

Marco Ceccarelli

List of Publications by Year in descending order

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491
papers

5,293
citations

126907

33
h-index

223800

46
g-index

561
all docs

561
docs citations

561
times ranked

2201
citing authors

#	ARTICLE	IF	CITATIONS
1	Fundamentals of Mechanics of Robotic Manipulation. , 2004, , .		229
2	A stiffness analysis for CaPaMan (Cassino Parallel Manipulator). Mechanism and Machine Theory, 2002, 37, 427-439.	4.5	131
3	Designing an underactuated mechanism for a 1 active DOF finger operation. Mechanism and Machine Theory, 2009, 44, 336-348.	4.5	110
4	A multi-objective optimum design of general 3R manipulators for prescribed workspace limits. Mechanism and Machine Theory, 2004, 39, 119-132.	4.5	92
5	A new 3 D.O.F. spatial parallel mechanism. Mechanism and Machine Theory, 1997, 32, 895-902.	4.5	87
6	A formulation for the workspace boundary of general N-revolute manipulators. Mechanism and Machine Theory, 1996, 31, 637-646.	4.5	79
7	Collision free path-planning for cable-driven parallel robots. Robotics and Autonomous Systems, 2009, 57, 1083-1093.	5.1	69
8	A Synthesis Algorithm for Three-Revolute Manipulators by Using an Algebraic Formulation of Workspace Boundary. Journal of Mechanical Design, Transactions of the ASME, 1995, 117, 298-302.	2.9	68
9	Numerical and experimental analysis of non-circular gears and cam-follower systems as function generators. Mechanism and Machine Theory, 2008, 43, 996-1008.	4.5	67
10	Optimal design of CaPaMan (Cassino Parallel Manipulator) with a specified orientation workspace. Robotica, 2002, 20, 159-166.	1.9	65
11	Kinematic analysis and multi-objective optimization of a 3-UPR parallel mechanism for a robotic leg. Mechanism and Machine Theory, 2018, 120, 192-202.	4.5	64
12	Optimal design of driving mechanism in a 1-DOF anthropomorphic finger. Mechanism and Machine Theory, 2006, 41, 897-911.	4.5	60
13	Design and simulation of a waist-trunk system for a humanoid robot. Mechanism and Machine Theory, 2012, 53, 50-65.	4.5	58
14	Comparison of indices for stiffness performance evaluation. Frontiers of Mechanical Engineering in China, 2010, 5, 270-278.	0.4	57
15	A Fairly General Algorithm to Evaluate Workspace Characteristics of Serial and Parallel Manipulators. Mechanics Based Design of Structures and Machines, 2008, 36, 14-33.	4.7	56
16	Legged Robotic Systems. , 2005, , .		49
17	A novel articulated mechanism mimicking the motion of index fingers. Robotica, 2002, 20, 13-22.	1.9	47
18	A stiffness analysis for a hybrid parallel-serial manipulator. Robotica, 2004, 22, 567-576.	1.9	46

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19	Operation analysis of a Chebyshev-Pantograph leg mechanism for a single DOF biped robot. <i>Frontiers of Mechanical Engineering</i> , 2012, 7, 357-370.	4.3	44
20	Design and test of a gripper prototype for horticulture products. <i>Robotics and Computer-Integrated Manufacturing</i> , 2017, 44, 266-275.	9.9	44
21	A Numerical Simulation for Design and Operation of an Underactuated Finger Mechanism for LARM Hand. <i>Mechanics Based Design of Structures and Machines</i> , 2009, 37, 86-112.	4.7	41
22	Application of line geometry and linear complex approximation to singularity analysis of the 3-DOF CaPaMan parallel manipulator. <i>Mechanism and Machine Theory</i> , 2004, 39, 75-95.	4.5	40
23	On the kinematic functionality of a four-bar based mechanism for guiding wheels in climbing steps and obstacles. <i>Mechanism and Machine Theory</i> , 2009, 44, 1507-1523.	4.5	40
24	Grasp configuration planning for a low-cost and easy-operation underactuated three-fingered robot hand. <i>Mechanism and Machine Theory</i> , 2018, 129, 51-69.	4.5	40
25	Experimental tests in human-robot collision evaluation and characterization of a new safety index for robot operation. <i>Mechanism and Machine Theory</i> , 2014, 80, 184-199.	4.5	39
26	A Serial-parallel robotic architecture for surgical tasks. <i>Robotica</i> , 2005, 23, 345-354.	1.9	38
27	An optimum design procedure for both serial and parallel manipulators. <i>Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science</i> , 2007, 221, 829-843.	2.1	38
28	CATRASY (Cassino Tracking System): A Wire System for Experimental Evaluation of Robot Workspace. <i>Journal of Robotics and Mechatronics</i> , 2002, 14, 78-87.	1.0	38
29	On the Workspace of General 4R Manipulators. <i>International Journal of Robotics Research</i> , 1995, 14, 152-160.	8.5	37
30	Renaissance of machines in Italy: From Brunelleschi to Galilei through Francesco di Giorgio and Leonardo. <i>Mechanism and Machine Theory</i> , 2008, 43, 1530-1542.	4.5	37
31	Design and numerical characterization of a new leg exoskeleton for motion assistance. <i>Robotica</i> , 2015, 33, 1147-1162.	1.9	37
32	Designing a robotic gripper for harvesting horticulture products. <i>Robotica</i> , 2000, 18, 105-111.	1.9	36
33	Analysis of a Wearable Robotic System for Ankle Rehabilitation. <i>Machines</i> , 2020, 8, 48.	2.2	36
34	Screw axis defined by Giulio Mozzi in 1763 and early studies on helicoidal motion. <i>Mechanism and Machine Theory</i> , 2000, 35, 761-770.	4.5	35
35	An optimum robot path planning with payload constraints. <i>Robotica</i> , 2002, 20, 395-404.	1.9	35
36	An Optimization Problem Algorithm for Kinematic Design of Mechanisms for Two-Finger Grippers. <i>The Open Mechanical Engineering Journal</i> , 2009, 3, 49-62.	0.3	34

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37	Performance analysis of a 3-2-1 pose estimation device. , 2005, 21, 288-297.		33
38	Design and tests of a three finger hand with 1-DOF articulated fingers. Robotica, 2006, 24, 183-196.	1.9	32
39	Identification of the Workspace Boundary Of a General 3-R Manipulator. Journal of Mechanical Design, Transactions of the ASME, 2006, 128, 236-242.	2.9	31
40	Characterization of a Cable-Based Parallel Mechanism for Measurement Purposes#. Mechanics Based Design of Structures and Machines, 2010, 38, 25-49.	4.7	31
41	Design of a Two-DOFs Driving Mechanism for a Motion-Assisted Finger Exoskeleton. Applied Sciences (Switzerland), 2020, 10, 2619.	2.5	31
42	A Closed-Form Formulation for the Inverse Dynamics of a Cassino Parallel Manipulator. Multibody System Dynamics, 2001, 5, 185-210.	2.7	30
43	Application of a 3-DOF parallel manipulator for earthquake simulations. IEEE/ASME Transactions on Mechatronics, 2006, 11, 241-246.	5.8	29
44	Regulation and control of LARM Hand III. Robotics and Computer-Integrated Manufacturing, 2010, 26, 202-211.	9.9	29
45	Problems and Issues for Service Robots in New Applications. International Journal of Social Robotics, 2011, 3, 299-312.	4.6	29
46	An experimental characterization of human torso motion. Frontiers of Mechanical Engineering, 2015, 10, 311-325.	4.3	29
47	Stiffness analysis of biped humanoid robot WABIAN-RIV. Mechanism and Machine Theory, 2006, 41, 17-40.	4.5	28
48	Design Considerations for Underactuated Grasp with a one D.O.F. Anthropomorphic Finger Mechanism. , 2006, , .		28
49	Design and Experiments of a Novel Humanoid Robot with Parallel Architectures. Robotics, 2018, 7, 79.	3.5	27
50	Walking programming for an electropneumatic biped robot. Mechatronics, 1999, 9, 941-964.	3.3	26
51	Effect of basic numerical parameters on a path planning of robots taking into account actuating energy. Mechanism and Machine Theory, 2004, 39, 247-260.	4.5	26
52	Experimental Tests on Feasible Operation of a Finger Mechanism in the LARM Hand[#]. Mechanics Based Design of Structures and Machines, 2008, 36, 1-13.	4.7	26
53	An optimum path planning for Cassino Parallel Manipulator by using inverse dynamics. Robotica, 2008, 26, 229-239.	1.9	26
54	Mechanism Schemes in Teaching: A Historical Overview. Journal of Mechanical Design, Transactions of the ASME, 1998, 120, 533-541.	2.9	24

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55	Experimental Stiffness Measurement of WL-16RII Biped Walking Vehicle During Walking Operation. <i>Journal of Robotics and Mechatronics</i> , 2007, 19, 272-280.	1.0	24
56	Robotic teachers' assistants - Low cost robots for research and teaching activities. <i>IEEE Robotics and Automation Magazine</i> , 2003, 10, 37-45.	2.0	23
57	Numerical and experimental characterization of singularities of a six-wire parallel architecture. <i>Robotica</i> , 2006, 25, 315-324.	1.9	23
58	Design issues for human-machine platform interface in cable-based parallel manipulators for physiotherapy applications. <i>Journal of Zhejiang University: Science A</i> , 2010, 11, 231-239.	2.4	23
59	An application of CaTraSys, a cable-based parallel measuring system for an experimental characterization of human walking. <i>Robotica</i> , 2010, 28, 119-133.	1.9	23
60	Design improvements and control of a hybrid walking robot. <i>Robotics and Autonomous Systems</i> , 2011, 59, 128-141.	5.1	23
61	A kinematic characterization of human walking by using CaTraSys. <i>Mechanism and Machine Theory</i> , 2015, 86, 125-139.	4.5	23
62	A Low-Cost Easy-Operation Hexapod Walking Machine. <i>International Journal of Advanced Robotic Systems</i> , 2008, 5, 21.	2.1	22
63	Parallel Architectures for Humanoid Robots. <i>Robotics</i> , 2020, 9, 75.	3.5	22
64	Progress and Development Trend of Space Intelligent Robot Technology. <i>Space: Science & Technology</i> , 2022, 2022, .	2.5	22
65	An analytical design for three circular-arc cams. <i>Mechanism and Machine Theory</i> , 2002, 37, 915-924.	4.5	21
66	Analysis and optimal design of an underactuated finger mechanism for LARM hand. <i>Frontiers of Mechanical Engineering</i> , 2011, 6, 332.	4.3	21
67	Kinematic calibration of precise 6-DOF Stewart platform-type positioning systems for radio telescope applications. <i>Frontiers of Mechanical Engineering</i> , 2013, 8, 252-260.	4.3	21
68	A Survey on Mechanical Solutions for Hybrid Mobile Robots. <i>Robotics</i> , 2020, 9, 32.	3.5	21
69	A workspace evaluation of an eclipse robot. <i>Robotica</i> , 2002, 20, 299-313.	1.9	20
70	A short account of history of IFToMM and its role in MMS. <i>Mechanism and Machine Theory</i> , 2015, 89, 75-91.	4.5	20
71	An experimental validation of a novel humanoid torso. <i>Robotics and Autonomous Systems</i> , 2017, 91, 299-313.	5.1	20
72	A Historical Perspective of Robotics Toward the Future. <i>Journal of Robotics and Mechatronics</i> , 2001, 13, 299-313.	1.0	20

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73	A Biped Walking Mechanism for a Rickshaw Robot[#]. Mechanics Based Design of Structures and Machines, 2010, 38, 227-242.	4.7	19
74	A unified dynamic control method for a redundant dual arm robot. Journal of Bionic Engineering, 2015, 12, 361-371.	5.0	19
75	Design and Simulation of a Cable-Driven Vertebra-Based Humanoid Torso. International Journal of Humanoid Robotics, 2016, 13, 1650015.	1.1	19
76	HeritageBot platform for service in Cultural Heritage frames. International Journal of Advanced Robotic Systems, 2018, 15, 172988141879069.	2.1	19
77	Design and Performance of an Elbow Assisting Mechanism. Machines, 2020, 8, 68.	2.2	19
78	A formulation for path planning of manipulators in complex environments by using adjacent configurations. Advanced Robotics, 1996, 11, 33-56.	1.8	18
79	A 4– cable-based parallel manipulator for an application in hospital environment. , 2007, , .		18
80	Water Dancer II-A: A Non-Tethered Telecontrollable Water Strider Robot. International Journal of Advanced Robotic Systems, 2011, 8, 39.	2.1	18
81	Design and simulation of an underactuated finger mechanism for LARM Hand. Robotica, 2017, 35, 483-497.	1.9	18
82	Climbing stairs with EP-WAR2 biped robot. , 0, , .		17
83	Development of a humanoid robot having 2-DOF waist and 2-DOF trunk. , 0, , .		17
84	Operation Strategy for a Low-Cost Easy-Operation Cassino Hexapod. Applied Bionics and Biomechanics, 2007, 4, 149-156.	1.1	17
85	A Methodology for the Design of Robotic Hands with Multiple Fingers. International Journal of Advanced Robotic Systems, 2008, 5, 22.	2.1	17
86	Design and Simulation of a Leg Exoskeleton Linkage for a Human Rehabilitation System. Mechanisms and Machine Science, 2014, , 117-125.	0.5	17
87	Experimental tests on operation performance of a LARM leg mechanism with 3-DOF parallel architecture. Mechanical Sciences, 2015, 6, 1-8.	1.0	17
88	Approximate four-bar circle-tracing mechanisms: classical and new synthesis. Mechanism and Machine Theory, 2000, 35, 1579-1599.	4.5	16
89	Singularity analysis of CaPaMan: A three-degree of freedom spatial parallel manipulator. , 0, , .		16
90	A Low-Cost Easy Operation 4-Cable Driven Parallel Manipulator. , 0, , .		16

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91	Early TMM in Le Mekaniche by Galileo Galilei in 1593. Mechanism and Machine Theory, 2006, 41, 1401-1406.	4.5	16
92	A Brief Illustrated History of Machines and Mechanisms. History of Mechanism and Machine Science, 2010, , .	0.2	16
93	Application of Counter-Rotary Counterweights to the Dynamic Balancing of a Spatial Parallel Manipulator. Applied Mechanics and Materials, 2012, 162, 224-233.	0.2	16
94	Towards a safety index for assessing head injury potential in service robotics. Advanced Robotics, 2013, 27, 831-844.	1.8	16
95	Force transmission and constraint analysis of a 3-SPR parallel manipulator. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2018, 232, 4399-4409.	2.1	16
96	Master-Slave Control of an Intention-Actuated Exoskeletal Robot for Locomotion and Lower Extremity Rehabilitation. International Journal of Precision Engineering and Manufacturing, 2018, 19, 983-991.	2.2	16
97	Design of arm exercises for rehabilitation assistance. Journal of Engineering Research, 2020, 8, 203-218.	0.7	16
98	The Effects of Design Parameters on the Workspace of a Turin Parallel Robot. International Journal of Robotics Research, 1998, 17, 886-902.	8.5	15
99	Grasp force control in two-finger grippers with pneumatic actuation. , 0, , .		15
100	Uncertainty Model and Singularities of 3-2-1 Wire-Based Tracking Systems. , 2002, , 107-116.		15
101	Descending stairs with EP-WAR3 biped robot. , 0, , .		15
102	Kinematic and Dynamic Analyses of a Pantograph-Leg for a Biped Walking Machine. , 2005, , 561-568.		15
103	Position and Force Control of a Parallel Robot Capaman 2 Bis Parallel Robot for Drilling Tasks. , 2009, , .		15
104	Analysis and design for changing finger posture in a robotic hand. Mechanism and Machine Theory, 2010, 45, 828-843.	4.5	15
105	New Assistive Device for People with Motor Disabilities. Applied Mechanics and Materials, 0, 772, 574-579.	0.2	15
106	Design and Characterization of a Novel Knee Articulation Mechanism. International Journal of Applied Mechanics and Engineering, 2016, 21, 611-622.	0.7	15
107	NURSE-2 DoF Device for Arm Motion Guidance: Kinematic, Dynamic, and FEM Analysis. Applied Sciences (Switzerland), 2020, 10, 2139.	2.5	15
108	Development and characterisation of a controllable adjustable knee joint mechanism. Mechanism and Machine Theory, 2021, 155, 104101.	4.5	15

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109	Historical Evolution of the Classification of Mechanisms. , 2004, , 285-302.		15
110	LARM Bot Humanoid Design Towards a Prototype. MOJ Applied Bionics and Biomechanics, 2017, 1, .	0.3	15
111	Application of Robots for Inspection and Restoration of Historical Sites. , 2005, , .		14
112	Trends in the drawing of mechanisms since the early Middle Ages. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2001, 215, 269-289.	2.1	13
113	Workspace Topologies of Industrial 3R Manipulators. International Journal of Advanced Robotic Systems, 2007, 4, 38.	2.1	13
114	Burmester and Allievi: A Theory and Its Application for Mechanism Design at the End of 19th Century. Journal of Mechanical Design, Transactions of the ASME, 2008, 130, .	2.9	13
115	The Genius of Archimedes – 23 Centuries of Influence on Mathematics, Science and Engineering. History of Mechanism and Machine Science, 2010, , .	0.2	13
116	An Experimental Analysis of Overcoming Obstacle in Human Walking. Journal of Bionic Engineering, 2014, 11, 497-505.	5.0	13
117	Design and simulated characteristics of a new biped mechanism. Robotica, 2015, 33, 1568-1588.	1.9	13
118	Multi-objective optimization of a parallel manipulator for the design of a prosthetic arm using genetic algorithms. Latin American Journal of Solids and Structures, 2018, 15, .	1.0	13
119	Notes for a History of Grasping Devices. Mechanisms and Machine Science, 2013, , 3-16.	0.5	13
120	Design, Modeling and Experimentation of a Biomimetic Wall-climbing Robot for Multiple Surfaces. Journal of Bionic Engineering, 2020, 17, 523-538.	5.0	13
121	Optimal design of 3R manipulators by using classical techniques and simulated annealin. Revista Brasileira De Ciencias Mecanicas/Journal of the Brazilian Society of Mechanical Sciences, 2002, 24, 293-301.	0.1	13
122	Experimental Characterization of Operation of a Waist-Trunk System with Parallel Manipulators. Chinese Journal of Mechanical Engineering (English Edition), 2011, 24, 713.	3.7	13
123	Cassino Hexapod : Experiences and new leg design. , 2010, , .		12
124	LARM PKM solutions for torso design in humanoid robots. Frontiers of Mechanical Engineering, 2014, 9, 308-316.	4.3	12
125	LARMbot: A New Humanoid Robot with Parallel Mechanisms. CISM International Centre for Mechanical Sciences, Courses and Lectures, 2016, , 275-283.	0.6	12
126	A feasibility study on the design and walking operation of a biped locomotor via dynamic simulation. Frontiers of Mechanical Engineering, 2016, 11, 144-158.	4.3	12

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127	Design and Feasibility Study of a Leg-exoskeleton Assistive Wheelchair Robot with Tests on Gluteus Medius Muscles. Sensors, 2019, 19, 548.	3.8	12
128	Service Robots for Restoration of Goods of Cultural Heritage. , 2012, , 213-228.		12
129	An optimum synthesis for gripping mechanisms by using natural coordinates. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2002, 216, 643-653.	2.1	11
130	Design and Characterization of a New Planetary Gear Box. Mechanisms and Machine Science, 2014, , 91-98.	0.5	11
131	Topology search of 3-DOF translational parallel manipulators with three identical limbs for leg mechanisms. Chinese Journal of Mechanical Engineering (English Edition), 2015, 28, 666-675.	3.7	11
132	HeritageBot Service Robot assisting in Cultural Heritage. , 2017, , .		11
133	Design and simulation of leg exoskeleton cycling-actuated wheelchair. International Journal of Advanced Robotic Systems, 2017, 14, 172988141774173.	2.1	11
134	Innovation challenges for Mechanism Design. Mechanism and Machine Theory, 2018, 125, 94-100.	4.5	11
135	Experimental Results of a 3-DOF Parallel Manipulator as an Earthquake Motion Simulator. , 2004, , .		11
136	An experimental characterization of human falling down. Mechanical Sciences, 2017, 8, 79-89.	1.0	11
137	Designing Two-Revolute Manipulators for Prescribed Feasible Workspace Regions. Journal of Mechanical Design, Transactions of the ASME, 2002, 124, 427-434.	2.9	10
138	Design of LARM hand: Problems and solutions. , 2008, , .		10
139	Design and operation of a tripod walking robot via dynamics simulation. Robotica, 2011, 29, 733-743.	1.9	10
140	A falling motion control of humanoid robots based on biomechanical evaluation of falling down of humans. , 2015, , .		10
141	Conceptual Kinematic Design and Performance Evaluation of a Chameleon-Like Service Robot for Space Stations. International Journal of Advanced Robotic Systems, 2015, 12, 17.	2.1	10
142	Elastodynamic Model-Based Vibration Characteristics Prediction of a Three Prismaticâ€“Revoluteâ€“Spherical Parallel Kinematic Machine. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2016, 138, .	1.6	10
143	Experimental characterization of an osteosynthesis implant. Mechanisms and Machine Science, 2019, , 53-62.	0.5	10
144	Problems and Experiences on Cable-Based Service Robots for Physiotherapy Applications. Mechanisms and Machine Science, 2014, , 27-42.	0.5	10

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145	Design Optimization of a Cable-Driven Parallel Robot in Upper Arm Training-Rehabilitation Processes. Mechanisms and Machine Science, 2018, , 413-423.	0.5	10
146	Design Considerations for an Underactuated Robotic Finger Mechanism. Chinese Journal of Mechanical Engineering (English Edition), 2009, 22, 475.	3.7	10
147	Optimal synthesis of three-revolute manipulators. Meccanica, 1994, 29, 95-103.	2.0	9
148	AN ALGEBRAIC FORMULATION AND EXPERIMENTAL ANALYSIS OF TWO CIRCULAR-ARC CAMS. Transactions of the Canadian Society for Mechanical Engineering, 2001, 25, 29-49.	0.8	9
149	A 3-DOF parallel manipulator as earthquake motion simulator. , 0, , .		9
150	Dynamic performance of CaPaMan by numerical simulations. Mechanism and Machine Theory, 2002, 37, 241-266.	4.5	9
151	Stiffness analysis of the humanoid robot WABIAN-RIV: modelling. , 0, , .		9
152	Analysis and grasp strategy modeling for underactuated multi-fingered robot hand. , 2009, , .		9
153	Prototype Design and Performance Tests of Beijing's Astronaut Robot. Applied Sciences (Switzerland), 2018, 8, 1342.	2.5	9
154	Enhanced D-H: an improved convention for establishing a robot link coordinate system fixed on the joint. Industrial Robot, 2019, 47, 197-205.	2.1	9
155	Pipeline Inspection Tests Using a Biomimetic Robot. Biomimetics, 2021, 6, 17.	3.3	9
156	DESIGN AND PROBLEMS OF A NEW LEG-WHEEL WALKING ROBOT. , 2007, , .		9
157	Control Design for CABLEankle, a Cable Driven Manipulator for Ankle Motion Assistance. Actuators, 2022, 11, 63.	2.3	9
158	A Characterization of the Workspace Boundary of Three-Revolute Manipulators. , 2002, , 1177.		8
159	Workspace analysis and performance of a binary actuated parallel manipulator with flexural joints. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2003, 217, 313-330.	2.1	8
160	EP-WAR3 biped robot for climbing and descending stairs. Robotica, 2004, 22, 405-417.	1.9	8
161	Agustin Betancourt: An Early Modern Scientist and Engineer in TMM. , 2006, , 301.		8
162	A Brief Account on Roman Machines and Cultural Frames. , 2009, , 83-100.		8

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163	Analysis and design of a modular underactuated mechanism for robotic fingers. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2012, 226, 242-256.	2.1	8
164	Contributions of Archimedes on mechanics and design of mechanisms. Mechanism and Machine Theory, 2014, 72, 86-93.	4.5	8
165	Adaptive fuzzy sliding mode control for redundant manipulators with varying payload. Industrial Robot, 2016, 43, 665-676.	2.1	8
166	Design and Kinematic Analysis of a Novel Metamorphic Mechanism for Lower Limb Rehabilitation. Mechanisms and Machine Science, 2016, , 545-558.	0.5	8
167	Experimental Validation of HeritageBot III, a Robotic Platform for Cultural Heritage. Journal of Intelligent and Robotic Systems: Theory and Applications, 2020, 100, 223-237.	3.4	8
168	A prototype characterization of ExoFinger, a finger exoskeleton. International Journal of Advanced Robotic Systems, 2021, 18, 172988142110248.	2.1	8
169	Design and Experimental Characterization of L-CADEL v2, an Assistive Device for Elbow Motion. Sensors, 2021, 21, 5149.	3.8	8
170	A Geometrical Characterization of Workspace Singularities in 3R Manipulators. , 2008, , 411-418.		8
171	Experimental Dynamic Tests of Rib Implants. Mechanisms and Machine Science, 2019, , 353-361.	0.5	8
172	Kinematic Design of a Tripod Parallel Mechanism for Robotic Legs. Mechanisms and Machine Science, 2018, , 121-130.	0.5	8
173	Kinematic Analysis of an Exoskeleton-Based Robot for Elbow and Wrist Rehabilitation. Mechanisms and Machine Science, 2018, , 424-433.	0.5	8
174	Italian Kinematic Studies in XIXth Century. , 2000, , 197-206.		8
175	Seismic motion simulation based on Cassino Parallel Manipulator. Revista Brasileira De Ciencias Mecanicas/Journal of the Brazilian Society of Mechanical Sciences, 2002, 24, 213-219.	0.1	8
176	Logical sensors and control system programming for an autonomous biped walking robot. , 0, , .		7
177	Stiffness performance estimation for biped locomotor WL-15. , 0, , .		7
178	Coordinate-free formulation of a 3-2-1 wire-based tracking device using Cayley-Menger determinants. , 0, , .		7
179	A Cartesian Representation for the Boundary Workspace of 3R Manipulators. , 2004, , 247-254.		7
180	Antropomorphic Design and Operation of a New Low-Cost Humanoid Robot. , 0, , .		7

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181	A Performance Analysis of a 4 Cable-Driven Parallel Manipulator. , 2006, , .		7
182	A design of a new leg-wheel walking robot. , 2007, , .		7
183	Simulation results for design and operation of CALUMA, a new low-cost humanoid robot. Robotica, 2008, 26, 601-618.	1.9	7
184	Problems and requirements for a chameleon-like service robot in space station. , 2011, , .		7
185	Numerical solution for designing telescopic manipulators with prescribed workspace points. Robotics and Computer-Integrated Manufacturing, 2014, 30, 201-205.	9.9	7
186	Structure-control design of a mechatronic system with parallelogram mechanism using an estimation of distribution algorithm. Mechanics Based Design of Structures and Machines, 2016, 44, 58-71.	4.7	7
187	Mechanical Design and Assessment of a Low-Cost 7-DOF Prosthetic Arm for Shoulder Disarticulation. Applied Bionics and Biomechanics, 2018, 2018, 1-13.	1.1	7
188	Kinematic Modelling and Motion Analysis of a Humanoid Torso Mechanism. Applied Sciences (Switzerland), 2021, 11, 2607.	2.5	7
189	Design and Experimental Characterization of a Cable-Driven Elbow Assisting Device. Journal of Medical Devices, Transactions of the ASME, 2021, 15, .	0.7	7
190	Design and Simulation of Kursk Robot for In-Pipe Inspection. , 2010, , 103-114.		7
191	Marcus Vitruvius Pollio (Second Half of the 1st Century B.C.). History of Mechanism and Machine Science, 2014, , 309-346.	0.2	7
192	An Analytical Design for CaPaMan With Prescribed Position and Orientation. , 2000, , .		7
193	International Symposium on History of Machines and Mechanisms. , 2009, , .		7
194	Experimental Validation of Light Cable-Driven Elbow-Assisting Device L-CADEL Design. Journal of Bionic Engineering, 2022, 19, 416-428.	5.0	7
195	Design of a Robot for Inspecting the Multishape Pipeline Systems. IEEE/ASME Transactions on Mechatronics, 2022, 27, 4608-4618.	5.8	7
196	Easy Programming of an Electropneumatic Walking Robot. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1997, 30, 747-754.	0.4	6
197	Numerical and experimental estimation of stiffness performances for the humanoid robot WABIAN-RV. , 0, , .		6
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201	A Multiobjective Optimal Path Planning for a 1-DOF Clutched ARM. Mechanics Based Design of Structures and Machines, 2012, 40, 109-121.	4.7	6
202	An experimental analysis of human straight walking. Frontiers of Mechanical Engineering, 2013, 8, 95-103.	4.3	6
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205	Experimental Characterization of NURSE, a Device for Arm Motion Guidance. Journal of Healthcare Engineering, 2018, 2018, 1-15.	1.9	6
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230	An Experimental Characterization of TORVEastro, Cable-Driven Astronaut Robot. Robotics, 2021, 10, 21.	3.5	5
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328	Underactuated Finger Mechanism for LARM Hand. Mechanisms and Machine Science, 2014, , 283-291.	0.5	2
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346	An Optimum Path Planning for LARM Clutched Arm. , 2010, , 393-400.		2
347	Experimental Determination of Robot Workspace by Means of CATRASYS (Cassino Tracking System). CISM International Centre for Mechanical Sciences, Courses and Lectures, 2000, , 85-92.	0.6	2
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365	Machinery During the Industrial Revolution. History of Mechanism and Machine Science, 2009, , 141-168.	0.2	1
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388	GRASPING SIMULATION OF AN UNDERACTUATED FINGER MECHANISM FOR LARM HAND. International Journal of Modelling and Simulation, 2010, 30, .	3.3	1
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391	History and Challenges of Mechanism and Machine Science within IFToMM Community. Studies in Computational Intelligence, 2009, , 469-488.	0.9	1
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393	Step Design of a Cassino Tripod Leg Mechanism. Mechanisms and Machine Science, 2015, , 211-219.	0.5	1
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