Qinglin Tian

List of Publications by Year in descending order

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1478505 1372567 12 387 10 6 citations h-index g-index papers 12 12 12 454 docs citations times ranked citing authors all docs

| # | Article | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | A Multi-Mode Dead Reckoning System for Pedestrian Tracking Using Smartphones. IEEE Sensors Journal, 2016, 16, 2079-2093. | 4.7 | 136 |
| 2 | A Low-Cost INS and UWB Fusion Pedestrian Tracking System. IEEE Sensors Journal, 2019, 19, 3733-3740. | 4.7 | 60 |
| 3 | Human Body Shadowing Effect on UWB-Based Ranging System for Pedestrian Tracking. IEEE Transactions on Instrumentation and Measurement, 2019, 68, 4028-4037. | 4.7 | 57 |
| 4 | A Hybrid Indoor Localization and Navigation System with Map Matching for Pedestrians Using Smartphones. Sensors, 2015, 15, 30759-30783. | 3.8 | 41 |
| 5 | A Resetting Approach for INS and UWB Sensor Fusion Using Particle Filter for Pedestrian Tracking. IEEE Transactions on Instrumentation and Measurement, 2020, 69, 5914-5921. | 4.7 | 35 |
| 6 | An INS and UWB Fusion Approach With Adaptive Ranging Error Mitigation for Pedestrian Tracking. IEEE Sensors Journal, 2020, 20, 4372-4381. | 4.7 | 34 |
| 7 | An enhanced pedestrian dead reckoning approach for pedestrian tracking using smartphones., 2015,,. | | 9 |
| 8 | Hierarchical Resampling Algorithm and Architecture for Distributed Particle Filters. Journal of Signal Processing Systems, 2013, 71, 237-246. | 2.1 | 5 |
| 9 | Real-Time Infrastructureless Indoor Tracking for Pedestrian Using a Smartphone. IEEE Sensors Journal, 2019, 19, 10782-10795. | 4.7 | 5 |
| 10 | An INS and UWB Fusion-Based Gyroscope Drift Correction Approach for Indoor Pedestrian Tracking. Sensors, 2020, 20, 4476. | 3.8 | 3 |
| 11 | DART: Distributed Particle Filter Algorithm with Resampling Tree for Ultimate Real-Time Capability. Journal of Signal Processing Systems, 2017, 88, 29-42. | 2.1 | 2 |
| 12 | Particle state compression scheme for centralized memory-efficient particle filters., 2013,,. | | 0 |