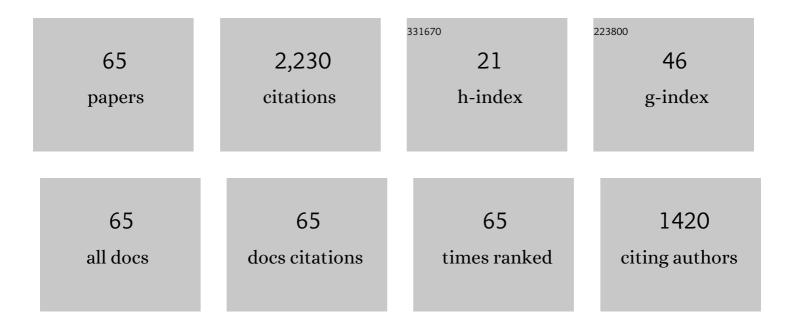
## Luigi Chisci

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/23637/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	Event-Triggered Consensus LMB Filter for Distributed Multitarget Tracking. IEEE Transactions on Aerospace and Electronic Systems, 2023, 59, 712-719.	4.7	1
2	Unknown source in spatially distributed systems: Identifiability analysis and estimation. Automatica, 2022, 136, 110025.	5.0	2
3	Multi-Agent Fusion With Different Limited Fields-of-View. IEEE Transactions on Signal Processing, 2022, 70, 1560-1575.	5.3	10
4	Distributed joint target detection, tracking and classification via Bernoulli filter. IET Radar, Sonar and Navigation, 2022, 16, 1000-1013.	1.8	3
5	Consensus variational Bayesian moving horizon estimation for distributed sensor networks with unknown noise covariances. Signal Processing, 2022, 198, 108571.	3.7	2
6	A variational Bayes moving horizon estimation adaptive filter with guaranteed stability. Automatica, 2022, 142, 110374.	5.0	1
7	Fusion of Labeled RFS Densities With Different Fields of View. IEEE Transactions on Aerospace and Electronic Systems, 2022, 58, 5908-5924.	4.7	6
8	An Event-Triggered Hybrid Consensus Filter for Distributed Sensor Network. IEEE Signal Processing Letters, 2022, 29, 1472-1476.	3.6	1
9	An adaptive variational Bayesian filter for nonlinear multi-sensor systems with unknown noise statistics. Signal Processing, 2021, 179, 107837.	3.7	26
10	Centralized Cooperative Sensor Fusion for Dynamic Sensor Network With Limited Field-of-View via Labeled Multi-Bernoulli Filter. IEEE Transactions on Signal Processing, 2021, 69, 878-891.	5.3	25
11	An Adaptive Consensus Filter for Distributed State Estimation With Unknown Noise Statistics. IEEE Signal Processing Letters, 2021, 28, 1595-1599.	3.6	10
12	PHD-SLAM 2.0: Efficient SLAM in the Presence of Missdetections and Clutter. IEEE Transactions on Robotics, 2021, 37, 1834-1843.	10.3	14
13	Fusion-Based Multidetection Multitarget Tracking With Random Finite Sets. IEEE Transactions on Aerospace and Electronic Systems, 2021, 57, 2438-2458.	4.7	15
14	Distributed multi-view multi-target tracking based on CPHD filtering. Signal Processing, 2021, 188, 108210.	3.7	15
15	Indirect adaptive fuzzy control of nonlinear descriptor systems. European Journal of Control, 2020, 51, 30-38.	2.6	14
16	Cooperative sensor fusion in centralized sensor networks using Cauchy–Schwarz divergence. Signal Processing, 2020, 167, 107278.	3.7	29
17	Distributed Joint Sensor Registration and Multitarget Tracking via Sensor Network. IEEE Transactions on Aerospace and Electronic Systems, 2020, 56, 1301-1317.	4.7	28
18	Radial pole path approach for fast response of affine constrained nonlinear systems with matched uncertainties. International Journal of Robust and Nonlinear Control, 2020, 30, 142-158.	3.7	4

Luigi Chisci

#	Article	IF	CITATIONS
19	Joint attack detection and secure state estimation of cyberâ€physical systems. International Journal of Robust and Nonlinear Control, 2020, 30, 4303-4330.	3.7	15
20	MAP moving horizon estimation for threshold measurements with application to field monitoring. International Journal of Adaptive Control and Signal Processing, 2020, 34, 796-811.	4.1	6
21	Random-Finite-Set-Based Distributed Multirobot SLAM. IEEE Transactions on Robotics, 2020, 36, 1758-1777.	10.3	21
22	Fusion of Labeled RFS Densities With Minimum Information Loss. IEEE Transactions on Signal Processing, 2020, 68, 5855-5868.	5.3	34
23	Distributed multi-target tracking over an asynchronous multi-sensor network. , 2020, , .		5
24	An Adaptive Filter for Nonlinear Multi-Sensor Systems with Heavy-Tailed Noise. Sensors, 2020, 20, 6757.	3.8	4
25	Multiobject Fusion With Minimum Information Loss. IEEE Signal Processing Letters, 2020, 27, 201-205.	3.6	53
26	Passive target detection and tracking from electromagnetic field measurements. International Journal of RF and Microwave Computer-Aided Engineering, 2020, 30, e22321.	1.2	2
27	GCI fusion based multi-detection multitarget tracking. , 2020, , .		0
28	Network equilibrium stabilization via single-node insertion. , 2019, , .		0
29	Event-Triggered Distributed Multitarget Tracking. IEEE Transactions on Signal and Information Processing Over Networks, 2019, 5, 570-584.	2.8	15
30	Direct Adaptive Fuzzy Control of Nonlinear Descriptor Systems. International Journal of Fuzzy Systems, 2019, 21, 2588-2599.	4.0	7
31	Interactive Multiple-Target Tracking via Labeled Multi-Bernoulli Filters. , 2019, , .		3
32	Distributed Joint Mapping and Registration with Limited Fields-of-View. , 2019, , .		5
33	Distributed state estimation under denial of service. , 2019, , .		2
34	Computationally Eff <roman>i</roman> cient Multi-Agent Multi-Object Tracking With Labeled Random Finite Sets. IEEE Transactions on Signal Processing, 2019, 67, 260-275.	5.3	67
35	Distributed joint sensor registration and target tracking via sensor network. Information Fusion, 2019, 46, 218-230.	19.1	23
36	A distributed Kalman filter with event-triggered communication and guaranteed stability. Automatica, 2018, 93, 75-82.	5.0	127

Luісі Снізсі

#	Article	IF	CITATIONS
37	Robust Fusion for Multisensor Multiobject Tracking. IEEE Signal Processing Letters, 2018, 25, 640-644.	3.6	95
38	Distributed Averaging of Exponential-Class Densities With Discrete-Time Event-Triggered Consensus. IEEE Transactions on Control of Network Systems, 2018, 5, 359-369.	3.7	10
39	Distributed Joint Attack Detection and Secure State Estimation. IEEE Transactions on Signal and Information Processing Over Networks, 2018, 4, 96-110.	2.8	49
40	Centralized Multiple-View Information Fusion for Multi-Object Tracking Using Labeled Multi-Bernoulli Filters. , 2018, , .		7
41	Event-Triggered Consensus Bernoulli Filtering. , 2018, , .		4
42	Multi-Sensor Multi-Object Tracking with Different Fields-of-View Using the LMB Filter. , 2018, , .		17
43	Distributed Finite-Element Kalman Filter for Field Estimation. IEEE Transactions on Automatic Control, 2017, 62, 3309-3322.	5.7	21
44	Memory Unscented Particle Filter for 6-DOF Tactile Localization. IEEE Transactions on Robotics, 2017, 33, 1139-1155.	10.3	30
45	Moving horizon estimation for discrete-time linear systems with binary sensors: Algorithms and stability results. Automatica, 2017, 85, 374-385.	5.0	19
46	Worst-case analysis of joint attack detection and resilient state estimation. , 2017, , .		8
47	Random Set Approach to Distributed Multivehicle SLAM. IFAC-PapersOnLine, 2017, 50, 2457-2464.	0.9	14
48	Secure State Estimation of Cyber-Physical Systems Under Switching Attacks. IFAC-PapersOnLine, 2017, 50, 4979-4986.	0.9	16
49	Control of multidimensional systems on complex network. PLoS ONE, 2017, 12, e0184431.	2.5	6
50	A Bayesian approach to joint attack detection and resilient state estimation. , 2016, , .		25
51	MAP Moving Horizon state estimation with binary measurements. , 2016, , .		3
52	Stability of consensus extended Kalman filter for distributed state estimation. Automatica, 2016, 68, 169-178.	5.0	230
53	Moving horizon state estimation for discrete-time linear systems with binary sensors. , 2015, , .		5
54	Networked target tracking With Doppler sensors. IEEE Transactions on Aerospace and Electronic Systems, 2015, 51, 3294-3306.	4.7	9

Luigi Chisci

#	Article	IF	CITATIONS
55	Consensusâ€based multipleâ€model Bayesian filtering for distributed tracking. IET Radar, Sonar and Navigation, 2015, 9, 401-410.	1.8	22
56	Kullback–Leibler average, consensus on probability densities, and distributed state estimation with guaranteed stability. Automatica, 2014, 50, 707-718.	5.0	390
57	Consensus CPHD Filter for Distributed Multitarget Tracking. IEEE Journal on Selected Topics in Signal Processing, 2013, 7, 508-520.	10.8	249
58	Data-driven communication for state estimation with sensor networks. Automatica, 2012, 48, 926-935.	5.0	70
59	An Information-Theoretic Approach to Distributed State Estimation. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 12477-12482.	0.4	30
60	Real-Time Epileptic Seizure Prediction Using AR Models and Support Vector Machines. IEEE Transactions on Biomedical Engineering, 2010, 57, 1124-1132.	4.2	213
61	An approach to threat assessment based on evidential networks. , 2007, , .		17
62	Estimation of Constrained Parameters With Guaranteed MSE Improvement. IEEE Transactions on Signal Processing, 2007, 55, 1264-1274.	5.3	14
63	Dual mode predictive tracking of piecewise constant references for constrained linear systems. International Journal of Control, 2003, 76, 61-72.	1.9	58
64	Robust Predictive Regulation with Invariance Constraint. European Journal of Control, 2002, 8, 2-14.	2.6	2
65	Modular and Numerically Stable Multichannel Fast Transversal Filters. IETE Journal of Research, 1989,	2.6	9