Richard Romano

List of Publications by Year in descending order

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| # | Article | IF | CITATIONS |
|----|---|------|-----------|
| 1 | Control Task Substitution in Semiautomated Driving. Human Factors, 2012, 54, 747-761. | 3.5 | 254 |
| 2 | Surrogate in-vehicle information systems and driver behaviour: Effects of visual and cognitive load in simulated rural driving. Transportation Research Part F: Traffic Psychology and Behaviour, 2005, 8, 79-96. | 3.7 | 162 |
| 3 | Using the UTAUT2 model to explain public acceptance of conditionally automated (L3) cars: A questionnaire study among 9,118 car drivers from eight European countries. Transportation Research Part F: Traffic Psychology and Behaviour, 2020, 74, 280-297. | 3.7 | 106 |
| 4 | Coming back into the loop: Drivers' perceptual-motor performance in critical events after automated driving. Accident Analysis and Prevention, 2017, 108, 9-18. | 5.7 | 84 |
| 5 | Were they in the loop during automated driving? Links between visual attention and crash potential. Injury Prevention, 2017, 23, 281-286. | 2.4 | 60 |
| 6 | Engaging with Highly Automated Driving: To be or Not to be in the Loop?. , 2015, , . | | 56 |
| 7 | Engaging in NDRTs affects drivers' responses and glance patterns after silent automation failures. Transportation Research Part F: Traffic Psychology and Behaviour, 2019, 62, 870-882. | 3.7 | 48 |
| 8 | Risk-based autonomous vehicle motion control with considering human driver's behaviour. Transportation Research Part C: Emerging Technologies, 2019, 107, 1-14. | 7.6 | 47 |
| 9 | Sustained sensorimotor control as intermittent decisions about prediction errors: computational framework and application to ground vehicle steering. Biological Cybernetics, 2018, 112, 181-207. | 1.3 | 45 |
| 10 | The effect of varying levels of vehicle automation on drivers' lane changing behaviour. PLoS ONE, 2018, 13, e0192190. | 2.5 | 24 |
| 11 | ActEarly: a City Collaboratory approach to early promotion of good health and wellbeing. Wellcome Open Research, 2019, 4, 156. | 1.8 | 23 |
| 12 | Variable-Drift Diffusion Models of Pedestrian Road-Crossing Decisions. Computational Brain & Behavior, 2022, 5, 60-80. | 1.7 | 22 |
| 13 | The effect of motor control requirements on drivers' eye-gaze pattern during automated driving. Accident Analysis and Prevention, 2020, 148, 105788. | 5.7 | 15 |
| 14 | Human-Like Decision Making and Motion Control for Smooth and Natural Car Following. IEEE Transactions on Intelligent Vehicles, 2023, 8, 263-274. | 12.7 | 13 |
| 15 | Real-Time Multi-Body Vehicle Dynamics Using a Modular Modeling Methodology. , 0, , . | | 12 |
| 16 | Using Driver Control Models to Understand and Evaluate Behavioral Validity of Driving Simulators. IEEE Transactions on Human-Machine Systems, 2018, 48, 592-603. | 3.5 | 12 |
| 17 | Optimal Smooth Paths Based on Clothoids for Car-like Vehicles in the Presence of Obstacles. International Journal of Control, Automation and Systems, 2021, 19, 2163-2182. | 2.7 | 10 |
| 18 | Modelling visual-vestibular integration and behavioural adaptation in the driving simulator. Transportation Research Part F: Traffic Psychology and Behaviour, 2019, 66, 310-323. | 3.7 | 9 |

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|----|---|-----|-----------|
| 19 | Predicting takeover response to silent automated vehicle failures. PLoS ONE, 2020, 15, e0242825. | 2.5 | 8 |
| 20 | Realtime Driving Simulation Using A Modular Modeling Methodology. , 2000, , . | | 7 |
| 21 | Impact of lane keeping assist system camera misalignment on driver behavior. Journal of Intelligent Transportation Systems: Technology, Planning, and Operations, 2021, 25, 157-169. | 4.2 | 6 |
| 22 | Driver-centred Autonomous Vehicle Motion Control within A Blended Corridor. IFAC-PapersOnLine, 2019, 52, 212-217. | 0.9 | 5 |
| 23 | Takeover Performance and Workload under Varying Automation Levels, Time Budget and Road Curvature. , 2022, , . | | 4 |
| 24 | Validation of Real-Time Multi-Body Vehicle Dynamics Models for Use in Product Design and Acquisition. , 2004, , . | | 3 |
| 25 | The effect of inconsistent steering guidance during transitions from Highly Automated Driving. Accident Analysis and Prevention, 2022, 167, 106572. | 5.7 | 3 |
| 26 | Automated Methods for Converting a Non Real-time Cartesian Multi-body Vehicle Dynamics Model to a Real-time Recursive Model. , 0, , . | | 1 |
| 27 | Motion Base Simulation of a Hybrid-Electric HMMWV for Fuel Economy Measurement. SAE International Journal of Commercial Vehicles, 2008, 1, 41-53. | 0.4 | 1 |
| 28 | Doctor when can I drive? Braking response after knee arthroplasty: A systematic review & meta-analysis of brake reaction time. Knee, 2021, 30, 214-240. | 1.6 | 1 |
| 29 | Development of a Vehicle Model/Simulation Evaluation Tool. SAE International Journal of Commercial Vehicles, 0, 1, 89-99. | 0.4 | 0 |