Henk Nijmeijer

List of Publications by Year
in descending order

328 papers	13,732 citations	47006 47 h-index	39675 94 g-index
336 all docs	336 docs citations	336 times ranked	6876 citing authors

#	Article	IF	Citations
1	Control-Oriented Models for Hyperelastic Soft Robots Through Differential Geometry of Curves. Soft Robotics, 2023, 10, 129-148.	8.0	11
2	Reset PID Design for Motion Systems With Stribeck Friction. IEEE Transactions on Control Systems Technology, 2022, 30, 294-310.	5.2	8
3	Rule-based control of a semi-active suspension system for road holding using limited sensor information: design and experiments. Vehicle System Dynamics, 2022, 60, 4226-4244.	3.7	5
4	A control strategy for merging a single vehicle into a platoon at highway on-ramps. Transportation Research Part C: Emerging Technologies, 2022, 136, 103511.	7.6	22
5	Robust CACC in the Presence of Uncertain Delays. IEEE Transactions on Vehicular Technology, 2022, 71, 3507-3518.	6.3	13
6	Practical Challenges in Hybrid Communication Ecosystems Based on ITS-G5 and LTE for CACC and GLOSA. Frontiers in Future Transportation, 2022, 3, .	1.8	2
7	Stability and performance analysis of hybrid integratorâ€"gain systems: A linear matrix inequality approach. Nonlinear Analysis: Hybrid Systems, 2022, 45, 101192.	3.5	2
8	Fast fluid heating by adaptive flow reorientation. International Journal of Thermal Sciences, 2022, 180, 107720.	4.9	1
9	Optimal thermal actuation for mirror temperature control. Computer Methods in Applied Mechanics and Engineering, 2022, 398, 115212.	6.6	1
10	Driver Intervention Detection via Real-Time Transfer Function Estimation. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 772-781.	8.0	5
11	Optimal Thermal Actuation for Mitigation of Heat-Induced Wafer Deformation. IEEE Transactions on Control Systems Technology, 2021, 29, 514-529.	5.2	3
12	Detecting coexisting oscillatory patterns in delay coupled Lurâ€™e systems. Chaos, 2021, 31, 033114.	2.5	0
13	State Estimation for Cooperative Lateral Vehicle Following Using Vehicle-to-Vehicle Communication. Electronics (Switzerland), 2021, 10, 651.	3.1	10
14	The method of images in thermoelasticity with an application to wafer heating. Journal of Thermal Stresses, 2021, 44, 970-1010.	2.0	1
15	Cooperative Driving of Automated Vehicles Using B-Splines for Trajectory Planning. IEEE Transactions on Intelligent Vehicles, 2021, 6, 594-604.	12.7	41
16	Projection-based integrators for improved motion control: Formalization, well-posedness and stability of hybrid integrator-gain systems. Automatica, 2021, 133, 109830.	5.0	13
17	Energy-based Control for Soft Manipulators using Cosserat-beam Models. , 2021, , .		2
18	Energy-based Control for Soft Manipulators using Cosserat-beam Models. , 2021, , .		2

#	Article	IF	Citations
19	Lyapunov-based temperature regulation by flow reorientation. , 2021, , .		0
20	Practical Challenges in CACC Communication: ITS G5, LTE Uu, and LTE Sidelink PC5. , 2021, , .		2
21	Frequency-domain Conditions for Global Synchronization of Nonlinear Systems Driven by a Nonperiodic External Signalâ€"Tribute to Gennady Leonov. Lobachevskii Journal of Mathematics, 2021, 42, 3344-3351.	0.9	1
22	Combined Longitudinal and Lateral Control of Car-Like Vehicle Platooning With Extended Look-Ahead. IEEE Transactions on Control Systems Technology, 2020, 28, 790-803.	5.2	40
23	Reference Spreading: Tracking Performance for Impact Trajectories of a 1DoF Setup. IEEE Transactions on Control Systems Technology, 2020, 28, 1124-1131.	5.2	7
24	Sensor and Actuator Placement for Proportional Feedback Control in Advection-Diffusion Equations. , 2020, 4, 193-198.		5
25	The Effect of Controller Design on Delayed Bilateral Teleoperation Performance: An Experimental Comparison. IEEE Transactions on Control Systems Technology, 2020, 28, 1727-1740.	5.2	2
26	Switching from autopilot to the driver: A transient performance analysis. Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 2020, 234, 1346-1360.	1.9	6
27	Compensation of Communication Delays in a Cooperative ACC System. IEEE Transactions on Vehicular Technology, 2020, 69, 1177-1189.	6.3	64
28	Hybrid Systems With State-Triggered Jumps: Sensitivity-Based Stability Analysis With Application to Trajectory Tracking. IEEE Transactions on Automatic Control, 2020, 65, 4568-4583.	5.7	9
29	Experimental Demonstration of a Nonlinear PID-Based Control Design Using Multiple Hybrid Integrator-Gain Elements. , 2020, , .		2
30	To stick or to slip: A reset PID control perspective on positioning systems with friction. Annual Reviews in Control, 2020, 49, 37-63.	7.9	17
31	A Computational Design Framework for Pressure-driven Soft Robots through Nonlinear Topology Optimization. , 2020, , .		21
32	Hybrid Integrator-Gain Systems: A Remedy for Overshoot Limitations in Linear Control?. , 2020, 4, 1042-1047.		24
33	Extended Look-Ahead Tracking Controller With Orientation-Error Observer for Vehicle Platooning. IEEE Transactions on Intelligent Transportation Systems, 2020, 21, 4808-4821.	8.0	18
34	Robust partial synchronization of delay-coupled networks. Chaos, 2020, 30, 013126.	2.5	6
35	Cooperative Adaptive Cruise Control of Heterogeneous Vehicle Platoons. IFAC-PapersOnLine, 2020, 53, 15217-15222.	0.9	16
36	Pattern Analysis in Networks of Delayed Coupled Nonlinear Systems. , 2020, , .		0

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37	Gap Opening Controller Design to Accommodate Merges in Cooperative Autonomous Platoons. IFAC-PapersOnLine, 2020, 53, 15294-15299.	0.9	5
38	Dynamic modeling of hyper-elastic soft robots using spatial curves. IFAC-PapersOnLine, 2020, 53, 9238-9243.	0.9	8
39	Network Synchronization of Linear Non-Minimum Phase Oscillators: A Motivating Example. , 2020, , .		0
40	Mitigation of Torsional Vibrations in Drilling Systems: A Robust Control Approach. IEEE Transactions on Control Systems Technology, 2019, 27, 249-265.	5.2	36
41	Reset integral control for improved settling of PID-based motion systems with friction. Automatica, 2019, 107, 483-492.	5.0	29
42	A Stochastic Model Predictive Control Approach for Driver-Aided Intersection Crossing With Uncertain Driver Time Delay. , 2019, , .		2
43	Automated Lane Changing With a Controlled Steering-Wheel Feedback Torque for Low Lateral Acceleration Purposes. IEEE Transactions on Intelligent Vehicles, 2019, 4, 578-587.	12.7	3
44	Enforcing synchronization in oscillators with Huygens' coupling via feed-forward control. Nonlinear Dynamics, 2019, 98, 3009-3023.	5.2	3
45	Data-Rate Constrained Observers of Nonlinear Systems. Entropy, 2019, 21, 282.	2.2	7
46	Robust Stability and Nonlinear Loop-Shaping Design for Hybrid Integrator-Gain-Based Control Systems. , 2019, , .		8
47	Optimal actuator shape design with input and state constraints for a wafer heating application. , 2019, , .		0
48	Sensitivity analysis for trajectories of nonsmooth mechanical systems with simultaneous impacts: a hybrid systems perspective. , 2019, , .		5
49	Linear Parameter-Varying Control of Nonlinear Systems based on Incremental Stability. IFAC-PapersOnLine, 2019, 52, 38-43.	0.9	7
50	Modeling of Energy Losses During Cornering for Electric City Buses. , 2019, , .		3
51	Hybrid model formulation and stability analysis of a PID-controlled motion system with Coulomb friction. IFAC-PapersOnLine, 2019, 52, 84-89.	0.9	1
52	Almost global decentralised formation tracking for multiple distinct UAVs. IFAC-PapersOnLine, 2019, 52, 186-191.	0.9	1
53	Dynamic coupling enhances network synchronization. IFAC-PapersOnLine, 2019, 52, 610-615.	0.9	7
54	Pattern Analysis in Networks of Diffusively Coupled Lur'e Systems. International Journal of Bifurcation and Chaos in Applied Sciences and Engineering, 2019, 29, 1950200.	1.7	2

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55	Smith Predictor Compensating for Vehicle Actuator Delays in Cooperative ACC Systems. IEEE Transactions on Vehicular Technology, 2019, 68, 1106-1115.	6.3	50
56	Implementation and validation of a three degrees of freedom steering-system model in a full vehicle model. Vehicle System Dynamics, 2019, 57, 86-107.	3.7	6
57	Semi-analytic approximation of the temperature field resulting from moving heat loads. International Journal of Heat and Mass Transfer, 2018, 122, 128-137.	4.8	20
58	Direct Force-Reflecting Two-Layer Approach for Passive Bilateral Teleoperation With Time Delays. IEEE Transactions on Robotics, 2018, 34, 194-206.	10.3	37
59	Motion Signals With Velocity Jumps: Velocity Estimation Employing Only Quantized Position Data. IEEE Robotics and Automation Letters, 2018, 3, 1498-1505.	5.1	5
60	Consensus Control for Vehicular Platooning With Velocity Constraints. IEEE Transactions on Control Systems Technology, 2018, 26, 1592-1605.	5.2	75
61	Battery electric vehicle energy consumption prediction for a trip based on route information. Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 2018, 232, 1528-1542.	1.9	52
62	Synchronization of â€œlight-sensitiveâ€•Hindmarshâ€"Rose neurons. Communications in Nonlinear Science and Numerical Simulation, 2018, 57, 322-330.	3.3	7
63	Controller Design for Cooperative Driving with Guaranteed Safe Behavior. , 2018, , .		11
64	A Data Rate Constrained Observer for Discrete Nonlinear Systems. , 2018, , .		1
65	Distributed Scenario Model Predictive Control for Driver Aided Intersection Crossing. , 2018, , .		7
66	Cross-Domain Modeling and Optimization of High-Speed Visual Servo Systems. , 2018, , .		1
67	Pattern Prediction in Networks of Diffusively Coupled Nonlinear Systems. IFAC-PapersOnLine, 2018, 51, 62-67.	0.9	2
68	A Lyapunov approach to stability analysis of partial synchronization in delay-coupled networks. IFAC-PapersOnLine, 2018, 51, 198-204.	0.9	1
69	Iterative pole-zero finite element model updating using generic parameters. Mechatronics, 2018, 55, 180-193.	3.3	3
70	Enhancing master-slave synchronization: The effect of using a dynamic coupling. Physical Review E, 2018, 98, 012208.	2.1	23
71	Experimental Validation of Torsional Controllers for Drilling Systems. , 2018, , 291-334.		0
72	Cooperative Intersection Control Based on Virtual Platooning. IEEE Transactions on Intelligent Transportation Systems, 2018, 19, 1727-1740.	8.0	90

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73	Hybrid PID control for transient performance improvement of motion systems with friction. , 2018, , .		2
74	Nonlinear output–feedback control of torsional vibrations in drilling systems. International Journal of Robust and Nonlinear Control, 2017, 27, 3659-3684.	3.7	27
75	On Centroidal Dynamics and Integrability of Average Angular Velocity. IEEE Robotics and Automation Letters, 2017, 2, 943-950.	5.1	17
76	Synchronization Control for a Swarm of Unicycle Robots: Analysis of Different Controller Topologies. Asian Journal of Control, 2017, 19, 1822-1833.	3.0	18
77	Adaptive Training of Neural Networks for Control of Autonomous Mobile Robots. Lecture Notes in Control and Information Sciences, 2017, , 387-405.	1.0	2
78	Experimental Validation of Robust Chatter Control for High-Speed Milling Processes. Advances in Delays and Dynamics, 2017, , 315-331.	0.4	4
79	Large amplitude dynamic behavior of thrust air bearings: Modeling and experiments. Tribology International, 2017, 109, 460-466.	5.9	6
80	A Spatial Approach to Control of Platooning Vehicles: Separating Path-Following from Tracking. IFAC-PapersOnLine, 2017, 50, 15000-15005.	0.9	5
81	Hybrid integrator design for enhanced tracking in motion control. , 2017, , .		24
82	Experimentally Validated Model Predictive Controller for a Hexacopter * *The authors gratefully acknowledge the partial sponsorship by DSTG, Australia.. IFAC-PapersOnLine, 2017, 50, 4076-4081.	0.9	15
83	Multi-objective platoon maneuvering using artificial potential fields. IFAC-PapersOnLine, 2017, 50, 15006-15011.	0.9	18
84	Vehicle State Estimation Using a State Dependent Riccati Equation. IFAC-PapersOnLine, 2017, 50, 3388-3393.	0.9	6
85	Set-point Control of Motion Systems with Uncertain Set-valued Stribeck Friction * *This research is supported by the Dutch Technology Foundation (STW, project 13896). IFAC-PapersOnLine, 2017, 50, 2965-2970.	0.9	4
86	Active Trailer Steering Control for High-Capacity Vehicle Combinations. IEEE Transactions on Intelligent Vehicles, 2017, 2, 251-265.	12.7	26
87	Almost global tracking control of a quadrotor UAV on SE(3). , 2017, , .		10
88	Consensus Control for a Multiagent System with Time Delays. Mathematical Problems in Engineering, 2017, 2017, 1-11.	1.1	6
89	Control of humanoid robot motions with impacts: Numerical experiments with reference spreading control. , 2017, , .		17
90	Padé Approximation of Delays in Cooperative ACC Based on String Stability Requirements. IEEE Transactions on Intelligent Vehicles, 2016, 1, 277-286.	12.7	47

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91	Huygens' inspired multi-pendulum setups: Experiments and stability analysis. Chaos, 2016, 26, 116304.	2.5	7
92	The PoincarÃ© method: A powerful tool for analyzing synchronization of coupled oscillators. Indagationes Mathematicae, 2016, 27, 1127-1146.	0.4	8
93	Robust Network Synchronization of Time-Delayed Coupled Systems. IFAC-PapersOnLine, 2016, 49, 74-79.	0.9	3
94	Synchronization of coupled Hindmarsh-Rose neurons: Effects of an exogenous parameter**Financially supported by Mexican National Council for Science and Technology (CONACYT).. IFAC-PapersOnLine, 2016, 49, 84-89.	0.9	5
95	Consensus-based bi-directional CACC for vehicular platooning. , 2016, , .		19
96	Hybrid Trajectory Tracking for a Hopping Robotic Leg. IFAC-PapersOnLine, 2016, 49, 107-112.	0.9	6
97	Second-order reset elements for stage control design. , 2016, , .		26
98	Training a Network of Electronic Neurons for Control of a Mobile Robot. International Journal of Bifurcation and Chaos in Applied Sciences and Engineering, 2016, 26, 1650196.	1.7	6
99	Synchronization and Partial Synchronization Experiments with Networks of Time-Delay Coupled Hindmarshâ€"Rose Neurons. International Journal of Bifurcation and Chaos in Applied Sciences and Engineering, 2016, 26, 1650111.	1.7	10
100	Coupling-modulated multi-stability and coherent dynamics in directed networks of heterogeneous nonlinear oscillators with modular topology. IFAC-PapersOnLine, 2016, 49, 62-67.	0.9	7
101	The sympathy of two pendulum clocks: beyond Huygensâ€™ observations. Scientific Reports, 2016, 6, 23580.	3.3	64
102	Combined lateral and longitudinal CACC for a unicycle-type platoon. , 2016, , .		17
103	A robust control analysis for a steer-by-wire vehicle with uncertainty on the tyre forces. Vehicle System Dynamics, 2016, 54, 1247-1268.	3.7	14
104	Merging Strategy for Vehicles by Applying Cooperative Tracking Control. IEEE Transactions on Intelligent Transportation Systems, 2016, 17, 3423-3433.	8.0	23
105	Modelling and simulation of a compliant tilting pad air bearing. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2016, 230, 69-87.	2.1	4
106	Trailer Steering Control of a Tractorâ€"Trailer Robot. IEEE Transactions on Control Systems Technology, 2016, 24, 1240-1252.	5.2	59
107	Rule-based control of a semi-active suspension for minimal sprung mass acceleration: design and measurement. Vehicle System Dynamics, 2016, 54, 281-300.	3.7	11
108	Split-path nonlinear integral control for transient performance improvement. Automatica, 2016, 66, 262-270.	5.0	15

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109	Active trailer steering for robotic tractor-trailer combinations. , 2015, , .		9
110	Trajectory tracking of mechanical systems with unilateral constraints: Experimental results of a recently introduced hybrid PD feedback controller. , 2015, , .		9
111	Predictor-based consensus control of a multi-agent system with time-delays. , 2015, , .		5
112	Directed cycles and multi-stability of coherent dynamics in systems of coupled nonlinear oscillators. IFAC-PapersOnLine, 2015, 48, 19-24.	0.9	2
113	Synchronization in Cartesian-Product Networks of Time-Delay Coupled Systems. IFAC-PapersOnLine, 2015, 48, 245-250.	0.9	1
114	Graceful Degradation of Cooperative Adaptive Cruise Control. IEEE Transactions on Intelligent Transportation Systems, 2015, 16, 488-497.	8.0	204
115	On optimal trajectory tracking for mechanical systems with unilateral constraints. , 2015, , .		16
116	Automation of a T-intersection Using Virtual Platoons of Cooperative Autonomous Vehicles. , 2015, , .		27
117	A two-layer architecture for force-reflecting bilateral teleoperation with time delays. , 2015, , .		2
118	Energy analysis of the Von Schlippe tyre model with application to shimmy. Vehicle System Dynamics, 2015, 53, 1795-1810.	3.7	12
119	Robust output-feedback control to eliminate stick-slip oscillations in drill-string systems. IFAC-PapersOnLine, 2015, 48, 266-271.	0.9	19
120	The effect of damping on the perception of hardness. , 2015, , .		13
121	Network synchronization of time-delayed coupled nonlinear systems using predictor-based diffusive dynamic couplings. Chaos, 2015, 25, 023108.	2.5	10
122	Fixed€structure robust controller design for chatter mitigation in high€speed milling. International Journal of Robust and Nonlinear Control, 2015, 25, 3495-3514.	3.7	4
123	Synthesis of Variable Gain Integral Controllers for Linear Motion Systems. IEEE Transactions on Control Systems Technology, 2015, 23, 139-149.	5.2	31
124	Network synchronization using invariant-manifold-based diffusive dynamic couplings with time-delay. Automatica, 2015, 57, 34-44.	5.0	23
125	Switched position-force tracking control of a manipulator interacting with a stiff environment. , 2015, , .		7
126	Pyragas-type feedback control for chatter mitigation in high-speed milling. IFAC-PapersOnLine, 2015, 48, 334-339.	0.9	8

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127	Extremum-Seeking Control for the Adaptive Design of Variable Gain Controllers. IEEE Transactions on Control Systems Technology, 2015, 23, 1041-1051.	5.2	11
128	Network Topology and Synchronization of Systems with Linear Time-Delayed Coupling. Lecture Notes in Control and Information Sciences, 2015, , 321-341.	1.0	0
129	Application of nonlinear tyre models to analyse shimmy. Vehicle System Dynamics, 2014, 52, 387-404.	3.7	32
130	Observer-based output-feedback control to eliminate torsional drill-string vibrations. , 2014, , .		8
131	Direct Motion Planning for Vision-Based Control. IEEE Transactions on Automation Science and Engineering, 2014, 11, 1282-1288.	5.2	12
132	Sensitivity analysis of hybrid systems with state jumps with application to trajectory tracking. , 2014, , .		26
133	Control of a semi-active suspension system for comfort by means of a rule-based controller. , 2014, , .		0
134	A dither-free extremum-seeking control approach using 1st-order least-squares fits for gradient estimation. , 2014, , .		22
135	Controller Synthesis for String Stability of Vehicle Platoons. IEEE Transactions on Intelligent Transportation Systems, 2014, 15, 854-865.	8.0	350
136	Cooperative Adaptive Cruise Control: Network-Aware Analysis of String Stability. IEEE Transactions on Intelligent Transportation Systems, 2014, 15, 1527-1537.	8.0	327
137	Lp String Stability of Cascaded Systems: Application to Vehicle Platooning. IEEE Transactions on Control Systems Technology, 2014, 22, 786-793.	5.2	474
138	Robust disturbance estimation for human-robotic comanipulation. International Journal of Robust and Nonlinear Control, 2014, 24, 1772-1796.	3.7	4
139	Experimental Validation of Object Positioning Via Stick–Slip Vibrations. IEEE/ASME Transactions on Mechatronics, 2014, 19, 1092-1101.	5.8	8
140	Predictor-Based Remote Tracking Control of a Mobile Robot. IEEE Transactions on Control Systems Technology, 2014, 22, 2087-2102.	5.2	25
141	Transient performance improvement of linear systems using a split-path nonlinear integrator. , 2014, , .		7
142	Further results on Lyapunov-like conditions of forward invariance and boundedness for a class of unstable systems. , 2014, , .		1
143	Networks of diffusively time-delay coupled systems: Conditions for synchronization and its relation to the network topology. Physica D: Nonlinear Phenomena, 2014, 277, 22-39.	2.8	21
144	Global Exponential Stabilization of a Two-Dimensional Pool-Boiling Model. IEEE Transactions on Automatic Control, 2014, 59, 205-210.	5.7	3

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145	Filling the gap between low frequency measurements with their estimates. , 2014, , .		2
146	Effect of hinge friction on the steady-state response of base-excited shallow arches. JVC/Journal of Vibration and Control, 2014, 20, 1877-1894.	2.6	0
147	Modal control of unstable boiling states in three-dimensional nonlinear pool-boiling. , 2014, , .		0
148	Model Reduction for Nonlinear Systems by Incremental Balanced Truncation. IEEE Transactions on Automatic Control, 2014, 59, 2739-2753.	5.7	48
149	Synchronization of Identical Linear Systems and Diffusive Time-Delayed Couplings. IEEE Transactions on Circuits and Systems I: Regular Papers, 2014, 61, 1801-1814.	5.4	14
150	Further understanding of Huygens' coupled clocks: The effect of stiffness. Physica D: Nonlinear Phenomena, 2014, 270, 11-19.	2.8	21
151	Output-based modal control of three-dimensional pool-boiling systems. International Journal of Thermal Sciences, 2014, 82, 34-46.	4.9	4
152	Battery thermal management by boiling heat-transfer. Energy Conversion and Management, 2014, 79, 9-17.	9.2	171
153	Partial Network Synchronization Using Diffusive Dynamic Couplings. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 4675-4680.	0.4	2
154	Adaptive Observers for Nonlinearly Parameterized Systems Subjected to Parametric Constraints. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 10869-10874.	0.4	2
155	Finite Element Model Reduction and Model Updating of structures for Control. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 4517-4522.	0.4	10
156	Controlled synchronization: a Huygens' inspired approach. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 3098-3103.	0.4	2
157	Adaptive observers and parameter estimation for a class of systems nonlinear in the parameters. Automatica, 2013, 49, 2409-2423.	5.0	79
158	Synchronization of weakly nonlinear oscillators with Huygens' coupling. Chaos, 2013, 23, 033118.	2.5	25
159	Introduction to the special issue on 'Performance of nonlinear control systems'. International Journal of Robust and Nonlinear Control, 2013, 23, 1063-1064.	3.7	0
160	Model reduction for nonlinear systems with incremental gain or passivity properties. Automatica, 2013, 49, 861-872.	5.0	32
161	Time Delay Compensation in Bilateral Teleoperations Using IMPACT. IEEE Transactions on Control Systems Technology, 2013, 21, 704-715.	5.2	19
162	A comparison of model reduction techniques from structural dynamics, numerical mathematics and systems and control. Journal of Sound and Vibration, 2013, 332, 4403-4422.	3.9	208

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163	Accuracy Assessment of Thermoacoustic Instability Models Using Binary Classification. International Journal of Spray and Combustion Dynamics, 2013, 5, 201-224.	1.0	8
164	Model-based piecewise affine variable-gain controller synthesis. , 2013, , .		3
165	Qualitative validation of humanoid robot models through balance recovery side-stepping experiments. , 2013, , .		2
166	Learning in the synthesis of data-driven variable-gain controllers. , 2013, , .		6
167	Generalized incremental balanced truncation for nonlinear systems. , 2013, , .		1
168	Graceful degradation of CACC performance subject to unreliable wireless communication. , 2013, , .		46
169	Vehicle state estimator based regenerative braking implementation on an electric vehicle to improve lateral vehicle stability. , 2013, , .		2
170	Evaluating the TU/e Lupo EL BEV performance. , 2013, , .		2
171	NETWORK SYNCHRONIZATION BY DYNAMIC DIFFUSIVE COUPLING. International Journal of Bifurcation and Chaos in Applied Sciences and Engineering, 2013, 23, 1350076.	1.7	5
172	Foot Placement Indicator for Balance of Planar Bipeds with Point Feet. International Journal of Advanced Robotic Systems, 2013, 10, 250.	2.1	4
173	Partial synchronization in diffusively time-delay coupled oscillator networks. Chaos, 2012, 22, 043144.	2.5	32
174	String stability of interconnected vehicles under communication constraints. , 2012, , .		68
175	Analysis of the lateral dynamic behaviour of articulated commercial vehicles. Vehicle System Dynamics, 2012, 50, 169-189.	3.7	33
176	Feed forward visual servoing for object exploration. , 2012, , .		2
177	Controlled Synchronization in Networks of Nonlinear Systems via Dynamic Coupling* *This work was partially supported by the Mexican Council for Science and Technology (CONACYT).. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 261-266.	0.4	2
178	An experimental study on synchronization of nonlinear oscillators with Huygens' coupling. Nonlinear Theory and Its Applications IEICE, 2012, 3, 128-142.	0.6	8
179	Robust Active Chatter Control in the High-Speed Milling Process. IEEE Transactions on Control Systems Technology, 2012, 20, 901-917.	5.2	101
180	Feedback stabilisation of a two-dimensional pool-boiling system by modal control. International Journal of Thermal Sciences, 2012, 61, 38-49.	4.9	5

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181	Steady-state performance optimization for variable-gain motion control using extremum seeking. , 2012, , .		3
182	Bifurcations of equilibrium sets in mechanical systems with dry friction. Physica D: Nonlinear Phenomena, 2012, 241, 1882-1894.	2.8	14
183	Collective Almost Synchronisation in Complex Networks. PLoS ONE, 2012, 7, e48118.	2.5	12
184	Steady-state dynamics of a 3D tensegrity structure: Simulations and experiments. International Journal of Solids and Structures, 2012, 49, 973-988.	2.7	11
185	Cooperative adaptive cruise control: Tradeoffs between control and network specifications. , 2011, , .		31
186	Structural stability of equilibrium sets for a class of discontinuous vector fields. , 2011, , .		0
187	Output Feedback Tracking of Ships. IEEE Transactions on Control Systems Technology, 2011, 19, 442-448.	5.2	91
188	Model-based analysis and control of axial and torsional stick-slip oscillations in drilling systems. , 2011, , .		9
189	On the achievable performance using variable geometry active secondary suspension systems in commercial vehicles. Vehicle System Dynamics, 2011, 49, 1553-1573.	3.7	7
190	Vibrational self-alignment of a rigid object exploiting friction. Nonlinear Dynamics, 2011, 65, 109-129.	5.2	3
191	Editorial: Special issue on stability of non-linear dynamic structures and systems. Nonlinear Dynamics, 2011, 66, 247-250.	5.2	4
192	Nonlinear resonances in an axially excited beam carrying aÂtop mass: simulations and experiments. Nonlinear Dynamics, 2011, 66, 285-302.	5.2	11
193	Synchronization and activation in a model of a network of <mml:math altimg="si13.gif" display="inline" overflow="scroll" xmlns:xocs="http://www.elsevier.com/xml/xocs/dtd" xmlns:xs="http://www.w3.org/2001/XMLSchema" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xmlns="http://www.elsevier.com/xml/ja/dtd" xmlns:ja="http://www.elsevier.com/xml/ja/dtd" xmlns:mml="http://www.w3.org/1998/Math/MathML" xmlns:tb="http://www.elsevier.com/xml/common/table/dtd" xmlns:sb="http://www.elsevier.com/xml/co	5.0	8
194	Low-order control design for chatter suppression in high-speed milling. , 2011, , .		2
195	Formation control of unicycle robots using the virtual structure approach. , 2011, , .		6
196	Model reduction of nonlinear systems with bounded incremental ™<inf>2</inf> gain. , 2011, , .		6
197	Design and experimental evaluation of cooperative adaptive cruise control. , 2011, , .		395
198	A virtual structure approach to formation control of unicycle mobile robots using mutual coupling. International Journal of Control, 2011, 84, 1886-1902.	1.9	89

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