Maarten Steinbuch

List of Publications by Year
in descending order

341 papers	7,730 citations	71102 41 h-index	74163 75 g-index
343 all docs	343 docs citations	343 times ranked	4870 citing authors

#	ARTICLE	IF	CITATIONS
1	Motion Control, Mechatronics Design, and Moore's Law. IEEJ Journal of Industry Applications, 2022, 11, 245-255.	1.1	8
2	Revisiting static charge schedules for electric vehicles as temporary solution to low-voltage grid congestion with recent charging and grid data. Sustainable Energy, Grids and Networks, 2022, 31, 100701.	3.9	5
3	A Concept for Accurate Edge-Coupled Multi-Fiber Photonic Interconnects. Journal of Lightwave Technology, 2019, 37, 1374-1380.	4.6	1
4	A representation method based on the probability of collision for safe robot navigation in domestic environments. Autonomous Robots, 2018, 42, 601-614.	4.8	3
5	A task analysis approach to quantify bottlenecks in task completion time of telemanipulated maintenance. Fusion Engineering and Design, 2018, 129, 300-308.	1.9	5
6	Resonant-Dynamics LTV Feedforward for Flexible Motion Systems. , 2018, , .		1
7	A comparative overview of frequency domain methods for nonlinear systems. Mechatronics, 2017, 42, 11-24.	3.3	24
8	Periodic Signal Tracking for Lightly Damped Systems. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2017, 139, .	1.6	1
9	Broadband damping of high-precision motion stages. Mechatronics, 2017, 41, 1-16.	3.3	7
10	A compliance feedforward scheme for a class of LTV motion systems. , 2017, , .		2
11	Iterative Learning Control and feedforward for LPV systems: Applied to a position-dependent motion system. , 2017, , .		12
12	Review of Optimization Strategies for System-Level Design in Hybrid Electric Vehicles. IEEE Transactions on Vehicular Technology, 2016, , 1-1.	6.3	143
13	Cloud based centralized task control for human domain multi-robot operations. Intelligent Service Robotics, 2016, 9, 63-77.	2.6	13
14	Model–based geometric calibration for medical x–ray systems. Medical Physics, 2015, 42, 6170-6181.	3.0	3
15	Identification of cyclic disturbances in positioning systems via compressive sensing. , 2015, , .		0
16	Second-Order Iterative Learning Control for Scaled Setpoints. IEEE Transactions on Control Systems Technology, 2015, 23, 805-812.	5.2	6
17	Control of a Waste Heat Recovery system with decoupled expander for improved diesel engine efficiency. , 2015, , .		6
18	Combining ILC and repetitive control to handle repeating, event-triggered disturbances in precision inkjet printing. , 2015, , .		3

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19	Effect of gear shift and engine start losses on energy management strategies for hybrid electric vehicles. International Journal of Powertrains, 2015, 4, 141.	0.3	6
20	Time-delay pre-filter design for vibration free tracking of periodic reference signals. , 2015, , .		1
21	Nanometre-accurate form measurement machine for E-ELT M1 segments. Precision Engineering, 2015, 40, 14-25.	3.4	7
22	Notch Filters for Port-Hamiltonian Systems. IEEE Transactions on Automatic Control, 2015, 60, 2440-2445.	5.7	2
23	Computation of transfer function data from frequency response data with application to data-based root-locus. Control Engineering Practice, 2015, 37, 20-31.	5.5	3
24	Iterative motion feedforward tuning: A data-driven approach based on instrumental variable identification. Control Engineering Practice, 2015, 37, 11-19.	5.5	79
25	From Optimal to Real-Time Control of a Mechanical Hybrid Powertrain. IEEE Transactions on Control Systems Technology, 2015, 23, 670-678.	5.2	8
26	Robust High Performance Bilateral Teleoperation Under Bounded Time-Varying Dynamics. IEEE Transactions on Control Systems Technology, 2015, 23, 206-218.	5.2	10
27	Linear viscoelastic fluid characterization of ultra-high-viscosity fluids for high-frequency damper design. Rheologica Acta, 2015, 54, 667-677.	2.4	7
28	Implementation of Dynamic Programming for Optimal Control Problems With Continuous States. IEEE Transactions on Control Systems Technology, 2015, 23, 1172-1179.	5.2	23
29	Application of a Time-Delay Pre-Filter Design for Periodic Signal Tracking of Lightly-Damped Multivariable Systemsâˆ—âˆ—The research leading to these results has received funding from the Dutch ministry of Economic afairs and is part of the joint Eindhoven University of Technology/Philips Healthcare IMXR Project.. IFAC-papersonline, 2015, 48, 135-140.	0.9	1
30	Non-diagonal <mml:math altimg="si0039.gif" overflow="scroll" xmlns:xocs="http://www.elsevier.com/xml/xocs/dtd" xmlns:xs="http://www.w3.org/2001/XMLSchema" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xmlns="http://www.elsevier.com/xml/ja/dtd" xmlns:ja="http://www.elsevier.com/xml/ja/dtd" xmlns:mml="http://www.w3.org/1998/Math/MathML" xmlns:tb="http://www.elsevier.com/xml/common/table/dtd" xmlns:sb="http://www.elsevier.com/xml/common/struct-bib/dtd" xmlns:ce="http://www.elsevier.com/x	5.5	3
31	Semi-task-dependent and uncertainty-driven world model maintenance. Autonomous Robots, 2015, 38, 1-15.	4.8	1
32	Model predictive control of a waste heat recovery system for automotive diesel engines. , 2014, , .		14
33	Modeling and Control of a Parallel Waste Heat Recovery System for Euro-VI Heavy-Duty Diesel Engines. Energies, 2014, 7, 6571-6592.	3.1	58
34	Semi-empirical power dissipation modelling of mechanical hybrid powertrain components. Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 2014, 228, 443-456.	1.9	3
35	Aspects in inferential Iterative Learning Control: A 2D systems analysis. , 2014, , .		2
36	Design of an E-ELT M1 segment measurement machine with nanometer accuracy. , 2014, , .		0

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37	Extremum seeking control with data-based disturbance feedforward. , 2014, , .		5
38	Accuracy aspects in motion feedforward tuning. , 2014, , .		17
39	Connecting System Identification and Robust Control for Next-Generation Motion Control of a Wafer Stage. IEEE Transactions on Control Systems Technology, 2014, 22, 102-118.	5.2	123
40	Using iterative learning control with basis functions to compensate medium deformation in a wide-format inkjet printer. Mechatronics, 2014, 24, 944-953.	3.3	59
41	On inferential Iterative Learning Control: With example to a printing system. , 2014, , .		8
42	Exploiting additional actuators and sensors for nano-positioning robust motion control. , 2014, , .		10
43	High performance teleoperation by bumpless transfer of robust controllers. , 2014, , .		2
44	Gear shift map design methodology for automotive transmissions. Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 2014, 228, 50-72.	1.9	25
45	Fast and smooth clutch engagement control for dual-clutch transmissions. Control Engineering Practice, 2014, 22, 57-68.	5.5	59
46	Optimal Control of a Mechanical Hybrid Powertrain With Cold-Start Conditions. IEEE Transactions on Vehicular Technology, 2014, 63, 1555-1566.	6.3	16
47	Solution for state constrained optimal control problems applied to power split control for hybrid vehicles. Automatica, 2014, 50, 187-192.	5.0	68
48	Topology and Flywheel Size Optimization for Mechanical Hybrid Powertrains. IEEE Transactions on Vehicular Technology, 2014, 63, 4192-4205.	6.3	23
49	Gain Scheduling Control of a Walking Piezo Actuator. IEEE/ASME Transactions on Mechatronics, 2014, 19, 954-962.	5.8	18
50	Fast and Smooth Clutch Engagement Control for a Mechanical Hybrid Powertrain. IEEE Transactions on Control Systems Technology, 2014, 22, 1241-1254.	5.2	38
51	Data-based spatial feedforward for over-actuated motion systems. Mechatronics, 2014, 24, 679-690.	3.3	3
52	A dynamic state observer for real-time reconstruction of the tokamak plasma profile state and disturbances. , 2014, , .		12
53	Two-phase plate-fin heat exchanger modeling for waste heat recovery systems in diesel engines. Applied Energy, 2014, 133, 183-196.	10.1	49
54	Optimally conditioned instrumental variable approach for frequency-domain system identification. Automatica, 2014, 50, 2281-2293.	5.0	30

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55	Real-time optical plasma boundary reconstruction for plasma position control at the TCV Tokamak. Nuclear Fusion, 2014, 54, 073018.	3.5	21
56	Frequency domain based real-time performance optimization of Lur'e systems. Mechanical Systems and Signal Processing, 2014, 42, 58-70.	8.0	5
57	Exploiting additional actuators and sensors for nano-positioning robust motion control. Mechatronics, 2014, 24, 619-631.	3.3	34
58	Learning intentions for improved human motion prediction. Robotics and Autonomous Systems, 2014, 62, 591-602.	5.1	44
59	Directional notch filters for motion control of flexible structures. Mechatronics, 2014, 24, 632-639.	3.3	14
60	Model-based spatial feedforward for over-actuated motion systems. Mechatronics, 2014, 24, 307-317.	3.3	26
61	Task analysis of human-in-the-loop tele-operated maintenance: What can be learned from JET?. Fusion Engineering and Design, 2014, 89, 2283-2288.	1.9	6
62	Combining extremum seeking control and tracking control for high-performance CVT operation. Control Engineering Practice, 2014, 29, 86-102.	5.5	8
63	Planar feature-based motion control for near-repetitive structures. Control Engineering Practice, 2014, 29, 123-134.	5.5	0
64	Extremum Seeking Control With Adaptive Disturbance Feedforward. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 383-388.	0.4	5
65	On numerically reliable frequency-domain system identification: new connections and a comparison of methods. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 10018-10023.	0.4	4
66	A representation method based on the probability of collision for safe robot navigation in domestic environments. , 2014, , .		8
67	Comparison of Bi-Level Optimization Frameworks for Sizing and Control of a Hybrid Electric Vehicle. , 2014, , .		27
68	Topology Optimization of Hybrid Power Trains. Lecture Notes in Control and Information Sciences, 2014, , 181-198.	1.0	3
69	Active Object Search Exploiting Probabilistic Object–Object Relations. Lecture Notes in Computer Science, 2014, , 13-24.	1.3	7
70	Sharing Open Hardware through ROP, the Robotic Open Platform. Lecture Notes in Computer Science, 2014, , 584-591.	1.3	5
71	Switching Robust Control Synthesis for Teleoperation via Dwell Time Conditions. Lecture Notes in Computer Science, 2014, , 158-166.	1.3	0
72	Analysis of human-in-the-loop tele-operated maintenance inspection tasks using VR. Fusion Engineering and Design, 2013, 88, 2164-2167.	1.9	18

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73	Optimal gear shift strategies for fuel economy and driveability. Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering, 2013, 227, 1398-1413.	1.9	58
74	Design and control of high tech systems. , 2013, , .		7
75	Model-based approach to minimize system calibrations for 3D reconstruction quality of a cone-beam CT system. , 2013, , .		3
76	Semantic world modeling using probabilistic multiple hypothesis anchoring. Robotics and Autonomous Systems, 2013, 61, 95-105.	5.1	44
77	Optimal higher-order encoder time-stamping. Mechatronics, 2013, 23, 481-490.	3.3	65
78	Deformable mirrors with thermo-mechanical actuators for extreme ultraviolet lithography: Design, realization and validation. Precision Engineering, 2013, 37, 353-363.	3.4	18
79	Learning intentions for improved human motion prediction. , 2013, , .		2
80	A fast, magnetics-free flux surface estimation and q-profile reconstruction algorithm for feedback control of plasma profiles. Plasma Physics and Controlled Fusion, 2013, 55, 025007.	2.1	6
81	Frequency domainâ€based nonlinearity detection and compensation in Lur'e systems. International Journal of Robust and Nonlinear Control, 2013, 23, 1168-1182.	3.7	14
82	Minimizing the number of iterations when computing a base pose for manipulation by mobile base inclusion in the inverse kinematics. , 2013, , .		2
83	Frequency-domain mapping approach of stability bounds for loop shaping of bilateral controllers. , 2013, , .		0
84	Heat exchanger modeling and identification for control of Waste Heat Recovery systems in diesel engines. , 2013, , .		9
85	Exploiting rational basis functions in iterative learning control. , 2013, , .		4
86	Integrating planning and execution for ROS enabled service robots using hierarchical action representations. , 2013, , .		4
87	Feedforward for flexible systems with time-varying performance locations. , 2013, , .		6
88	Switching Robust Control for Transparent and Stable Teleoperation. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 530-536.	0.4	1
89	Experimental Validation of a Dynamic Waste Heat Recovery System Model for Control Purposes. , 2013, , .		15
90	Robust adaptive control of the sawtooth instability in nuclear fusion. , 2012, , .		0

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91	A new Robust Delay-Variable Repetitive Controller with application to media transport in a printer. , 2012, , .		0
92	Extending Energy Management in Hybrid Electric Vehicles with explicit control of gear shifting and start-stop. , 2012, , .		15
93	Sawtooth period control strategies and designs for improved performance. Nuclear Fusion, 2012, 52, 074005.	3.5	10
94	Model-based feedforward for inferential motion systems, with application to a prototype lightweight motion system. , 2012, , .		5
95	Robust performance control design for bilateral teleoperation under time-varying bounded operator and environment dynamics. , 2012, , .		2
96	Real-time period determination for relaxation oscillators using wavelets. , 2012, , .		0
97	Systematic design and simulation of a tearing mode suppression feedback control system for the TEXTOR tokamak. Nuclear Fusion, 2012, 52, 074009.	3.5	6
98	New Connections Between Frequency Response Functions for a Class of Nonlinear Systems*. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 280-285.	0.4	0
99	Review of Optimal Design Strategies for Hybrid Electric Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 57-64.	0.4	29
100	Analysis of optimal mechanical-hybrid powertrain topologies. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 41-48.	0.4	4
101	High Performance and Stable Teleoperation under Bounded Operator and Environment Dynamics. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 373-379.	0.4	13
102	Performance simulations of a low-cost hybrid powertrain with large fuel savings. International Journal of Powertrains, 2012, 1, 377.	0.3	3
103	Uniquely connecting frequency domain representations of given order polynomial Wiener–Hammerstein systems. Automatica, 2012, 48, 2381-2384.	5.0	7
104	High Speed Visual Motion Control Applied to Products With Repetitive Structures. IEEE Transactions on Control Systems Technology, 2012, 20, 1450-1460.	5.2	8
105	Iterative learning control with basis functions for media positioning in scanning inkjet printers. , 2012, , .		12
106	Improving Continuously Variable Transmission Efficiency With Extremum Seeking Control. IEEE Transactions on Control Systems Technology, 2012, 20, 1376-1383.	5.2	18
107	Optimal Control of the Gearshift Command for Hybrid Electric Vehicles. IEEE Transactions on Vehicular Technology, 2012, 61, 3531-3543.	6.3	104
108	Robust sawtooth period control based on adaptive online optimization. Nuclear Fusion, 2012, 52, 074006.	3.5	6

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109	A new mechanism for sawtooth period control. EPJ Web of Conferences, 2012, 32, 02008.	0.3	0
110	Design, implementation, and experimental validation of optimal power split control for hybrid electric trucks. Control Engineering Practice, 2012, 20, 547-558.	5.5	43
111	Linear control of time-domain constrained systems. Automatica, 2012, 48, 736-746.	5.0	6
112	Frequency domain based nonlinear feed forward control design for friction compensation. Mechanical Systems and Signal Processing, 2012, 27, 551-562.	8.0	44
113	Optimal Control of a Mechanical Hybrid Powertrain. IEEE Transactions on Vehicular Technology, 2012, 61, 485-497.	6.3	51
114	Frequency domain based friction compensation - Industrial application to transmission electron microscopes -. , 2011, , .		5
115	Two level world modeling for cooperating robots using a multiple hypotheses filter. , 2011, , .		6
116	Systematic design of a sawtooth period feedback controller using a Kadomtsevâ€"Porcelli sawtooth model. Nuclear Fusion, 2011, 51, 073024.	3.5	16
117	Control of sawteeth and neo-classical tearing modes in tokamaks using electron cyclotron waves. , 2011, , .		0
118	Hierarchical control for drift correction in transmission electron microscopes. , 2011, , .		4
119	ITER Upper Port Plug handling cask system assessment and design proposals. Fusion Engineering and Design, 2011, 86, 1937-1940.	1.9	3
120	Real-time wavelet detection of crashes in limit cycles of non-stationary fusion plasmas. Fusion Engineering and Design, 2011, 86, 2908-2919.	1.9	9
121	Predictive gear shift control for a parallel Hybrid Electric Vehicle. , 2011, , .		24
122	Spectral Analysis of Block Structured Nonlinear Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 4416-4421.	0.4	0
123	Optimal Trajectories for Vehicles with Energy Recovery Options*. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 3831-3836.	0.4	16
124	Analysis of modelling and simulation methodologies for vehicular propulsion systems. International Journal of Powertrains, 2011, 1, 117.	0.3	5
125	Model-Based Drift Control for Electron Microscopes. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 8583-8588.	0.4	4
126	Modeling and Waveform Optimization of a Nano-motion Piezo Stage. IEEE/ASME Transactions on Mechatronics, 2011, 16, 615-626.	5.8	54

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127	Delay-varying repetitive control with application to a walking piezo actuator. Automatica, 2011, 47, 1737-1743.	5.0	28
128	Spectral analysis of block structured nonlinear systems and higher order sinusoidal input describing functions. Automatica, 2011, 47, 2684-2688.	5.0	30
129	The NANOMEFOS non-contact measurement machine for freeform optics. Precision Engineering, 2011, 35, 607-624.	3.4	70
130	A novel ball handling mechanism for the RoboCup middle size league. Mechatronics, 2011, 21, 469-478.	3.3	19
131	Directional Repetitive Control of a Metrological AFM. IEEE Transactions on Control Systems Technology, 2011, 19, 1622-1629.	5.2	10
132	Belt-pulley friction estimation for the Continuously Variable Transmission. , 2011, , .		6
133	Numerical demonstration of injection locking of the sawtooth period by means of modulated EC current drive. Nuclear Fusion, 2011, 51, 103043.	3.5	10
134	A Validated Modular Model for Hydraulic Actuation in a Pushbelt Continuously Variable Transmission. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2011, 133, .	1.6	2
135	Control-oriented modeling of the Electron Cyclotron Current Drive actuated hybrid mode in ITER. , 2011, , .		1
136	Optimal energy management for a flywheel-based hybrid vehicle. , 2011, , .		1
137	Comparison of EGR-VTG Control Schemes for an EPA2010 Heavy-Duty Diesel Engine. , 2011, , .		0
138	CONTROL ORIENTED ANALYSIS AND FEEDBACK CONTROL OF A SAWTOOTH INSTABILITY MODEL. , 2011, , .		0
139	An Enhanced CMM Model for the Accurate Prediction of Steady-State Performance of CVT Chain Drives. Journal of Mechanical Design, Transactions of the ASME, 2010, 132, .	2.9	23
140	ENERGY MANAGEMENT IN HYBRID ELECTRIC VEHICLES: BENEFIT OF PREDICTION. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 264-269.	0.4	16
141	Implementation of an Optimal Control Energy Management Strategy in a Hybrid Truck. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 61-66.	0.4	8
142	Directional Repetitive Control of a Metrological AFM. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 206-211.	0.4	2
143	Velocity and acceleration estimation for optical incremental encoders. Mechatronics, 2010, 20, 20-26.	3.3	84
144	Rejection of fixed direction disturbances in multivariable electromechanical motion systems. Mechatronics, 2010, 20, 45-52.	3.3	2

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145	String-Stable CACC Design and Experimental Validation: A Frequency-Domain Approach. IEEE Transactions on Vehicular Technology, 2010, 59, 4268-4279.	6.3	688
146	Modeling of a walking piezo actuator. Sensors and Actuators A: Physical, 2010, 162, 51-60.	4.1	28
147	Design of a long stroke translation stage for AFM. International Journal of Machine Tools and Manufacture, 2010, 50, 183-190.	13.4	40
148	MIMO feed-forward design in wafer scanners using a gradient approximation-based algorithm. Control Engineering Practice, 2010, 18, 495-506.	5.5	92
149	Design and implementation of parameterized adaptive cruise control: An explicit model predictive control approach. Control Engineering Practice, 2010, 18, 882-892.	5.5	100
150	Performance analysis of reset control systems. International Journal of Robust and Nonlinear Control, 2010, 20, 1213-1233.	3.7	98
151	Optimal Energy Management in Hybrid Electric Trucks Using Route Information. Oil and Gas Science and Technology, 2010, 65, 103-113.	1.4	39
152	Combining extremum seeking control and tracking control for high-performance CVT operation. , 2010, , .		4
153	A robust-control-relevant model validation approach for continuously variable transmission control. , 2010, , .		5
154	Velocity trajectory optimization in Hybrid Electric trucks. , 2010, , .		50
155	Second-order odd-harmonic repetitive control and its application to active filter control. , 2010, , .		10
156	Closed loop control of the sawtooth instability in nuclear fusion. , 2010, , .		0
157	Reference governors for controlled belt restraint systems. Vehicle System Dynamics, 2010, 48, 831-850.	3.7	7
158	Nonlinearities in Industrial motion stages - detection and classification. , 2010, , .		9
159	Frequency response data based optimal control using the data based symmetric root locus. , 2010, , .		6
160	Non-iterative data-driven controller tuning with guaranteed stability: Application to direct-drive pick-and-place robot. , 2010, , .		8
161	Robust control of a clutch system to prevent judder-induced driveline oscillations. Vehicle System Dynamics, 2010, 48, 1379-1394.	3.7	27
162	Optical boundary reconstruction of tokamak plasmas for feedback control of plasma position and shape. Review of Scientific Instruments, 2010, 81, 113504.	1.3	34

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163	A Model Predictive Control Approach to Design a Parameterized Adaptive Cruise Control. Lecture Notes in Control and Information Sciences, 2010, , 273-284.	1.0	10
164	Improvement of fuel economy in Power-Shift Automated Manual Transmission through shift strategy optimization - an experimental study. , 2010, , .		22
165	Real-time control of tearing modes using a line-of-sight electron cyclotron emission diagnostic. Plasma Physics and Controlled Fusion, 2010, 52, 104006.	2.1	40
166	The design of a semi-automated football table. , 2010, , .		4
167	Cooperative adaptive cruise control, design and experiments. , 2010, , .		83
168	New educational demands for the future: Automotive Technology - Master of Science. , 2010, , .		0
169	Control Relevant Blind Identification of Disturbances With Application to a Multivariable Active Vibration Isolation Platform. IEEE Transactions on Control Systems Technology, 2010, 18, 393-404.	5.2	9
170	Advanced Motion Control Design. The Electrical Engineering Handbook, 2010, , 27-1-27-25.	0.2	12
171	A Haptic Gearshift Interface for Cars. Lecture Notes in Computer Science, 2010, , 315-320.	1.3	1
172	An analogy between the Van der Pol equation and the Greitzer model. , 2009, , .		0
173	Control oriented modeling and simulation of the sawtooth instability in nuclear fusion tokamak plasmas. , 2009, , .		1
174	Model-free norm-based fixed structure controller synthesis. , 2009, , .		9
175	Dynamic decoupling in motion systems using a gradient approximation-based algorithm. , 2009, , .		3
176	Reading of cracked optical discs using Iterative Learning Control. , 2009, , .		1
177	LPV control of an active vibration isolation system. , 2009, , .		0
178	Direct dynamic visual servoing at 1 kHz by using the product as 1.5D encoder. , 2009, , .		3
179	ECE system on ASDEX-upgrade placed inline at the high power waveguide based transmission system. , 2009, , .		4
180	Improving pushbelt continuously variable transmission efficiency via extremum seeking control. , 2009, , .		5

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181	Modeling and compensation of asymmetric hysteresis in a piezo actuated metrological AFM. , 2009, , .		7
182	Linear control of time-domain constrained systems. , 2009, , .		1
183	Deformable mirrors: design fundamentals for force actuation of continuous facesheets. , 2009, , .		7
184	Design of CVT-Based Hybrid Passenger Cars. IEEE Transactions on Vehicular Technology, 2009, 58, 572-587.	6.3	36
185	Energy buffered carriage reversal for wide format printing systems. Mechatronics, 2009, 19, 735-747.	3.3	1
186	A closed-loop control system for stabilization of MHD events on TEXTOR. Fusion Engineering and Design, 2009, 84, 928-934.	1.9	16
187	Identification, control and hysteresis compensation of a 3 DOF metrological AFM. Asian Journal of Control, 2009, 11, 130-143.	3.0	49
188	Control-oriented modelling of occupants in frontal impacts. International Journal of Crashworthiness, 2009, 14, 323-337.	1.9	15
189	Repetitive control applied to a walking piezo actuator. , 2009, , .		5
190	Nanometer level freeform surface measurements with the NANOMEFOS non-contact measurement machine. , 2009, , .		6
191	Design of a minimally invasive surgical teleoperated master-slave system with haptic feedback. , 2009, , .		26
192	Modeling of a walking piezo actuator. , 2009, , .		5
193	Time-domain performance based non-linear state feedback control of constrained linear systems. International Journal of Control, 2009, 82, 352-364.	1.9	4
194	Using a Walking Piezo Actuator to Drive and Control a High-Precision Stage. IEEE/ASME Transactions on Mechatronics, 2009, 14, 21-31.	5.8	79
195	Stability Analysis of Networked Control Systems Using a Switched Linear Systems Approach. Lecture Notes in Computer Science, 2009, , 150-164.	1.3	41
196	Improving Maneuverability and Tactile Feedback in Medical Catheters by Optimizing the Valve Toward Minimal Friction. Journal of Medical Devices, Transactions of the ASME, 2009, 3, .	0.7	1
197	Recovering Data from Cracked Optical Discs using Hankel Iterative Learning Control. , 2009, , 147-166.		1
198	Multivariable control of a metrological Atomic Force Microscope. , 2009, , .		0

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199	Iterative learning control with wavelet filtering. International Journal of Robust and Nonlinear Control, 2008, 18, 1052-1071.	3.7	17
200	Experimental characterization of the stick/sliding transition in a precision mechanical system using the third order sinusoidal input describing function. Mechatronics, 2008, 18, 100-110.	3.3	11
201	Measuring the higher order sinusoidal input describing functions of a non-linear plant operating in feedback. Control Engineering Practice, 2008, 16, 101-113.	5.5	19
202	Robust control of piecewise linear systems: A case study in sheet flow control. Control Engineering Practice, 2008, 16, 991-1003.	5.5	21
203	Data-driven multivariable controller design using Ellipsoidal Unfalsified Control. Systems and Control Letters, 2008, 57, 759-762.	2.3	28
204	Adaptive Iterative Learning Control for High Precision Motion Systems. IEEE Transactions on Control Systems Technology, 2008, 16, 1075-1082.	5.2	72
205	Reference governors for controlled belt restraint systems. , 2008, , .		3
206	Data-Driven Controller Unfalsification With Analytic Update Applied to a Motion System. IEEE Transactions on Control Systems Technology, 2008, 16, 1207-1217.	5.2	9
207	Explicit MPC design and performance-based tuning of an Adaptive Cruise Control Stop-&-Go. , 2008, , .		15
208	An LMI-based L<inf>2</inf> gain performance analysis for reset control systems. , 2008, , .		3
209	Bias Removal in Higher Order Sinusoidal Input Describing Functions. , 2008, , .		1
210	Circle criterion in linear control design. , 2008, , .		5
211	Validation of a new adaptive deformable mirror concept. , 2008, , .		11
212	Modeling, identification and control of a metrological Atomic Force Microscope with a 3DOF stage. , 2008, , .		3
213	Norm optimal Cross-Coupled Iterative Learning Control. , 2008, , .		22
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