

# Robert Babuska

## List of Publications by Year in descending order

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312  
papers

12,021  
citations

50276

46  
h-index

38395

95  
g-index

320  
all docs

320  
docs citations

320  
times ranked

8265  
citing authors

#	ARTICLE	IF	CITATIONS
1	A Comprehensive Survey of Multiagent Reinforcement Learning. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2008, 38, 156-172.	2.9	1,328
2	Fuzzy Modeling for Control. International Series in Intelligent Technologies, 1998, , .	0.1	661
3	A Survey of Actor-Critic Reinforcement Learning: Standard and Natural Policy Gradients. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2012, 42, 1291-1307.	2.9	606
4	Similarity measures in fuzzy rule base simplification. IEEE Transactions on Systems, Man, and Cybernetics, 1998, 28, 376-386.	5.0	398
5	Perspectives of fuzzy systems and control. Fuzzy Sets and Systems, 2005, 156, 432-444.	2.7	358
6	Fuzzy model for the prediction of unconfined compressive strength of rock samples. International Journal of Rock Mechanics and Minings Sciences, 1999, 36, 339-349.	5.8	299
7	Multi-agent Reinforcement Learning: An Overview. Studies in Computational Intelligence, 2010, , 183-221.	0.9	278
8	Neuro-fuzzy methods for nonlinear system identification. Annual Reviews in Control, 2003, 27, 73-85.	7.9	250
9	An overview of fuzzy modeling for control. Control Engineering Practice, 1996, 4, 1593-1606.	5.5	247
10	Modified Gath-Geva fuzzy clustering for identification of Takagi-Sugeno fuzzy models. IEEE Transactions on Systems, Man, and Cybernetics, 2002, 32, 612-621.	5.0	246
11	Rule-based modeling: precision and transparency. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 1998, 28, 165-169.	2.9	238
12	Residential Demand Response of Thermostatically Controlled Loads Using Batch Reinforcement Learning. IEEE Transactions on Smart Grid, 2017, 8, 2149-2159.	9.0	232
13	Railway Track Circuit Fault Diagnosis Using Recurrent Neural Networks. IEEE Transactions on Neural Networks and Learning Systems, 2017, 28, 523-533.	11.3	220
14	Multi-agent discrete-time graphical games and reinforcement learning solutions. Automatica, 2014, 50, 3038-3053.	5.0	206
15	Deep convolutional neural networks for detection of rail surface defects. , 2016, , .		205
16	Experience Replay for Real-Time Reinforcement Learning Control. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2012, 42, 201-212.	2.9	165
17	Stability Analysis and Nonlinear Observer Design Using Takagi-Sugeno Fuzzy Models. Studies in Fuzziness and Soft Computing, 2011, , .	0.8	137
18	Optimal model-free output synchronization of heterogeneous systems using off-policy reinforcement learning. Automatica, 2016, 71, 334-341.	5.0	130

#	ARTICLE	IF	CITATIONS
19	Fuzzy predictive control applied to an air-conditioning system. Control Engineering Practice, 1997, 5, 1395-1406.	5.5	128
20	Effective Optimization for Fuzzy Model Predictive Control. IEEE Transactions on Fuzzy Systems, 2004, 12, 661-675.	9.8	119
21	Fuzzy model-based predictive control using Takagi-Sugeno models. International Journal of Approximate Reasoning, 1999, 22, 3-30.	3.3	116
22	Multiobjective identification of Takagi-Sugeno fuzzy models. IEEE Transactions on Fuzzy Systems, 2003, 11, 847-860.	9.8	113
23	Reinforcement Learning Applied to an Electric Water Heater: From Theory to Practice. IEEE Transactions on Smart Grid, 2018, 9, 3792-3800.	9.0	112
24	Genetic algorithms for optimization in predictive control. Control Engineering Practice, 1997, 5, 1363-1372.	5.5	101
25	Efficient Model Learning Methods for Actor-Critic Control. IEEE Transactions on Systems, Man, and Cybernetics, 2012, 42, 591-602.	5.0	97
26	A Big Data Analysis Approach for Rail Failure Risk Assessment. Risk Analysis, 2017, 37, 1495-1507.	2.7	86
27	Fuzzy relational classifier trained by fuzzy clustering. IEEE Transactions on Systems, Man, and Cybernetics, 1999, 29, 619-625.	5.0	84
28	Adaptive observers for TS fuzzy systems with unknown polynomial inputs. Fuzzy Sets and Systems, 2010, 161, 2043-2065.	2.7	84
29	Input Selection for Nonlinear Regression Models. IEEE Transactions on Fuzzy Systems, 2004, 12, 688-696.	9.8	81
30	Reinforcement learning based compensation methods for robot manipulators. Engineering Applications of Artificial Intelligence, 2019, 78, 236-247.	8.1	77
31	Integrating State Representation Learning Into Deep Reinforcement Learning. IEEE Robotics and Automation Letters, 2018, 3, 1394-1401.	5.1	72
32	Fuzzy gain scheduling: controller and observer design based on lyapunov method and convex optimization. IEEE Transactions on Fuzzy Systems, 2003, 11, 285-298.	9.8	69
33	Identification and Control of Nonlinear Systems Using Fuzzy Hammerstein Models. Industrial & Engineering Chemistry Research, 2000, 39, 4302-4314.	3.7	68
34	Machine Learning Algorithms in Bipedal Robot Control. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2012, 42, 728-743.	2.9	66
35	Constructing Fuzzy Models by Product Space Clustering. , 1997, , 53-90.		64
36	Multi-Agent Reinforcement Learning: A Survey. , 2006, , .		64

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37	Towards automation of control software: A review of challenges in mechatronic design. <i>Mechatronics</i> , 2010, 20, 876-886.	3.3	64
38	Rule base reduction: some comments on the use of orthogonal transforms. <i>IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews</i> , 2001, 31, 199-206.	2.9	62
39	Timely condition-based maintenance planning for multi-component systems. <i>Reliability Engineering and System Safety</i> , 2017, 159, 310-321.	8.9	62
40	Parametric Bayesian Filters for Nonlinear Stochastic Dynamical Systems: A Survey. <i>IEEE Transactions on Cybernetics</i> , 2013, 43, 1607-1624.	9.5	59
41	Cross-Entropy Optimization of Control Policies With Adaptive Basis Functions. <i>IEEE Transactions on Systems, Man, and Cybernetics</i> , 2011, 41, 196-209.	5.0	58
42	Combining knowledge and historical data for system-level fault diagnosis of HVAC systems. <i>Engineering Applications of Artificial Intelligence</i> , 2017, 59, 260-273.	8.1	55
43	Fuzzy self-tuning PI control of pH in fermentation. <i>Engineering Applications of Artificial Intelligence</i> , 2002, 15, 3-15.	8.1	54
44	Comparison of intelligent control schemes for real-time pressure control. <i>Control Engineering Practice</i> , 1996, 4, 1585-1592.	5.5	53
45	Performance improvement of a drop-on-demand inkjet printhead using an optimization-based feedforward control method. <i>Control Engineering Practice</i> , 2011, 19, 771-781.	5.5	53
46	Bayesian and Dempster-Shafer reasoning for knowledge-based fault diagnosis: A comparative study. <i>Engineering Applications of Artificial Intelligence</i> , 2017, 60, 136-150.	8.1	53
47	Compatible cluster merging for fuzzy modelling. , 0, , .		52
48	Approximate dynamic programming with a fuzzy parameterization. <i>Automatica</i> , 2010, 46, 804-814.	5.0	52
49	Adaptive fuzzy control of satellite attitude by reinforcement learning. <i>IEEE Transactions on Fuzzy Systems</i> , 1998, 6, 185-194.	9.8	50
50	Port-Hamiltonian Systems in Adaptive and Learning Control: A Survey. <i>IEEE Transactions on Automatic Control</i> , 2016, 61, 1223-1238.	5.7	50
51	Stability of Cascaded Fuzzy Systems and Observers. <i>IEEE Transactions on Fuzzy Systems</i> , 2009, 17, 641-653.	9.8	49
52	Knowledge-based fuzzy model for performance prediction of a rock-cutting trencher. <i>International Journal of Approximate Reasoning</i> , 1997, 16, 43-66.	3.3	47
53	Fuzzy modeling with multivariate membership functions: gray-box identification and control design. <i>IEEE Transactions on Systems, Man, and Cybernetics</i> , 2001, 31, 755-767.	5.0	46
54	Unified Modeling and Control of Walking and Running on the Spring-Loaded Inverted Pendulum. <i>IEEE Transactions on Robotics</i> , 2016, 32, 1178-1195.	10.3	46

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55	Computer-controlled mechanical simulation of the artificially ventilated human respiratory system. IEEE Transactions on Biomedical Engineering, 2003, 50, 731-743.	4.2	45
56	Identification of MIMO systems by input-output TS fuzzy models. , 0, , .		43
57	A fast sampling method for estimating the domain of attraction. Nonlinear Dynamics, 2016, 86, 823-834.	5.2	42
58	Decentralized Reinforcement Learning of Robot Behaviors. Artificial Intelligence, 2018, 256, 130-159.	5.8	41
59	Incorporating prior knowledge in fuzzy model identification. International Journal of Systems Science, 2000, 31, 657-667.	5.5	40
60	A new identification method for linguistic fuzzy models. , 0, , .		39
61	Adaptive fuzzy control of a non-linear servo-drive: Theory and experimental results. Engineering Applications of Artificial Intelligence, 2008, 21, 846-857.	8.1	39
62	Online least-squares policy iteration for reinforcement learning control. , 2010, , .		39
63	Clavulanic Acid Degradation in Streptomyces clavuligerus Fed-Batch Cultivations. Biotechnology Progress, 2002, 18, 451-457.	2.6	37
64	A Waveform Design Method for a Piezo Inkjet Printhead Based on Robust Feedforward Control. Journal of Microelectromechanical Systems, 2012, 21, 1365-1374.	2.5	37
65	Robust stability constraints for fuzzy model predictive control. IEEE Transactions on Fuzzy Systems, 2002, 10, 50-64.	9.8	36
66	Distributed Controller Design Approach to Dynamic Speed Limit Control against Shockwaves on Freeways. Transportation Research Record, 2008, 2086, 93-99.	1.9	36
67	Distributed nonlinear estimation for robot localization using weighted consensus. , 2010, , .		35
68	Soft computing applications in aircraft sensor management and flight control law reconfiguration. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2002, 32, 125-139.	2.9	34
69	A fuzzy decision support system for traffic control centers. , 0, , .		33
70	Reinforcement Learning for Port-Hamiltonian Systems. IEEE Transactions on Cybernetics, 2015, 45, 1017-1027.	9.5	33
71	Vision-based Navigation Using Deep Reinforcement Learning. , 2019, , .		32
72	Local and global identification and interpretation of parameters in Takagi-Sugeno fuzzy models. , 0, , .		31

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73	Design of a gain-scheduling mechanism for flight control laws by fuzzy clustering. Control Engineering Practice, 2006, 14, 769-781.	5.5	30
74	Ant Colony Routing algorithm for freeway networks. Transportation Research Part C: Emerging Technologies, 2013, 37, 1-19.	7.6	30
75	Distributed Kalman filtering for cascaded systems. Engineering Applications of Artificial Intelligence, 2008, 21, 457-469.	8.1	29
76	Attitude and altitude estimation and control on board a Flapping Wing Micro Air Vehicle. , 2015, , .		29
77	Transparent Fuzzy Modelling. International Journal of Human Computer Studies, 1998, 49, 159-179.	5.6	28
78	Fuzzy logic based full-envelope autonomous flight control for an atmospheric re-entry spacecraft. Control Engineering Practice, 2003, 11, 11-25.	5.5	28
79	Fuzzy logic based attitude control of the spacecraft X-38 along a nominal re-entry trajectory. Control Engineering Practice, 2001, 9, 699-707.	5.5	27
80	Control of the fluidised bed in the pellet softening process. Chemical Engineering Science, 2008, 63, 1390-1400.	3.8	27
81	Accurate, Transparent, and Compact Fuzzy Models for Function Approximation and Dynamic Modeling through Multi-objective Evolutionary Optimization. Lecture Notes in Computer Science, 2001, , 653-667.	1.3	27
82	Virtual sensor for fault detection and isolation in flight control systems - fuzzy modeling approach. , 0, , .		26
83	Decentralized Reinforcement Learning Control of a Robotic Manipulator. , 2006, , .		25
84	Ant Colony Optimization for traffic dispersion routing. , 2010, , .		25
85	Modeling and Control of Legged Locomotion via Switching Max-Plus Models. IEEE Transactions on Robotics, 2014, 30, 652-665.	10.3	25
86	Learning state representation for deep actor-critic control. , 2016, , .		25
87	Probabilistic Defect-Based Risk Assessment Approach for Rail Failures in Railway Infrastructure. IFAC-PapersOnLine, 2016, 49, 73-77.	0.9	25
88	Model-Plant Mismatch Compensation Using Reinforcement Learning. IEEE Robotics and Automation Letters, 2018, 3, 2471-2477.	5.1	25
89	Control delay in Reinforcement Learning for real-time dynamic systems: A memoryless approach. , 2010, , .		24
90	Passivity-based reinforcement learning control of a 2-DOF manipulator arm. Mechatronics, 2014, 24, 1001-1007.	3.3	24

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91	Virtual Sensor for the Angle-of-Attack Signal in Small Commercial Aircraft. , 2006, , .		23
92	Visual Navigation in Real-World Indoor Environments Using End-to-End Deep Reinforcement Learning. IEEE Robotics and Automation Letters, 2021, 6, 4345-4352.	5.1	23
93	Decentralized Kalman filter comparison for distributed-parameter systems: A case study for a 1D heat conduction process. , 2011, , .		22
94	Directional Singularity-Robust Torque Control for Gyroscopic Actuators. IEEE/ASME Transactions on Mechatronics, 2016, 21, 2755-2763.	5.8	21
95	Intelligent adaptive control of bioreactors. Journal of Intelligent Manufacturing, 2003, 14, 255-265.	7.3	20
96	A semi-supervised method to detect seismic random noise with fuzzy GK clustering. Journal of Geophysics and Engineering, 2008, 5, 457-468.	1.4	20
97	Model learning actor-critic algorithms: Performance evaluation in a motion control task. , 2012, , .		20
98	Constrained distributed algebraic connectivity maximization in robotic networks. Automatica, 2013, 49, 1348-1357.	5.0	20
99	Comparison of model-free and model-based methods for time optimal hit control of a badminton robot. Mechatronics, 2014, 24, 1021-1030.	3.3	20
100	Rule base simplification with similarity measures. , 0, , .		19
101	Fuzzy modeling of enzymatic penicillin-G conversion. Engineering Applications of Artificial Intelligence, 1999, 12, 79-92.	8.1	19
102	Saturated Particle Filter: Almost sure convergence and improved resampling. Automatica, 2013, 49, 147-159.	5.0	19
103	A Multiple-Model Reliability Prediction Approach for Condition-Based Maintenance. IEEE Transactions on Reliability, 2018, 67, 1364-1376.	4.6	19
104	Efficient training algorithm for Takagi-Sugeno type neuro-fuzzy network. , 0, , .		18
105	Estimation of respiratory parameters via fuzzy clustering. Artificial Intelligence in Medicine, 2001, 21, 91-105.	6.5	18
106	Online self-evolving fuzzy controller with global learning capabilities. Evolving Systems, 2010, 1, 225-239.	3.9	18
107	On distributed maximization of algebraic connectivity in robotic networks. , 2011, , .		18
108	Benchmarking model-free and model-based optimal control. Robotics and Autonomous Systems, 2017, 92, 81-90.	5.1	18

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109	Closed-Loop Control Through Self-Sensing of a Joule-Heated Twisted and Coiled Polymer Muscle. <i>Soft Robotics</i> , 2019, 6, 621-630.	8.0	18
110	Complexity reduction in fuzzy modeling. <i>Mathematics and Computers in Simulation</i> , 1998, 46, 507-516.	4.4	17
111	COMPOSITE ADAPTIVE FUZZY CONTROL. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2005, 38, 97-102.	0.4	17
112	Genetic polynomial regression as input selection algorithm for non-linear identification. <i>Soft Computing</i> , 2006, 10, 785-795.	3.6	17
113	Model-based operational constraints for fluidised bed crystallisation. <i>Water Research</i> , 2008, 42, 327-337.	11.3	17
114	Estimation of the soil-dependent time-varying parameters of the hopper sedimentation model: The FPF versus the BPF. <i>Control Engineering Practice</i> , 2014, 24, 67-78.	5.5	17
115	Balancing a Legged Robot Using State-Dependent Riccati Equation Control. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2014, 47, 2177-2182.	0.4	17
116	Improved deep reinforcement learning for robotics through distribution-based experience retention. , 2016, , .		17
117	Sequential stability analysis and observer design for distributed TS fuzzy systems. <i>Fuzzy Sets and Systems</i> , 2011, 174, 1-30.	2.7	16
118	Active learning of affordances for robot use of household objects. , 2014, , .		16
119	Constructing parsimonious analytic models for dynamic systems via symbolic regression. <i>Applied Soft Computing Journal</i> , 2020, 94, 106432.	7.2	16
120	Fuzzy modeling - a control engineering perspective. , 0, , .		15
121	Predictive control by local linearization of a Takagi-Sugeno fuzzy model. , 0, , .		15
122	Fault-tolerant model-based predictive control using multiple Takagi-Sugeno fuzzy models. , 0, , .		15
123	Fuzzy Ant Colony Optimization for optimal control. , 2009, , .		15
124	DETERMINATION OF HYDROCORTISONE IN PHARMACEUTICAL DRUG BY TLC WITH DENSITOMETRIC DETECTION IN UV. <i>Journal of Liquid Chromatography and Related Technologies</i> , 2011, 34, 753-769.	1.0	15
125	Actor-critic reinforcement learning for tracking control in robotics. , 2016, , .		15
126	Fault diagnosis using spatial and temporal information with application to railway track circuits. <i>Engineering Applications of Artificial Intelligence</i> , 2016, 56, 200-211.	8.1	15



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127	Learning Complex Behaviors via Sequential Composition and Passivity-Based Control. Studies in Systems, Decision and Control, 2015, , 53-74.	1.0	15
128	Integrated operation of drinking water treatment plant at Amsterdam water supply. Water Science and Technology: Water Supply, 2004, 4, 263-270.	2.1	14
129	FUZZSAM - visualization of fuzzy clustering results by modified Sammon mapping. , 0, , .		14
130	Dynamic modelling for optimisation of pellet softening. Journal of Water Supply: Research and Technology - AQUA, 2008, 57, 45-56.	1.4	14
131	A new ant colony routing approach with a trade-off between system and user optimum. , 2011, , .		14
132	Nested compliant admittance control for robotic mechanical assembly of misaligned and tightly toleranced parts. , 2016, , .		14
133	Learning Sequential Composition Control. IEEE Transactions on Cybernetics, 2016, 46, 2559-2569.	9.5	14
134	Interpolation issues in Sugeno-Takagi reasoning. , 0, , .		13
135	Predictive control of nonlinear systems based on fuzzy and neural models. , 1999, , .		13
136	A multi-objective evolutionary algorithm for fuzzy modeling. , 0, , .		13
137	On non-PDC local observers for TS fuzzy systems. , 2010, , .		13
138	Optimistic planning for continuous-action deterministic systems. , 2013, , .		13
139	Multi-agent discrete-time graphical games: interactive Nash equilibrium and value iteration solution. , 2013, , .		13
140	Reinforcement learning for sequential composition control. , 2013, , .		13
141	Rapid learning in sequential composition control. , 2014, , .		13
142	An application of sequential composition control to cooperative systems. , 2015, , .		13
143	Comparison of conventional and fuzzy predictive control. , 0, , .		12
144	Adaptive Friction Compensation: A Globally Stable Approach. IEEE/ASME Transactions on Mechatronics, 2015, , 1-1.	5.8	12

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145	Exploiting spatial and temporal dependencies to enhance fault diagnosis: Application to railway track circuits. , 2015, , .		12
146	Policy derivation methods for critic-only reinforcement learning in continuous spaces. Engineering Applications of Artificial Intelligence, 2018, 69, 178-187.	8.1	12
147	Multi-objective symbolic regression for physics-aware dynamic modeling. Expert Systems With Applications, 2021, 182, 115210.	7.6	12
148	Continuous-State Reinforcement Learning with Fuzzy Approximation. Lecture Notes in Computer Science, 2008, , 27-43.	1.3	12
149	Fuzzy Clustering Algorithms with Applications to Rule Extraction. Studies in Fuzziness and Soft Computing, 2000, , 139-173.	0.8	12
150	Symbolic regression driven by training data and prior knowledge. , 2020, , .		12
151	Online self-organizing adaptive fuzzy controller: Application to a nonlinear servo system. , 2010, , .		11
152	Optimistic planning for sparsely stochastic systems. , 2011, , .		11
153	Actor-Critic Control with Reference Model Learning. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 14723-14728.	0.4	11
154	Takagi-Sugeno fuzzy observer and extended-Kalman filter for adaptive payload estimation. , 2013, , .		11
155	Robot learning and use of affordances in goal-directed tasks. , 2013, , .		11
156	Automated Transitions Between Walking and Running in Legged Robots. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 2171-2176.	0.4	11
157	AN OVERVIEW OF FUZZY MODELING AND MODEL-BASED FUZZY CONTROL. World Scientific Series in Robotics and Intelligent Systems, 1999, , 3-35.	0.1	11
158	Improved inference for Takagi-Sugeno models. , 0, , .		10
159	Internal model control with a fuzzy model: application to an air-conditioning system. , 0, , .		10
160	Modeling and identification of a strip guidance process with internal feedback. IEEE Transactions on Control Systems Technology, 1998, 6, 88-102.	5.2	10
161	Optimal flow distribution over multiple parallel pellet reactors: a model-based approach. Water Science and Technology, 2006, 53, 493-501.	2.5	10
162	Novel ant colony optimization approach to optimal control. International Journal of Intelligent Computing and Cybernetics, 2009, 2, 414-434.	2.7	10

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163	Adaptive fuzzy and sliding-mode control of a robot manipulator with varying payload. , 2011, , .		10
164	Least-Squares Methods for Policy Iteration. Adaptation, Learning, and Optimization, 2012, , 75-109.	0.6	10
165	On-line Reinforcement Learning for Nonlinear Motion Control: Quadratic and Non-Quadratic Reward Functions. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 7043-7048.	0.4	10
166	Symbolic method for deriving policy in reinforcement learning. , 2016, , .		10
167	Automated tuning and configuration of path planning algorithms. , 2017, , .		10
168	Laboratory evaluation of fuzzy controllers. Annual Review in Automatic Programming, 1992, 17, 189-194.	0.2	9
169	Reinforcement Learning Control for Biped Robot Walking on Uneven Surfaces. , 2006, , .		9
170	Particle filtering for on-line estimation of overflow losses in a hopper dredger. , 2006, , .		9
171	Switching Max-Plus models for legged locomotion. , 2009, , .		9
172	Fuzzy observer for state estimation of the METANET traffic model. , 2010, , .		9
173	Synchronization of a class of cyclic discrete-event systems describing legged locomotion. Discrete Event Dynamic Systems: Theory and Applications, 2016, 26, 225-261.	1.5	9
174	Identification of distributed-parameter systems from sparse measurements. Applied Mathematical Modelling, 2017, 51, 605-625.	4.2	9
175	Approximate Dynamic Programming and Reinforcement Learning. Studies in Computational Intelligence, 2010, , 3-44.	0.9	9
176	Where to Look Next: Learning Viewpoint Recommendations for Informative Trajectory Planning. , 2022, , .		9
177	Fault detection and isolation using multiple Takagi-Sugeno fuzzy models. , 0, , .		8
178	Comments on the benchmarks in "A proposal for improving the accuracy of Linguistic Modeling" and related articles. IEEE Transactions on Fuzzy Systems, 2003, 11, 861-865.	9.8	8
179	Max-plus algebra for optimal scheduling of multiple sheets in a printer. , 2012, , .		8
180	Effective transfer learning of affordances for household robots. , 2014, , .		8

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181	Learning rate free reinforcement learning for real-time motion control using a value-gradient based policy. <i>Mechatronics</i> , 2014, 24, 966-974.	3.3	8
182	Optimal Control via Reinforcement Learning with Symbolic Policy Approximation. <i>IFAC-PapersOnLine</i> , 2017, 50, 4162-4167.	0.9	8
183	Change detection using weighted features for image-based localization. <i>Robotics and Autonomous Systems</i> , 2021, 135, 103676.	5.1	8
184	Methods for Simplification of Fuzzy Models. , 1997, , 91-108.		8
185	Automated design environment for serial industrial manipulators. <i>Industrial Robot</i> , 2005, 32, 32-34.	2.1	7
186	Fuzzy Approximation for Convergent Model-Based Reinforcement Learning. , 2007, , .		7
187	Ant Colony Optimization for optimal control. , 2008, , .		7
188	Model-Based Dosing Control of a Pellet Softening Reactor. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2009, 42, 267-272.	0.4	7
189	Minimization of cross-talk in a piezo inkjet printhead based on system identification and feedforward control. <i>Journal of Micromechanics and Microengineering</i> , 2012, 22, 115035.	2.6	7
190	Reasoning under Uncertainty for Knowledge-Based Fault Diagnosis: A Comparative Study. <i>IFAC-PapersOnLine</i> , 2015, 48, 422-427.	0.9	7
191	Reinforcement Learning with Symbolic Input-Output Models. , 2018, , .		7
192	Data-driven Construction of Symbolic Process Models for Reinforcement Learning. , 2018, , .		7
193	Simultaneous task allocation and motion scheduling for complex tasks executed by multiple robots. , 2020, , .		7
194	Object-Based Pose Graph for Dynamic Indoor Environments. <i>IEEE Robotics and Automation Letters</i> , 2020, 5, 5401-5408.	5.1	7
195	Accurate, transparent and compact fuzzy models by multi-objective evolutionary algorithms. <i>Studies in Fuzziness and Soft Computing</i> , 2003, , 431-451.	0.8	7
196	Automated procedure for gain scheduled flight control law design. , 2000, , .		6
197	Engine load prediction in off-road vehicles using multi-objective nonlinear identification. <i>Control Engineering Practice</i> , 2004, 12, 615-624.	5.5	6
198	Decentralized estimation of overflow losses in a hopper dredger. <i>Control Engineering Practice</i> , 2008, 16, 392-406.	5.5	6

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199	Stability analysis and observer design for decentralized TS fuzzy systems. , 2008, , .		6
200	Toward a flexible control design framework to automatically generate control code for mechatronic systems. , 2009, , .		6
201	Policy search with cross-entropy optimization of basis functions. , 2009, , .		6
202	Optimization-based feedforward control for a Drop-on-Demand inkjet printhead. , 2010, , .		6
203	Using prior knowledge to accelerate online least-squares policy iteration. , 2010, , .		6
204	Particle filters for estimating average grain diameter of material excavated by hopper dredger. , 2010, , .		6
205	On the eigenstructure of a class of max-plus linear systems. , 2011, , .		6
206	Learning Assembly Tasks in a Few Minutes by Combining Impedance Control and Residual Recurrent Reinforcement Learning. Advanced Intelligent Systems, 2022, 4, 2100095.	6.1	6
207	Enhanced Symbolic Regression Through Local Variable Transformations. , 2017, , .		6
208	Identification of Nonlinear Dynamic Systems as a Composition of Local Linear Parametric or State-Space Models. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1997, 30, 675-680.	0.4	5
209	Performance evaluation of a fuzzy rule base for control purpose. , 0, , .		5
210	ON MULTI-OBJECTIVE IDENTIFICATION OF TAKAGI-SUGENO FUZZY MODEL PARAMETERS. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2002, 35, 115-120.	0.4	5
211	Information and communication technology embraces control. Annual Reviews in Control, 2006, 30, 31-40.	7.9	5
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