

Radu Serban

List of Publications by Year in descending order

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53
papers

3,371
citations

430754

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h-index

254106

43
g-index

56
all docs

56
docs citations

56
times ranked

3491
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | SUNDIALS. ACM Transactions on Mathematical Software, 2005, 31, 363-396. | 1.6 | 2,134 |
| 2 | Adjoint Sensitivity Analysis for Differential-Algebraic Equations: The Adjoint DAE System and Its Numerical Solution. SIAM Journal of Scientific Computing, 2003, 24, 1076-1089. | 1.3 | 284 |
| 3 | Chrono: An Open Source Multi-physics Dynamics Engine. Lecture Notes in Computer Science, 2016, , 19-49. | 1.0 | 105 |
| 4 | Sensitivity analysis of differential-algebraic equations and partial differential equations. Computers and Chemical Engineering, 2006, 30, 1553-1559. | 2.0 | 84 |
| 5 | A high-fidelity approach for vehicle mobility simulation: Nonlinear finite element tires operating on granular material. Journal of Terramechanics, 2017, 72, 39-54. | 1.4 | 78 |
| 6 | Identification and Identifiability of Unknown Parameters in Multibody Dynamic Systems. Multibody System Dynamics, 2001, 5, 335-350. | 1.7 | 57 |
| 7 | Halo orbit mission correction maneuvers using optimal control. Automatica, 2002, 38, 571-583. | 3.0 | 55 |
| 8 | Error Estimation for Reduced-Order Models of Dynamical Systems. SIAM Review, 2007, 49, 277-299. | 4.2 | 50 |
| 9 | Error Estimation for Reduced-Order Models of Dynamical Systems. SIAM Journal on Numerical Analysis, 2005, 43, 1693-1714. | 1.1 | 49 |
| 10 | Parallel Computing in Multibody System Dynamics: Why, When, and How. Journal of Computational and Nonlinear Dynamics, 2014, 9, . | 0.7 | 41 |
| 11 | Kinematic and Kinetic Derivatives in Multibody System Analysis— . Mechanics Based Design of Structures and Machines, 1998, 26, 145-173. | 0.6 | 39 |
| 12 | Compliant contact versus rigid contact: A comparison in the context of granular dynamics. Physical Review E, 2017, 96, 042905. | 0.8 | 32 |
| 13 | Computational Algorithm for Dynamic Optimization of Chemical Vapor Deposition Processes in Stagnation Flow Reactors. Journal of the Electrochemical Society, 2000, 147, 2718. | 1.3 | 26 |
| 14 | Using a half-implicit integration scheme for the SPH-based solution of fluid–solid interaction problems. Computer Methods in Applied Mechanics and Engineering, 2019, 345, 100-122. | 3.4 | 25 |
| 15 | On the Importance of Displacement History in Soft-Body Contact Models. Journal of Computational and Nonlinear Dynamics, 2016, 11, . | 0.7 | 24 |
| 16 | Chrono::Vehicle: template-based ground vehicle modelling and simulation. International Journal of Vehicle Performance, 2019, 5, 18. | 0.2 | 23 |
| 17 | A Topology-Based Approach for Exploiting Sparsity in Multibody Dynamics in Cartesian Formulation*. Mechanics Based Design of Structures and Machines, 1997, 25, 379-396. | 0.6 | 21 |
| 18 | Adaptive algorithms for optimal control of time-dependent partial differential-algebraic equation systems. International Journal for Numerical Methods in Engineering, 2003, 57, 1457-1469. | 1.5 | 20 |

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 19 | Posing Multibody Dynamics With Friction and Contact as a Differential Complementarity Problem. <i>Journal of Computational and Nonlinear Dynamics</i> , 2018, 13, . | 0.7 | 20 |
| 20 | COOPT " a software package for optimal control of large-scale differential" algebraic equation systems. <i>Mathematics and Computers in Simulation</i> , 2001, 56, 187-203. | 2.4 | 17 |
| 21 | A GPU"based preconditioned Newton"Krylov solver for flexible multibody dynamics. <i>International Journal for Numerical Methods in Engineering</i> , 2015, 102, 1585-1604. | 1.5 | 17 |
| 22 | A Topology-Based Approach to Exploiting Sparsity in Multibody Dynamics: Joint Formulation*. <i>Mechanics Based Design of Structures and Machines</i> , 1997, 25, 221-241. | 0.6 | 14 |
| 23 | A High Performance Computing Approach to the Simulation of Fluid-Solid interaction Problems with Rigid and Flexible Components. <i>Archive of Mechanical Engineering</i> , 2014, 61, 227-251. | 0.7 | 13 |
| 24 | Deformable soil with adaptive level of detail for tracked and wheeled vehicles. <i>International Journal of Vehicle Performance</i> , 2019, 5, 60. | 0.2 | 13 |
| 25 | Globally Independent Coordinates for Real-Time Vehicle Simulation. <i>Journal of Mechanical Design, Transactions of the ASME</i> , 2000, 122, 575-582. | 1.7 | 12 |
| 26 | Chrono::GPU: An Open-Source Simulation Package for Granular Dynamics Using the Discrete Element Method. <i>Processes</i> , 2021, 9, 1813. | 1.3 | 12 |
| 27 | Numerical Methods for High-Speed Vehicle Dynamic Simulation. <i>Mechanics Based Design of Structures and Machines</i> , 1999, 27, 507-533. | 0.6 | 9 |
| 28 | The Effect of Problem Perturbations on Nonlinear Dynamical Systems and their Reduced-Order Models. <i>SIAM Journal of Scientific Computing</i> , 2007, 29, 2621-2643. | 1.3 | 8 |
| 29 | Implicit Integration in Molecular Dynamics Simulation. , 2008, , . | | 8 |
| 30 | Sensitivity Analysis for Hybrid Systems and Systems With Memory. <i>Journal of Computational and Nonlinear Dynamics</i> , 2019, 14, . | 0.7 | 8 |
| 31 | An integrated framework for high-performance, high-fidelity simulation of ground vehicle-tyre-terrain interaction. <i>International Journal of Vehicle Performance</i> , 2019, 5, 233. | 0.2 | 8 |
| 32 | Traction control design for off-road mobility using an SPH-DAE cosimulation framework. <i>Multibody System Dynamics</i> , 2022, 55, 165-188. | 1.7 | 7 |
| 33 | Efficient Computation of Sensitivities for Ordinary Differential Equation Boundary Value Problems. <i>SIAM Journal on Numerical Analysis</i> , 2002, 40, 220-232. | 1.1 | 6 |
| 34 | A model of macroscale deformation and microvibration in skeletal muscle tissue. <i>ESAIM: Mathematical Modelling and Numerical Analysis</i> , 2009, 43, 805-823. | 0.8 | 6 |
| 35 | A Sensor Simulation Framework for Training and Testing Robots and Autonomous Vehicles. <i>ASME Journal of Autonomous Vehicles and Systems</i> , 2021, 1, . | 0.6 | 6 |
| 36 | Analysis of a Splitting Approach for the Parallel Solution of Linear Systems on GPU Cards. <i>SIAM Journal of Scientific Computing</i> , 2017, 39, C215-C237. | 1.3 | 5 |

| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 37 | Autonomous Vehicles in the Cyberspace: Accelerating Testing via Computer Simulation. , 0, , . | | 4 |
| 38 | A Lagrangianâ€“Lagrangian Framework for the Simulation of Rigid and Deformable Bodies in Fluid. Computational Methods in Applied Sciences (Springer), 2014, , 33-52. | 0.1 | 4 |
| 39 | Chrono::Vehicle: template-based ground vehicle modelling and simulation. International Journal of Vehicle Performance, 2019, 5, 18. | 0.2 | 4 |
| 40 | Optimal Control for Halo Orbit Missions. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2000, 33, 1-6. | 0.4 | 3 |
| 41 | A parallel computational model for sensitivity analysis in optimization for robustness. Optimization Methods and Software, 2009, 24, 105-121. | 1.6 | 3 |
| 42 | Multibody Dynamics Versus Fluid Dynamics: Two Perspectives on the Dynamics of Granular Flows. Journal of Computational and Nonlinear Dynamics, 2020, 15, . | 0.7 | 3 |
| 43 | A Partitioned Lagrangian-Lagrangian Approach for Fluid-Solid Interaction Problems. , 2017, , . | | 2 |
| 44 | Enabling Artificial Intelligence Studies in Off-Road Mobility Through Physics-Based Simulation of Multiagent Scenarios. Journal of Computational and Nonlinear Dynamics, 2022, 17, . | 0.7 | 2 |
| 45 | End-to-end learning for off-road terrain navigation using the Chrono open-source simulation platform. Multibody System Dynamics, 2022, 54, 399-414. | 1.7 | 2 |
| 46 | Variable Fidelity Differential-Algebraic Equation Model Correlation. Mechanics Based Design of Structures and Machines, 1997, 25, 61-85. | 0.6 | 1 |
| 47 | On Simulating Sloshing in Vehicle Dynamics. , 2018, , . | | 1 |
| 48 | SynChrono: An open-source framework for physics-based simulation of collaborating robots. , 2018, , . | | 1 |
| 49 | An Overview of a Connected Autonomous Vehicle Emulator (CAVE). , 2017, , . | | 1 |
| 50 | SynChrono: A Scalable, Physics-Based Simulation Platform For Testing Groups of Autonomous Vehicles and/or Robots. , 2020, , . | | 1 |
| 51 | An Investigation on New Numerical Methods for Molecular Dynamics Simulation. , 2007, , 1467. | | 0 |
| 52 | A Connected Autonomous Vehicle Emulator (CAVE) for Testing Multi-agent, Conventionalâ€“Autonomous Mixed Vehicle Traffic Scenarios. , 2021, , 339-358. | | 0 |
| 53 | A Geographically Distributed Simulation Framework for the Analysis of Mixed Traffic Scenarios Involving Conventional and Autonomous Vehicles. , 0, , . | | 0 |