## Torbjorn Dahl

## List of Publications by Year in descending order

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Version: 2024-02-01


Multi-robot task allocation through vacancy chain scheduling. Robotics and Autonomous Systems,
2009, 57, 674-687.

Local interactions over global broadcasts for improved task allocation in self-organized multi-robot systems. Robotics and Autonomous Systems, 2014, 62, 1453-1462.

Division of labour in ant colonies in terms of attractive fields. Ecological Complexity, 2009, 6, 396-402.
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A Machine Learning Method for Improving Task Allocation in Distributed Multi-Robot Transportation. , 2006, , 307-337.

Compressed Sparse Code Hierarchical SOM on learning and reproducing gestures in humanoid robots. , 2010, , .
7 A developmental perspective on humanoid skill learning using a hierarchical SOM-based encoding.

2014, . .

Learning Robot Control Using a Hierarchical SOM-Based Encoding. IEEE Transactions on Cognitive and
Developmental Systems, 2017, 9, 30-43.

A Force-Distance Model of Humanoid Arm Withdrawal Reflexes. Lecture Notes in Computer Science,
2012, , 13-24.
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Flexible communication in multi-robotic control system using head: hybrid event-driven architecture on d-bus. , 2010, , .

Problems with using a human-dog interaction model for human-robot interaction?. Interaction
Studies, 2014, 15, 190-194.

Incremental Development of Adaptive Behaviors using Trees of Self-Contained Solutions. Adaptive Behavior, 2005, 13, 243-260.

A Robotic Validation of the Attractive Field Model: An Inter-disciplinary Model of Self-regulatory
Social Systems. Lecture Notes in Computer Science, 2010, , 24-35.
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