## You Li

## List of Publications by Year in descending order

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201674 182427 2,752 73 27 51 citations h-index g-index papers 74 74 74 2584 citing authors all docs docs citations times ranked

#	Article	IF	Citations
1	Smartphone-Based Indoor Localization with Bluetooth Low Energy Beacons. Sensors, 2016, 16, 596.	3.8	334
2	An Improved RANSAC for 3D Point Cloud Plane Segmentation Based on Normal Distribution Transformation Cells. Remote Sensing, 2017, 9, 433.	4.0	167
3	Evaluation of Two WiFi Positioning Systems Based on Autonomous Crowdsourcing of Handheld Devices for Indoor Navigation. IEEE Transactions on Mobile Computing, 2016, 15, 1982-1995.	5 <b>.</b> 8	152
4	An improved inertial/wifi/magnetic fusion structure for indoor navigation. Information Fusion, 2017, 34, 101-119.	19.1	111
5	PDR/INS/WiFi Integration Based on Handheld Devices for Indoor Pedestrian Navigation. Micromachines, 2015, 6, 793-812.	2.9	98
6	Indoor navigation: state of the art and future trends. Satellite Navigation, 2021, 2, .	8.6	96
7	Toward Location-Enabled IoT (LE-IoT): IoT Positioning Techniques, Error Sources, and Error Mitigation. IEEE Internet of Things Journal, 2021, 8, 4035-4062.	8.7	91
8	Toward Robust Crowdsourcing-Based Localization: A Fingerprinting Accuracy Indicator Enhanced Wireless/Magnetic/Inertial Integration Approach. IEEE Internet of Things Journal, 2019, 6, 3585-3600.	8.7	87
9	A Hybrid WiFi/Magnetic Matching/PDR Approach for Indoor Navigation With Smartphone Sensors. IEEE Communications Letters, 2016, 20, 169-172.	4.1	86
10	Fast Thermal Calibration of Low-Grade Inertial Sensors and Inertial Measurement Units. Sensors, 2013, 13, 12192-12217.	3.8	83
11	Wireless Access Point Localization Using Nonlinear Least Squares and Multi-Level Quality Control. IEEE Wireless Communications Letters, 2015, 4, 693-696.	<b>5.</b> O	79
12	Autonomous Calibration of MEMS Gyros in Consumer Portable Devices. IEEE Sensors Journal, 2015, 15, 4062-4072.	4.7	76
13	Deep Reinforcement Learning (DRL): Another Perspective for Unsupervised Wireless Localization. IEEE Internet of Things Journal, 2020, 7, 6279-6287.	8.7	68
14	A dual growing method for the automatic extraction of individual trees from mobile laser scanning data. ISPRS Journal of Photogrammetry and Remote Sensing, 2016, 120, 37-52.	11.1	62
15	A Two-Filter Integration of MEMS Sensors and WiFi Fingerprinting for Indoor Positioning. IEEE Sensors Journal, 2016, 16, 5125-5126.	4.7	59
16	WiFi-Aided Magnetic Matching for Indoor Navigation with Consumer Portable Devices. Micromachines, 2015, 6, 747-764.	2.9	58
17	An <i>in situ</i> hand calibration method using a pseudo-observation scheme for low-end inertial measurement units. Measurement Science and Technology, 2012, 23, 105104.	2.6	57
18	A Pervasive Integration Platform of Low-Cost MEMS Sensors and Wireless Signals for Indoor Localization. IEEE Internet of Things Journal, 2018, 5, 4616-4631.	8.7	52

#	Article	IF	CITATIONS
19	Multi-Sensor Multi-Floor 3D Localization With Robust Floor Detection. IEEE Access, 2018, 6, 76689-76699.	4.2	50
20	Self-Contained Indoor Pedestrian Navigation Using Smartphone Sensors and Magnetic Features. IEEE Sensors Journal, 2016, 16, 7173-7182.	4.7	46
21	Consistent ST-EKF for Long Distance Land Vehicle Navigation Based on SINS/OD Integration. IEEE Transactions on Vehicular Technology, 2019, 68, 10525-10534.	6.3	44
22	A Localization Database Establishment Method Based on Crowdsourcing Inertial Sensor Data and Quality Assessment Criteria. IEEE Internet of Things Journal, 2018, 5, 4764-4777.	8.7	43
23	Navigation Engine Design for Automated Driving Using INS/GNSS/3D LiDAR-SLAM and Integrity Assessment. Remote Sensing, 2020, 12, 1564.	4.0	37
24	Railway irregularity measuring using Rauch–Tung–Striebel smoothed multi-sensors fusion system: quad-GNSS PPP, IMU, odometer, and track gauge. GPS Solutions, 2018, 22, 1.	4.3	34
25	Wireless Fingerprinting Uncertainty Prediction Based on Machine Learning. Sensors, 2019, 19, 324.	3.8	33
26	Study on Population Distribution Pattern at the County Level of China. Sustainability, 2018, 10, 3598.	3.2	31
27	Collaborative WiFi Fingerprinting Using Sensor-Based Navigation on Smartphones. Sensors, 2015, 15, 17534-17557.	3.8	28
28	A Novel Kalman Filter with State Constraint Approach for the Integration of Multiple Pedestrian Navigation Systems. Micromachines, 2015, 6, 926-952.	2.9	27
29	A method based on an adaptive radius cylinder model for detecting pole-like objects in mobile laser scanning data. Remote Sensing Letters, 2016, 7, 249-258.	1.4	25
30	IMU/Magnetometer/Barometer/Mass-Flow Sensor Integrated Indoor Quadrotor UAV Localization with Robust Velocity Updates. Remote Sensing, 2019, 11, 838.	4.0	25
31	A Profile-Matching Method for Wireless Positioning. IEEE Communications Letters, 2016, 20, 2514-2517.	4.1	23
32	Odometer, low-cost inertial sensors, and four-GNSS data to enhance PPP and attitude determination. GPS Solutions, 2018, 22, 1.	4.3	23
33	RSS-Based Visible Light Positioning Using Nonlinear Optimization. IEEE Internet of Things Journal, 2022, 9, 14137-14150.	8.7	22
34	A Density-Based Clustering Method for Urban Scene Mobile Laser Scanning Data Segmentation. Remote Sensing, 2017, 9, 331.	4.0	21
35	Thermal Calibration Procedure and Thermal Characterisation of Low-cost Inertial Measurement Units. Journal of Navigation, 2016, 69, 373-390.	1.7	20
36	Using inertial sensors of iPhone 4 for car navigation. , 2012, , .		19

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37	Evaluation on the impact of IMU grades on BDS + GPS PPP/INS tightly coupled integration. Advances in Space Research, 2017, 60, 1283-1299.	2.6	19
38	Inertial Sensing Meets Machine Learning: Opportunity or Challenge?. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 9995-10011.	8.0	19
39	Localization and Extraction of Road Poles in Urban Areas from Mobile Laser Scanning Data. Remote Sensing, 2019, 11, 401.	4.0	18
40	Modeling of multi-sensor tightly aided BDS triple-frequency precise point positioning and initial assessments. Information Fusion, 2020, 55, 184-198.	19.1	17
41	Cost-Effective Localization Using RSS From Single Wireless Access Point. IEEE Transactions on Instrumentation and Measurement, 2020, 69, 1860-1870.	4.7	17
42	Real-time indoor navigation using smartphone sensors. , 2015, , .		16
43	A Multi-Type Features Method for Leg Detection in 2-D Laser Range Data. IEEE Sensors Journal, 2018, 18, 1675-1684.	4.7	16
44	Simulation of the Separating Crowd Behavior in a T-Shaped Channel Based on the Social Force Model. IEEE Access, 2019, 7, 13668-13682.	4.2	16
45	Enhanced Gaussian Process-Based Localization Using a Low Power Wide Area Network. IEEE Communications Letters, 2019, 23, 164-167.	4.1	15
46	An Adaptive Low-Cost GNSS/MEMS-IMU Tightly-Coupled Integration System with Aiding Measurement in a GNSS Signal-Challenged Environment. Sensors, 2015, 15, 23953-23982.	3.8	14
47	Towards Location Enhanced IoT: Characterization of LoRa Signal For Wide Area Localization. , 2018, , .		14
48	Robust Kalman Filter Aided GEO/IGSO/GPS Raw-PPP/INS Tight Integration. Sensors, 2019, 19, 417.	3.8	14
49	A survey on indoor 3D modeling and applications via RGB-D devices. Frontiers of Information Technology and Electronic Engineering, 2021, 22, 815-826.	2.6	14
50	IVPR: An Instant Visual Place Recognition Approach Based on Structural Lines in Manhattan World. IEEE Transactions on Instrumentation and Measurement, 2020, 69, 4173-4187.	4.7	13
51	OdoNet: Untethered Speed Aiding for Vehicle Navigation Without Hardware Wheeled Odometer. IEEE Sensors Journal, 2022, 22, 12197-12208.	4.7	13
52	Research on Time-Correlated Errors Using Allan Variance in a Kalman Filter Applicable to Vector-Tracking-Based GNSS Software-Defined Receiver for Autonomous Ground Vehicle Navigation. Remote Sensing, 2019, 11, 1026.	4.0	12
53	Calibrating Multi-Channel RSS Observations for Localization Using Gaussian Process. IEEE Wireless Communications Letters, 2019, 8, 1116-1119.	5.0	12
54	The Impact of Vehicle Maneuvers on the Attitude Estimation of GNSS / INS for Mobile Mapping. Journal of Applied Geodesy, 2015, 9, .	1.1	11

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55	Distribution Characteristics of the Transportation Network in China at the County Level. IEEE Access, 2019, 7, 49251-49261.	4.2	11
56	Fast and Automatic Reconstruction of Semantically Rich 3D Indoor Maps from Low-quality RGB-D Sequences. Sensors, 2019, 19, 533.	3.8	11
57	Pole-Like Street Furniture Segmentation and Classification in Mobile LiDAR Data by Integrating Multiple Shape-Descriptor Constraints. Remote Sensing, 2019, 11, 2920.	4.0	11
58	Enhanced Wireless Localization Based on Orientation-Compensation Model and Differential Received Signal Strength. IEEE Sensors Journal, 2019, 19, 4201-4210.	4.7	10
59	Orientation-Aided Stochastic Magnetic Matching for Indoor Localization. IEEE Sensors Journal, 2020, 20, 1003-1010.	4.7	10
60	Using Inertial Sensors in Smartphones for Curriculum Experiments of Inertial Navigation Technology. Education Sciences, 2015, 5, 26-46.	2.6	9
61	FusionVLP: The Fusion of Photodiode and Camera for Visible Light Positioning. IEEE Transactions on Vehicular Technology, 2021, 70, 11796-11811.	6.3	8
62	A modularized real-time indoor navigation algorithm on smartphones. , 2015, , .		7
63	Recognition and Reconstruction of Zebra Crossings on Roads from Mobile Laser Scanning Data. ISPRS International Journal of Geo-Information, 2016, 5, 125.	2.9	7
64	The Integration of Photodiode and Camera for Visible Light Positioning by Using Fixed-Lag Ensemble Kalman Smoother. Remote Sensing, 2019, 11, 1387.	4.0	6
65	The Distribution Pattern of the Railway Network in China at the County Level. ISPRS International Journal of Geo-Information, 2019, 8, 336.	2.9	6
66	Real-time attitude tracking of mobile devices. , 2015, , .		5
67	An IMU Evaluation Method Using a Signal Grafting Scheme. Sensors, 2016, 16, 854.	3.8	5
68	Simulation Analysis for the Influences of Vehicle Maneuvers to the Attitude Estimations of GNSS/INS Navigation Systems. Lecture Notes in Electrical Engineering, 2012, , 679-694.	0.4	2
69	An automatic multi-level gyro calibration architecture for consumer portable devices. , 2014, , .		2
70	Near Relation-Based Indoor Positioning Method under Sparse Wi-Fi Fingerprints. ISPRS International Journal of Geo-Information, 2020, 9, 714.	2.9	2
71	Indoors Positioning Based on Spatial Relationships in Locality Description. IEEE Access, 2020, 8, 34794-34809.	4.2	2
72	An efficient method for evaluating the performance of integrated multiple pedestrian navigation systems. , 2015, , .		0

#	# ARTICLE	IF	CITATIONS
7:	Parametric/fingerprinting integrated angle and location estimation using R multiâ€antenna access point. Electronics Letters, 2019, 55, 563-565.	SS from single 1.0	О