## Alexander V Terekhov

List of Publications by Year in descending order

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840776 996975 18 476 11 15 citations h-index g-index papers 18 18 18 551 docs citations times ranked citing authors all docs

| #  | Article  | IF  | Citations |
|----|--|-----|-----------|
| 1  | Segregation of Tactile Input Features in Neurons of the Cuneate Nucleus. Neuron, 2014, 83, 1444-1452.  | 8.1 | 111       |
| 2  | The Change in Fingertip Contact Area as a Novel Proprioceptive Cue. Current Biology, 2016, 26, 1159-1163.  | 3.9 | 60        |
| 3  | An analytical approach to the problem of inverse optimization with additive objective functions: an application to human prehension. Journal of Mathematical Biology, 2010, 61, 423-453. | 1.9 | 53        |
| 4  | Intersegmental Coordination During Human Locomotion: Does Planar Covariation of Elevation Angles Reflect Central Constraints?. Journal of Neurophysiology, 2006, 96, 1406-1419.          | 1.8 | 50        |
| 5  | Spatio-temporal skin strain distributions evoke low variability spike responses in cuneate neurons. Journal of the Royal Society Interface, 2014, 11, 20131015.                          | 3.4 | 49        |
| 6  | Minimal adhesion surface area in tangentially loaded digital contacts. Journal of Biomechanics, 2011, 44, 2508-2510.   | 2.1 | 29        |
| 7  | Analytical and numerical analysis of inverse optimization problems: conditions of uniqueness and computational methods. Biological Cybernetics, 2011, 104, 75-93.                        | 1.3 | 26        |
| 8  | Optimality and stability of intentional and unintentional actions: I. Origins of drifts in performance. Experimental Brain Research, 2017, 235, 481-496.                                 | 1.5 | 23        |
| 9  | Forces and moments generated by the human arm: variability and control. Experimental Brain Research, 2012, 223, 159-175.   | 1.5 | 20        |
| 10 | Learning agent's spatial configuration from sensorimotor invariants. Robotics and Autonomous Systems, 2015, 71, 49-59.   | 5.1 | 17        |
| 11 | Discovering space —ÂGrounding spatial topology and metric regularity in a naive agent's sensorimotor experience. Neural Networks, 2018, 105, 371-392.                                    | 5.9 | 11        |
| 12 | Reconstruction of the Unknown Optimization Cost Functions from Experimental Recordings during Static Multi-Finger Prehension. Motor Control, 2012, 16, 195-228.                          | 0.6 | 10        |
| 13 | Optimization and Variability of Motor Behavior in Multifinger Tasks: What Variables Does the Brain Use?. Journal of Motor Behavior, 2013, 45, 289-305.                                   | 0.9 | 7         |
| 14 | Comparison of Interfinger Connection Matrix Computation Techniques. Journal of Applied Biomechanics, 2013, 29, 525-534.  | 0.8 | 4         |
| 15 | Stochastic optimization of a neural network-based controller for aggressive maneuvers on loose surfaces. , 2010, , .   |     | 2         |
| 16 | EXPERIMENTAL STUDY OF A FAST MOBILE ROBOT PERFORMING A DRIFT MANEUVER. , 2010, , .   |     | 2         |
| 17 | Stochastic optimization of a chain sliding mode controller for the mobile robot maneuvering. , 2011, , .   |     | 1         |
| 18 | Analytical Inverse Optimization in Two-Hand Prehensile Tasks. Journal of Motor Behavior, 2016, 48, 424-434.  | 0.9 | 1         |