Yannick S Krieger

List of Publications by Year in descending order

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| | 1684188 | 1720034 |
|----------------|--------------|--------------------------------|
| 114 | 5 | 7 |
| citations | h-index | g-index |
| | | |
| | | |
| | | |
| 17 | 17 | 127 |
| docs citations | times ranked | citing authors |
| | | |
| | citations 17 | 114 5 citations h-index 17 17 |

| # | Article | lF | CITATIONS |
|----|---|-----|-----------|
| 1 | PLAFOKON: a new concept for a patient-individual and intervention-specific flexible surgical platform. Surgical Endoscopy and Other Interventional Techniques, 2022, 36, 5303-5312. | 2.4 | 2 |
| 2 | Evaluation of improved bi-manual endoscopic resection using a customizable 3D-printed manipulator system designed for use with standard endoscopes: a feasibility study using a porcine ex-vivo model. Endoscopy International Open, 2021, 09, E881-E887. | 1.8 | 3 |
| 3 | Automated design of underactuated monolithic soft robotics structures with multiple predefined end poses., 2021,,. | | 1 |
| 4 | Evaluation of long-term stability of monolithic 3D-printed robotic manipulator structures for minimally invasive surgery. International Journal of Computer Assisted Radiology and Surgery, 2020, 15, 1693-1697. | 2.8 | 6 |
| 5 | Improved endoscopic resection of large flat lesions and early cancers using an external additional working channel (AWC): a case series. Endoscopy International Open, 2019, 07, E298-E301. | 1.8 | 17 |
| 6 | Compensation for Geometrical Deviations in Additive Manufacturing. Technologies, 2019, 7, 83. | 5.1 | 14 |
| 7 | Electronic Control Concept for Surgical Manipulators Generated Using an Automated Design Process., 2018,,. | | 2 |
| 8 | Multi-arm snake-like robot. , 2017, , . | | 19 |
| 9 | Distributed navigated control for active instruments in a real-time networked operating room. , 2017, , . | | O |
| 10 | Fatigue strength of laser sintered flexure hinge structures for soft robotic applications. , 2017, , . | | 16 |
| 11 | Development of a double arm endoscopic mini-manipulator system for transurethral resection of bladder tumors (TURBT). , 2017, , . | | 4 |
| 12 | A new concept for a Single Incision Laparoscopic Manipulator System integrating intraoperative Laparoscopic Ultrasound. , 2016, , . | | 2 |
| 13 | A new 3D-printed overtube system for endoscopic submucosal dissection: first results of a randomized study in a porcine model. Endoscopy, 2016, 48, 762-765. | 1.8 | 16 |
| 14 | Mechatronic device for the optimization of the DBS-electrode placement. , 2016, , . | | 2 |
| 15 | Design and manufacturing concept of a postoperative adjustable prosthesis for ossicular chain reconstructions. , $2016, , .$ | | O |
| 16 | Automated construction of gear racks, spur gears and helical gears using Matlab & amp; amp; STL files for rapid manufacturing., 2013 ,,. | | 5 |