal of Robust and Nonlinear Control, 2022, 32, 900-916.	3.7	6
67	Position tracking control for permanent magnet synchronous motor based on integral high-order terminal sliding mode control. , 2017, , .		5
68	Finite-time attitude regulation control for a rigid spacecraft under input saturation. , 2014, , .		4
69	Fixed-time synchronization of a class of second-order nonlinear multi-agent systems. , 2016, , .		4
70	Finite-time formation control of multiple mobile robots. , 2016, , .		4
71	Distributed formation control of multiple quadrotor aircraft based on quaternion. , 2017, , .		4
72	Intelligent station area recognition technology based on NB-IoT and SVM. , 2019, , .		4

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73	Finite-Time Consensus for Power Regulation of Parallel PV Grid-Connected Inverters. IEEE Transactions on Circuits and Systems II: Express Briefs, 2020, 67, 2632-2636.	3.0	4
74	Finite-time position tracking control of a quadrotor aircraft., 2017,,.		3
75	Application research on improved CGAN in image raindrop removal. Journal of Engineering, 2019, 2019, 8404-8408.	1.1	3
76	Research on Angle Steel Tower Climbing Robot System Based on Digital Twin. , 2020, , .		3
77	Global output feedback stabilization of a class of upper-triangular systems with input delay. , 2012, , .		2
78	Analysis of the effect of sampled-data control on continuous finite-time control systems. , 2014, , .		2
79	Finite-time output feedback control for DC-DC buck power converters system. , 2017, , .		2
80	Finite-time speed regulation control for permanent magnet synchronous motor system. , 2017, , .		2
81	Finite-time consensus control for a group of quadrotor aircraft. , 2017, , .		2
82	Finite-time Leaderless Consensus of Second-order Multi-agent Systems With Velocity and Input Constraints. , 2020, , .		2
83	Indoor positioning system based on multi-camera joint calibration. , 2021, , .		2
84	Current-constrained finite-time control algorithm for DC-DC Buck converter. Journal of the Franklin Institute, 2021, 358, 9467-9467.	3.4	2
85	Chattering-Free Discrete-time Fast Terminal Sliding Mode Control of Automotive Electronic Throttle with Disturbances. , 2020, , .		2
86	Gait Planning of Quadruped Robot Based on ROS. , 2020, , .		2
87	Finite-time consensus tracking of multiple coupled harmonic oscillations via bounded control. , 2013, , .		1
88	Design and application of field equipment information acquisition system based on OPC. , 2017, , .		1
89	Attitude Trajectory Planning and Finite-Time Attitude Tracking Control for a Quadrotor Aircraft. , 2018, , .		1
90	A Nested Saturated Second-order Sliding Mode Controller Design. , 2018, , .		1

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91	Observerâ€based finiteâ€time outputâ€feedback controller for DCâ€DC buck converters with unknown load variations. International Journal of Robust and Nonlinear Control, 2019, 29, 5274-5289.	3.7	1
92	Observer-Based Output Feedback Stabilization for Perturbed Second-Order Uncertain System with Finite-Time Convergence. , 2019, , .		1
93	Speed Regulation for PMSM Based on Fixed-time Sliding Mode Control. , 2020, , .		1
94	Robust discrete-time non-smooth consensus protocol for multi-agent systems via super-twisting algorithm. Applied Mathematics and Computation, 2022, 413, 126636.	2.2	1
95	Global finite-time attitude stabilization for spacecraft under velocity constraint., 2020,,.		1
96	Research on trajectory planning method of dual-arm robot based on ROS. , 2020, , .		1
97	Analysis and control of complex cyberâ€physical networks. Asian Journal of Control, 2022, 24, 495-497.	3.0	1
98	Analysis and Synthesis of Stochastic Nonlinear Systems. Mathematical Problems in Engineering, 2015, 2015, 1-2.	1.1	0
99	Pinning synchronization of complex networks with Lur'e-type nodes and directed switching topology. , 2015, , .		0
100	Global finite-time stabilization of second-order systems subject to mismatched disturbances with application to consensus. , 2015 , , .		0
101	Attitude synchronization for multiple heterogeneous spacecraft with communication delays. , 2016, , .		0
102	Global Stabilization for A Class of Nonlinear Systems with Time Delays via Sampled-Data Output Feedback * *This work is supported by the National Natural Science Foundation of China under grant nos. 61473080, 61673153, 61503078, 61628302 and 61504027, the NSF of Jiangsu Province (BK20140647), t Fundamental Research Funds for the Central Universities and the Priority Academic Program	he0.9	0
103	Development of Jiangsu Higher Education Institutions IFAC-PapersOnLine, 2017, 50, 16040-16045. Distributed Control of Networked Agent Systems: Theory and Applications. Journal of Control Science and Engineering, 2017, 2017, 1-2.	1.0	0
104	Second-Order Sliding Mode Control of Nonlinear Systems with Nonvanishing Mismatched Disturbance. , 2018, , .		0
105	Position Tracking Control for Permanent Magnet Linear Motor via Discrete-time Terminal Sliding Mode Control. , 2018, , .		0
106	Integral Active Finite-time Disturbance Rejection Control for Attitude Tracking of Quad-rotor. , 2019, , .		0
107	Current-constrained Finite-time Control Algorithm for Buck Converter. , 2020, , .		0
108	Autonomous Obstacle Navigating System of Quadrotor UAV Based on Vision Positioning and Cascade Control Algorithm. , 2021, , .		0

#	Article	IF	CITATIONS
109	Flying velocity constraint control for quad-rotor system based on finite-Time control technique. , 2020, , .		O
110	A Coupled Finite-Time Attitude Controller and Finite-Time Observer with an Unknown Constant Drift Bias. , 2020, , .		0
111	Design and Analysis of Nonlinear Constrained Control Algorithm for Rigid Aircraft. IFAC-PapersOnLine, 2020, 53, 476-478.	0.9	O
112	Research on finite-time consensus algorithm for second-order multi-agent systems under sampled-data control., 2021,,.		0