## Jürgen Sturm

## List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/10552292/publications.pdf

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18	4,384	3	3
papers	citations	h-index	g-index
18	18	18	3016
all docs	docs citations	times ranked	citing authors

#	Article	IF	Citations
1	Volumetric 3D mapping in real-time on a CPU., 2014, , .		110
2	Scale-aware navigation of a low-cost quadrocopter with a monocular camera. Robotics and Autonomous Systems, 2014, 62, 1646-1656.	5.1	172
3	Robust odometry estimation for RGB-D cameras. , 2013, , .		388
4	A generalized framework for opening doors and drawers in kitchen environments. , 2012, , .		51
5	A benchmark for the evaluation of RGB-D SLAM systems. , 2012, , .		2,188
6	Real-time human motion tracking using multiple depth cameras. , 2012, , .		62
7	An evaluation of the RGB-D SLAM system. , 2012, , .		493
8	Camera-based navigation of a low-cost quadrocopter. , 2012, , .		238
9	Real-time visual odometry from dense RGB-D images. , 2011, , .		238
10	Tactile Sensing for Mobile Manipulation. IEEE Transactions on Robotics, 2011, 27, 558-568.	10.3	93
10	Tactile Sensing for Mobile Manipulation. IEEE Transactions on Robotics, 2011, 27, 558-568.  Tactile object class and internal state recognition for mobile manipulation., 2010,,.	10.3	93
		10.3	
11	Tactile object class and internal state recognition for mobile manipulation. , 2010, , .	10.3	44
11 12	Tactile object class and internal state recognition for mobile manipulation., 2010,,.  Operating articulated objects based on experience., 2010,,.  Vision-based detection for learning articulation models of cabinet doors and drawers in household	10.3	30
11 12 13	Tactile object class and internal state recognition for mobile manipulation. , 2010, , .  Operating articulated objects based on experience. , 2010, , .  Vision-based detection for learning articulation models of cabinet doors and drawers in household environments. , 2010, , .	10.3	30
11 12 13 14	Tactile object class and internal state recognition for mobile manipulation. , 2010, , .  Operating articulated objects based on experience. , 2010, , .  Vision-based detection for learning articulation models of cabinet doors and drawers in household environments. , 2010, , .  Regression-based online situation recognition for vehicular traffic scenarios. , 2009, , .	10.3	<ul><li>44</li><li>30</li><li>24</li><li>6</li></ul>
11 12 13 14	Tactile object class and internal state recognition for mobile manipulation., 2010,,.  Operating articulated objects based on experience., 2010,,.  Vision-based detection for learning articulation models of cabinet doors and drawers in household environments., 2010,,.  Regression-based online situation recognition for vehicular traffic scenarios., 2009,,.  Object identification with tactile sensors using bag-of-features., 2009,,.	2.1	<ul> <li>44</li> <li>30</li> <li>24</li> <li>6</li> <li>156</li> </ul>